

Spring 2019

CSCI 621: Digital Geometry Processing

11.1 Remeshing



Hao Li

<http://cs621.hao-li.com>

Outline

- *What* is remeshing?
- *Why* remeshing?
- *How* to do remeshing?

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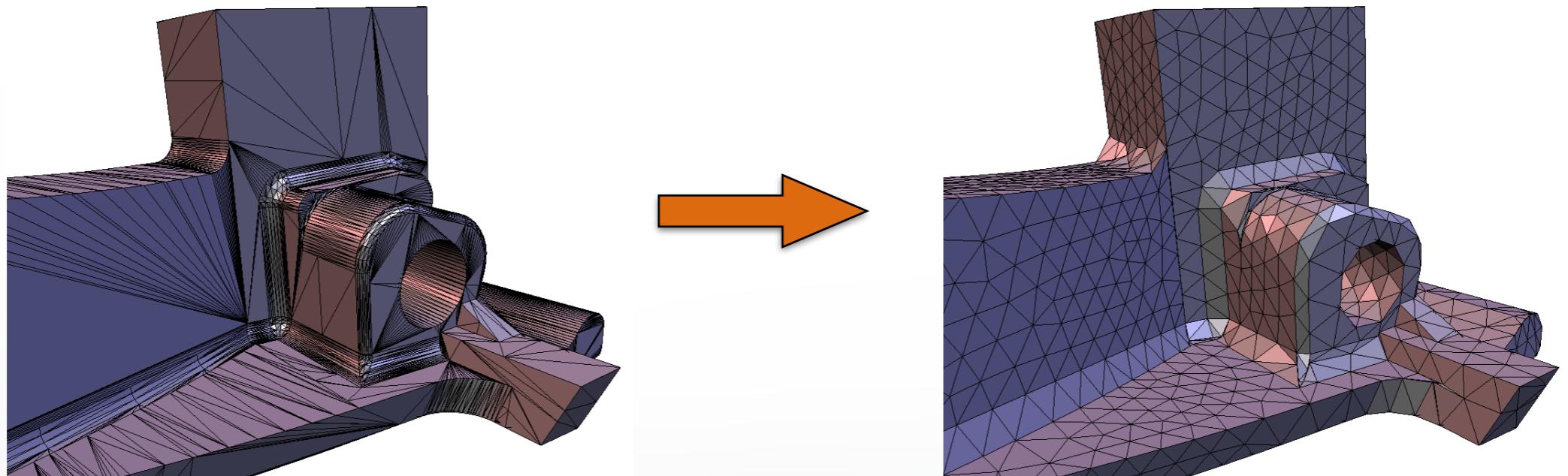
Definition

Given a 3D mesh

- Already a manifold mesh

Compute another mesh

- Satisfy some quality requirements
- Approximate well the input mesh



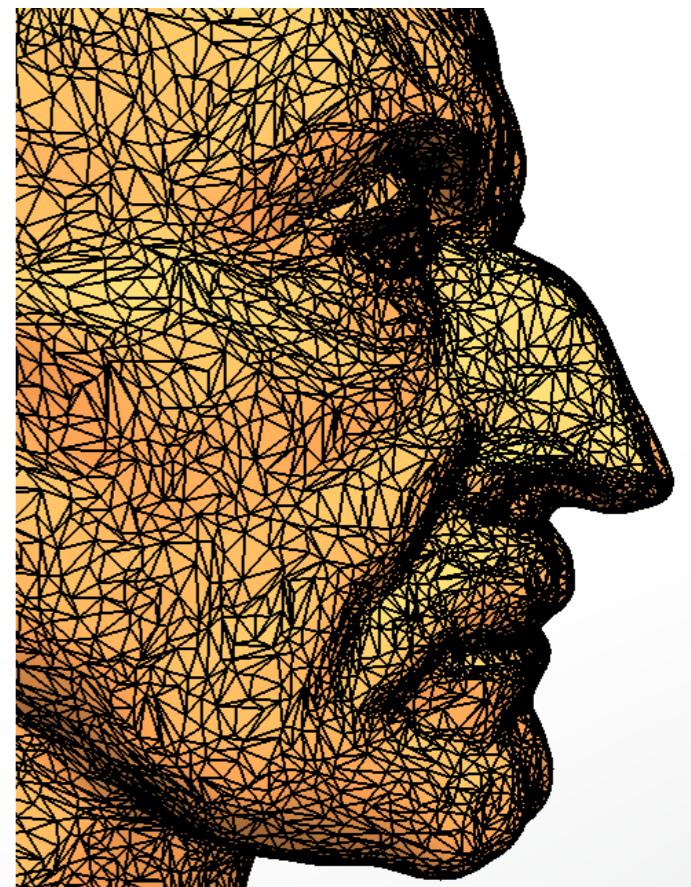
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- *What* is remeshing?
- **Why** remeshing?
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Motivation

Unsatisfactory “raw” mesh

- By scanning or implicit representations

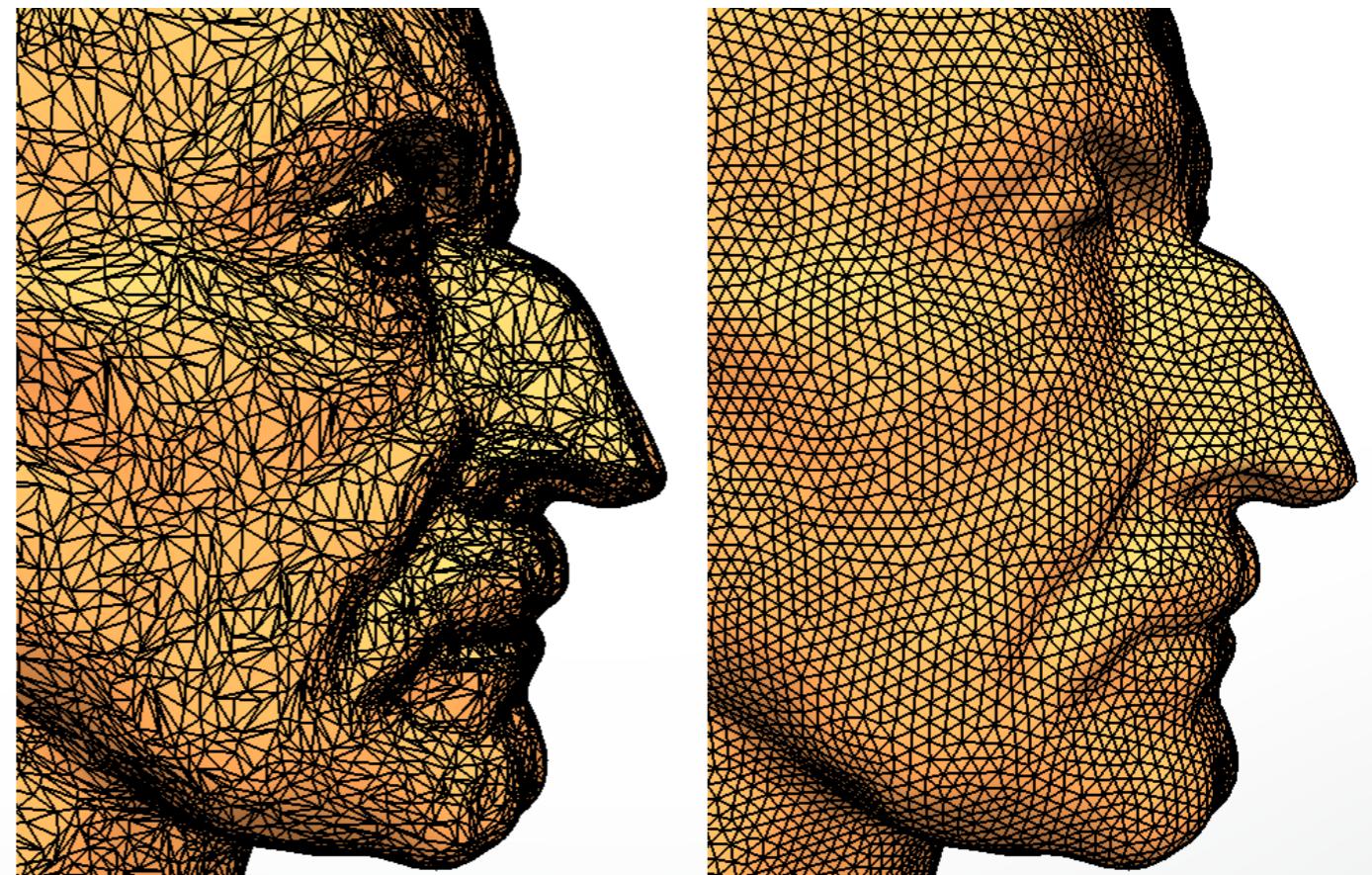


Motivation

Unsatisfactory “raw” mesh

- By scanning or implicit representations

Improve mesh quality for further use



Motivation

Unsatisfactory “raw” mesh

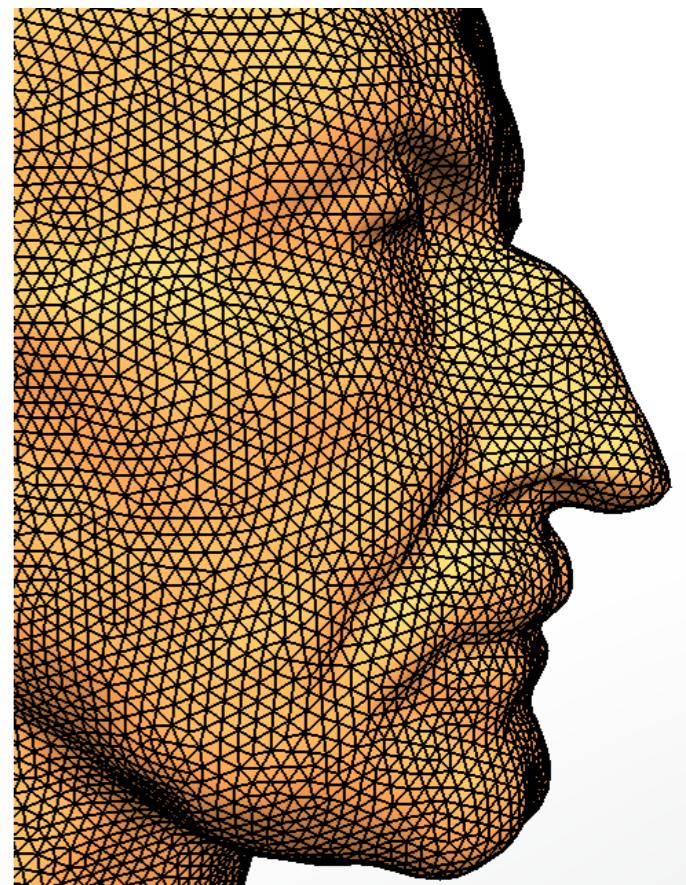
- By scanning or implicit representations

Improve mesh quality for further use

- Modeling: easy processing
- Simulation: numerical robustness
-

Quality requirements

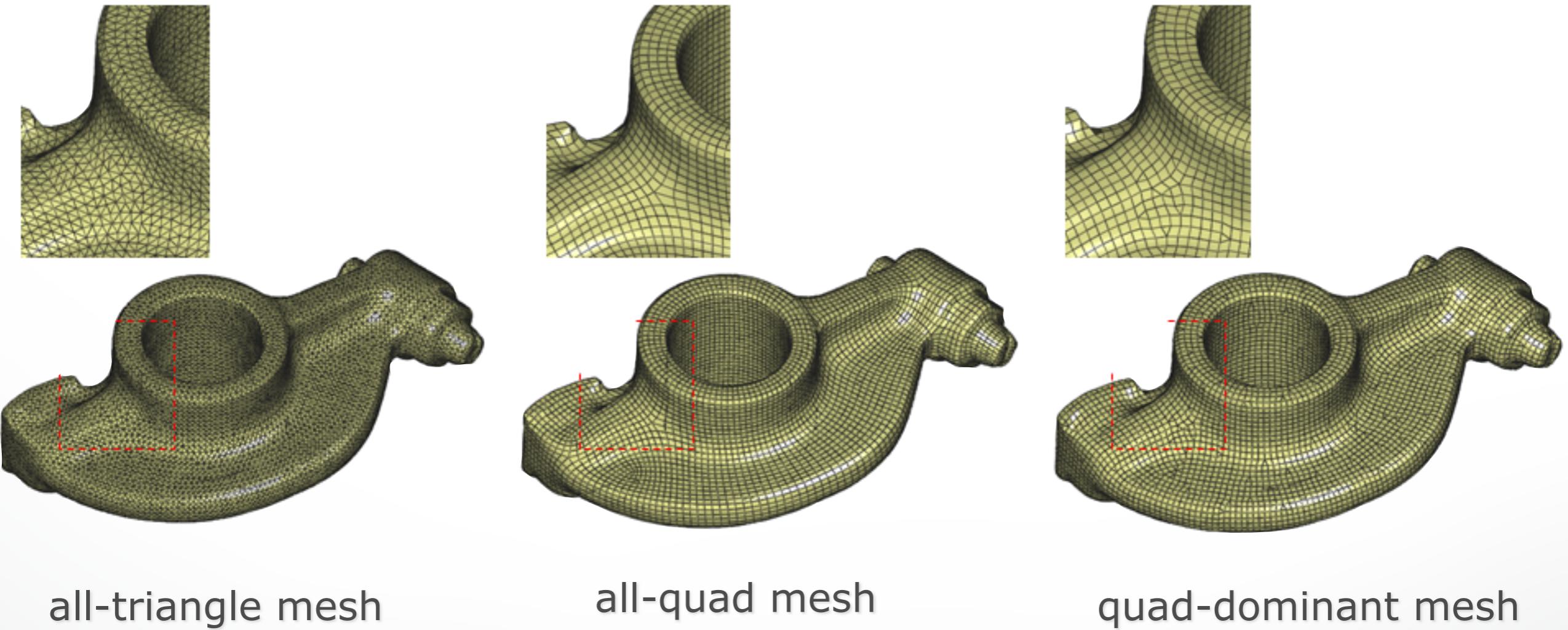
- Local structure
- Global structure



Local structure

Element type

- Triangles vs. quadrangles



all-triangle mesh

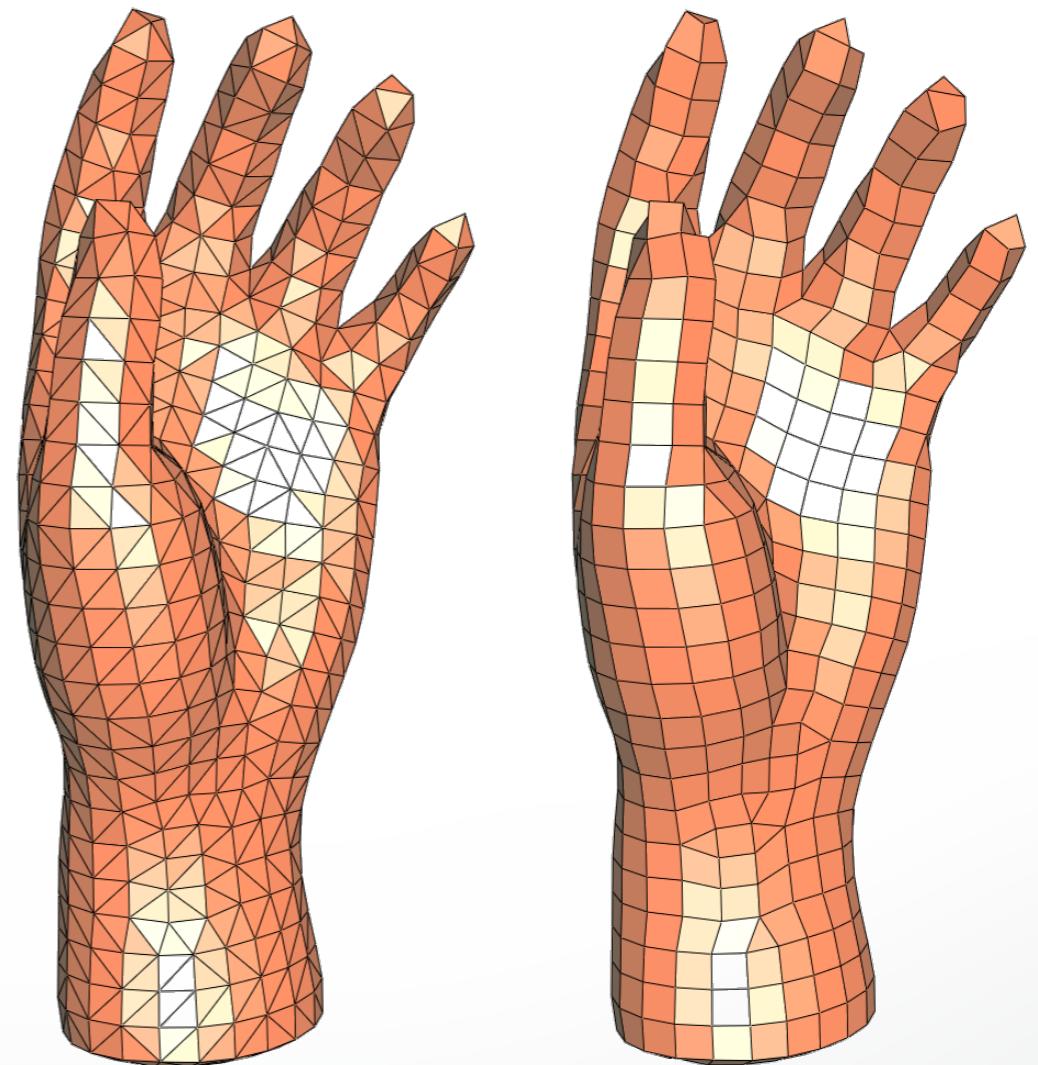
all-quad mesh

quad-dominant mesh

Local structure

Element type

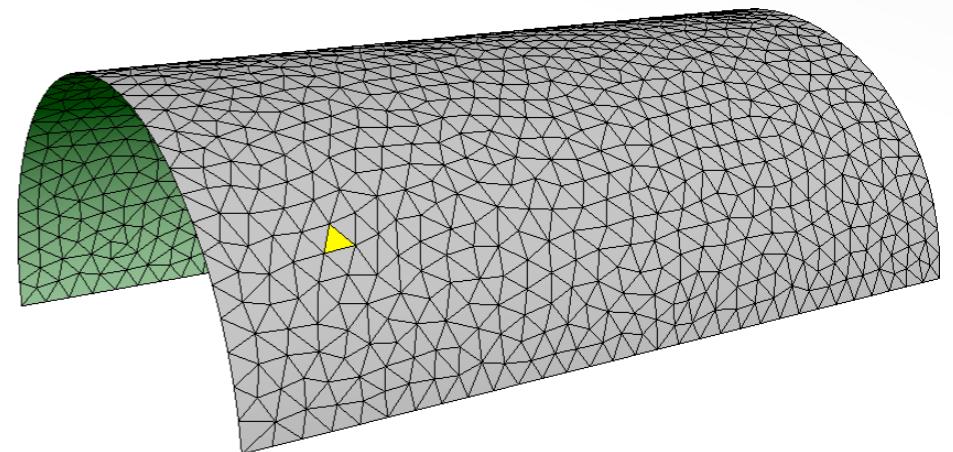
- Triangles vs. quadrangles



Local structure

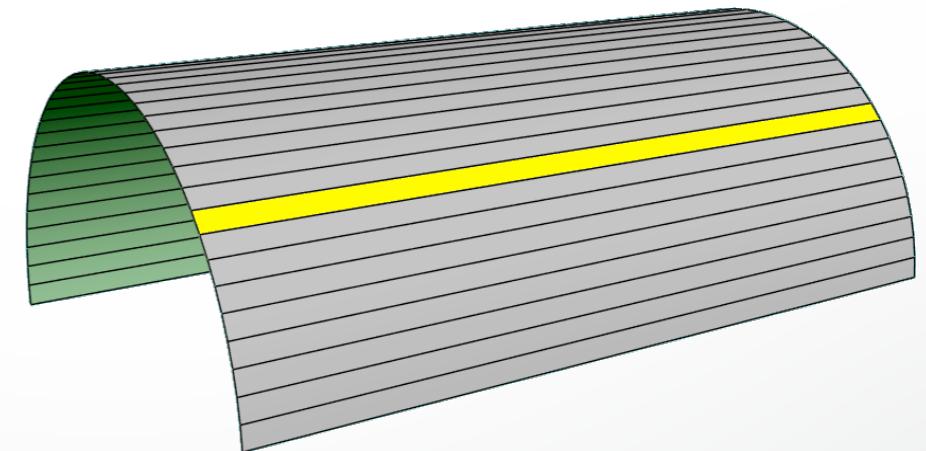
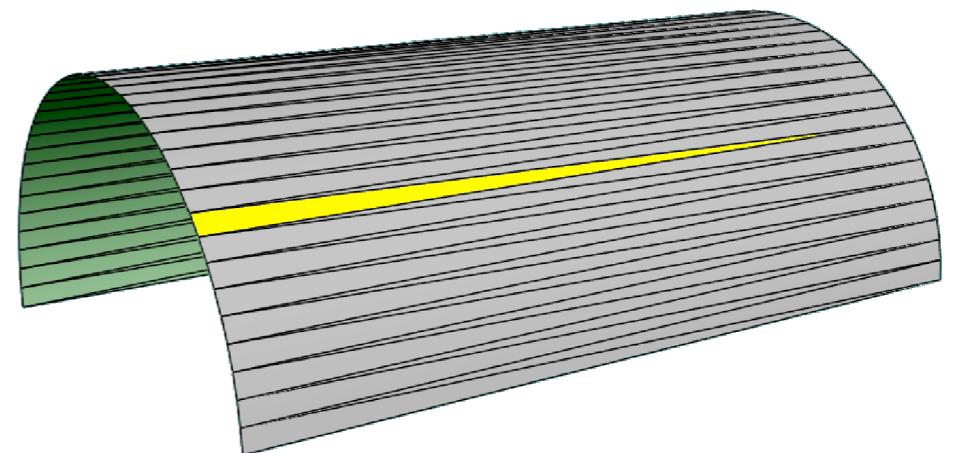
Element type

- Triangles vs. quadrangles



Element shape

- Isotropic vs. anisotropic



Local structure

Element type

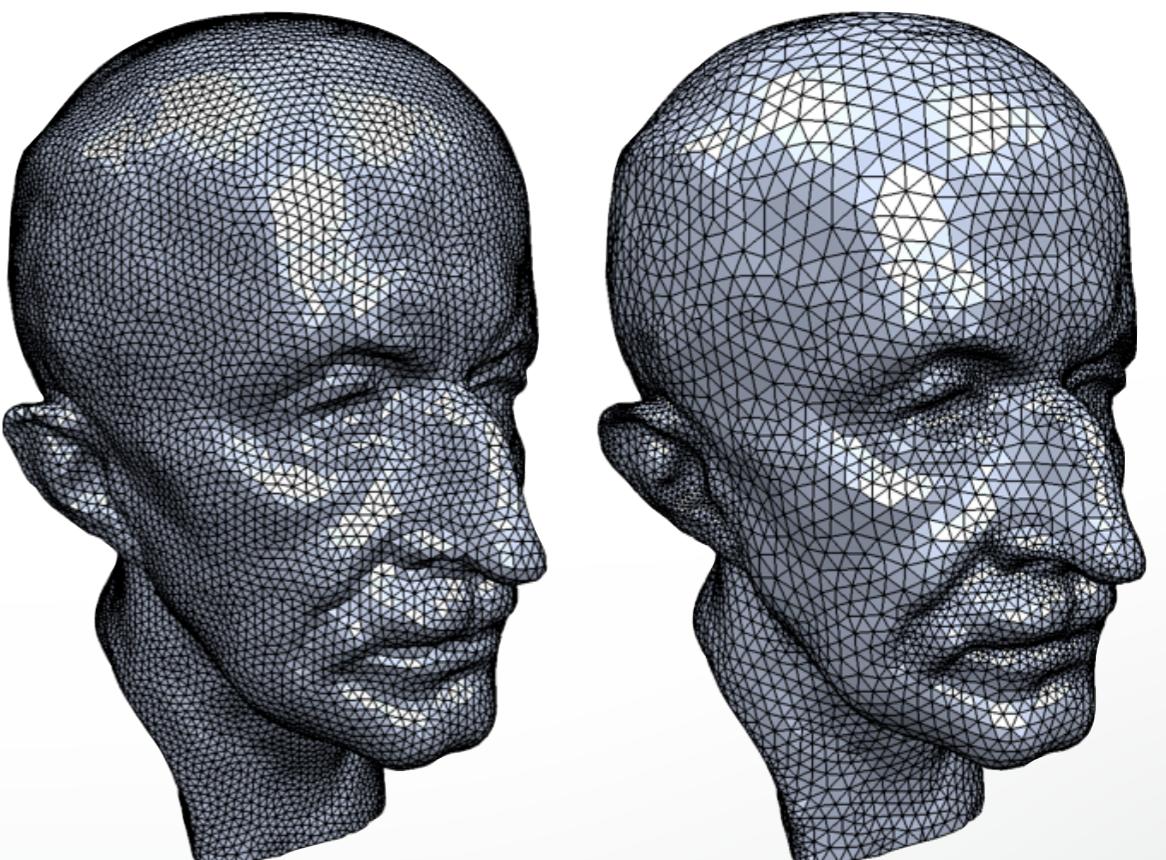
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Element shape

- Isotropic vs. anisotropic

Element distribution

- Uniform vs. adaptive



Local structure

Element type

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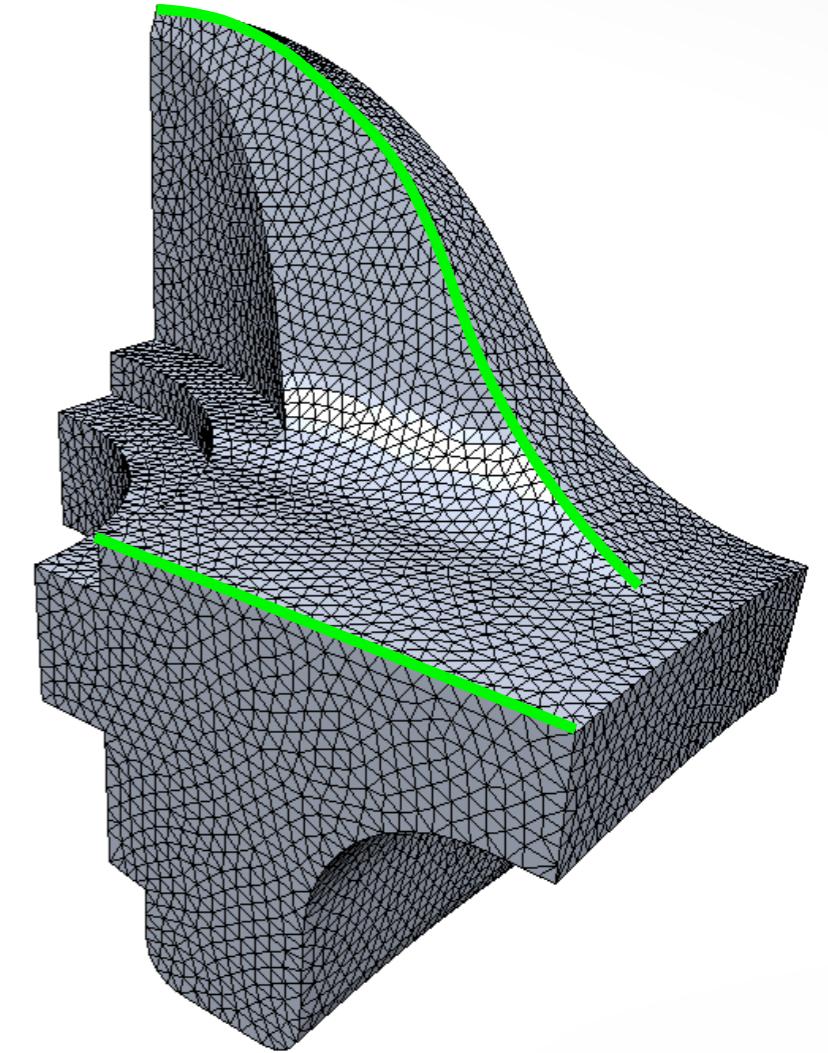
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Element distribution

- Uniform vs. adaptive

Element alignment

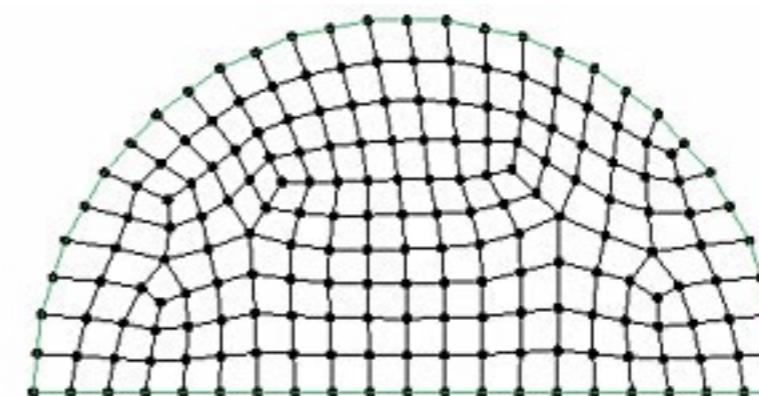
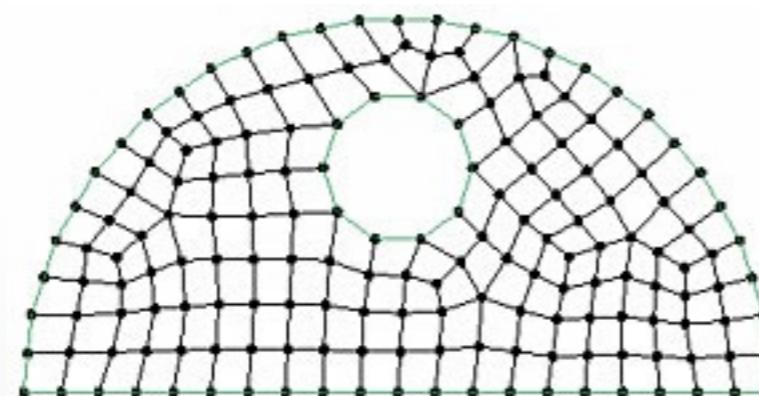
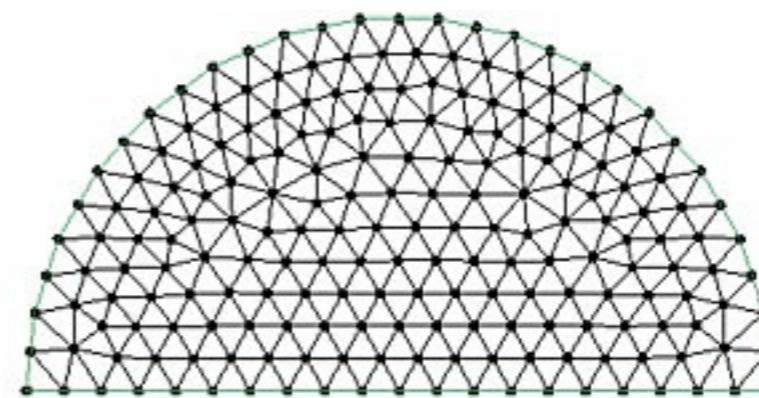
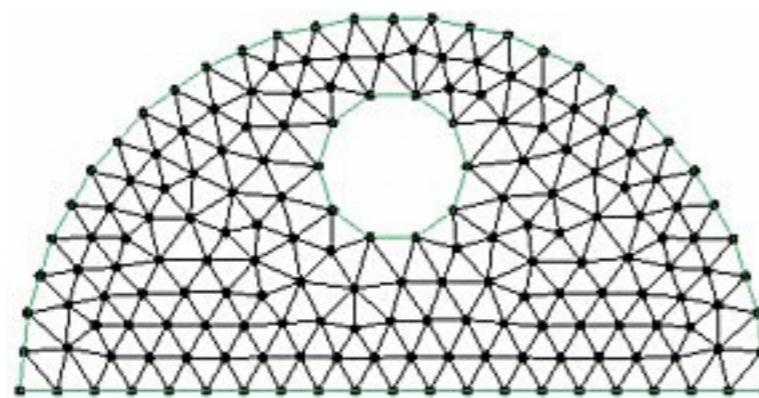
- Preserve sharp features and curvature lines



Global structure

Valence of a *regular* vertex

	Interior vertex	Boundary vertex
Triangle mesh	6	4
Quadrangle mesh	4	3



Global structure

Valence of a *regular* vertex

	Interior vertex	Boundary vertex
Triangle mesh	6	4
Quadrangle mesh	4	3

Different types of mesh structure

- Irregular
- Semi-regular: multi-resolution analysis / modeling
- Highly regular: numerical simulation
- Regular: only possible for special models

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 - **Isotropic remeshing**
 - Anisotropic remeshing

Isotropic remeshing

Incremental remeshing

- Simple to implement and robust
- Not need parameterization
- Efficient for high-resolution input

Variational remeshing

- Energy minimization
- Parameterization-based → expensive
- Works for coarse input mesh

Greedy remeshing

Isotropic remeshing

Incremental remeshing

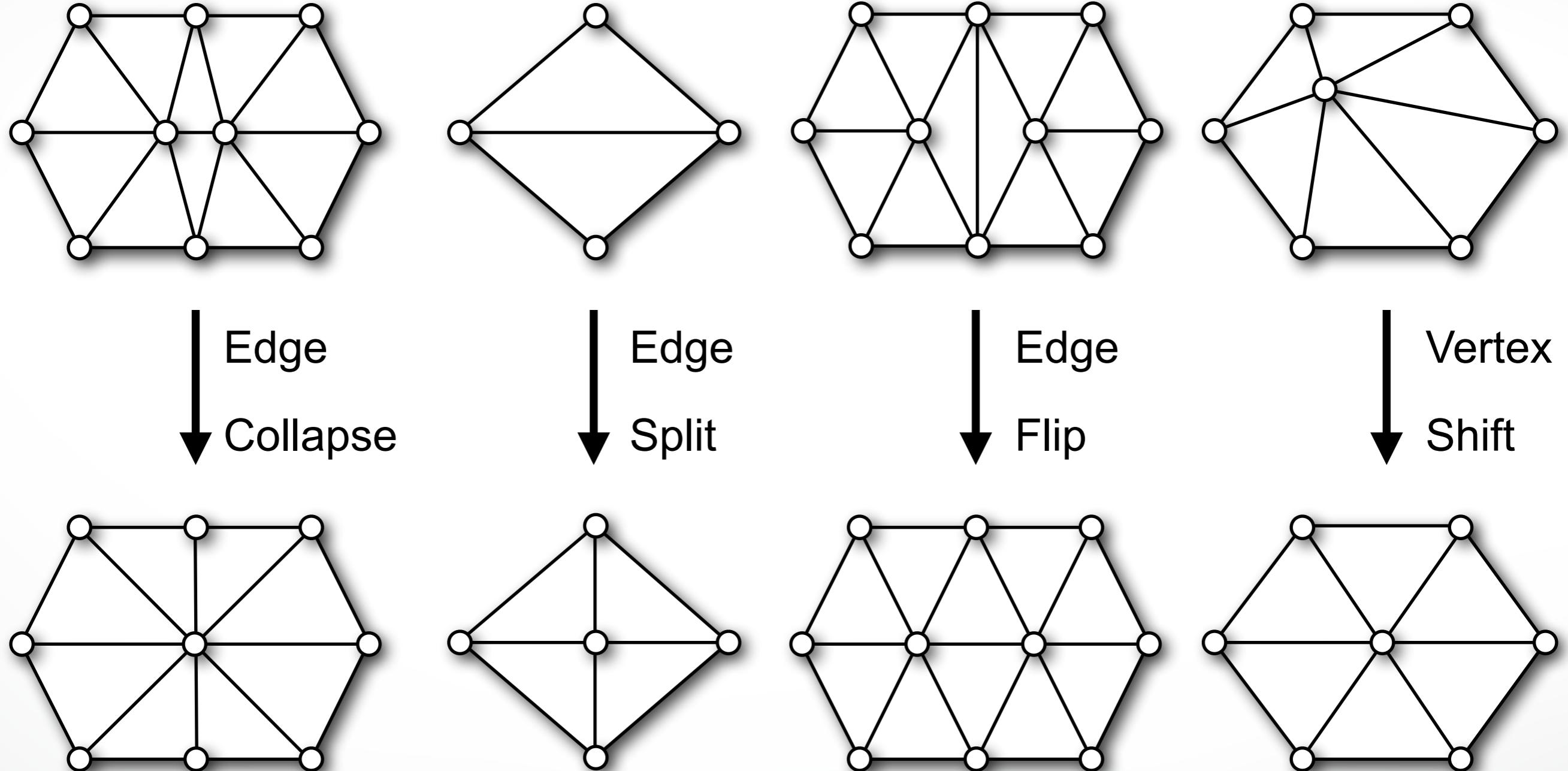
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Greedy remeshing

Local remeshing operators



Incremental remeshing

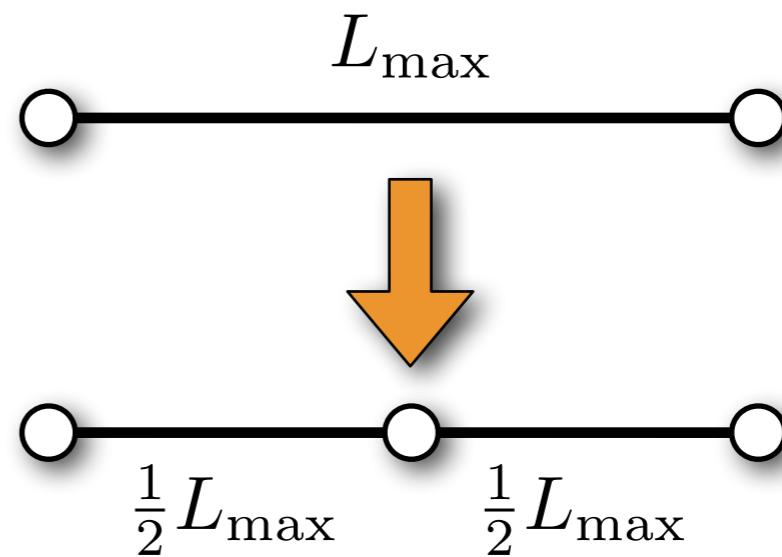
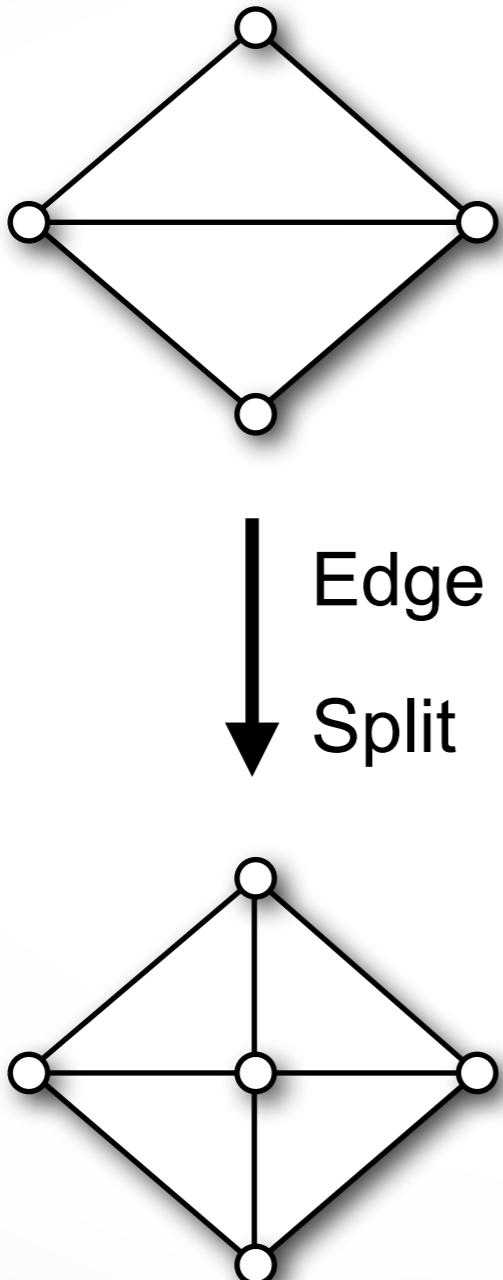
Specify target edge length L

$$L_{\max} = 4/3 * L; L_{\min} = 4/5 * L;$$

Iterate:

1. Split edges longer than L_{\max}
2. Collapse edges shorter than L_{\min}
3. Flip edges to get closer to optimal valence
4. Vertex shift by tangential relaxation
5. Project vertices onto reference mesh

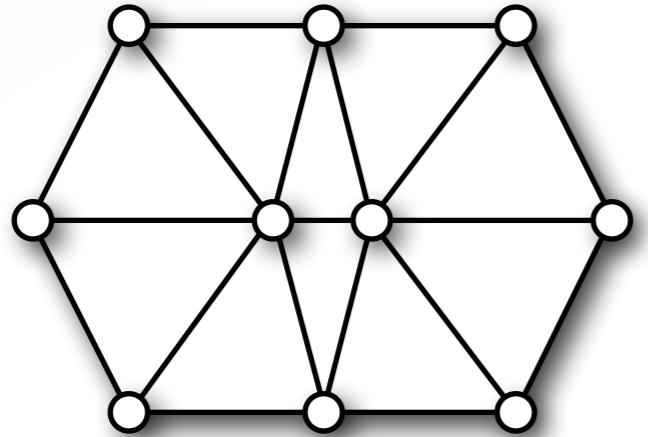
Edge split



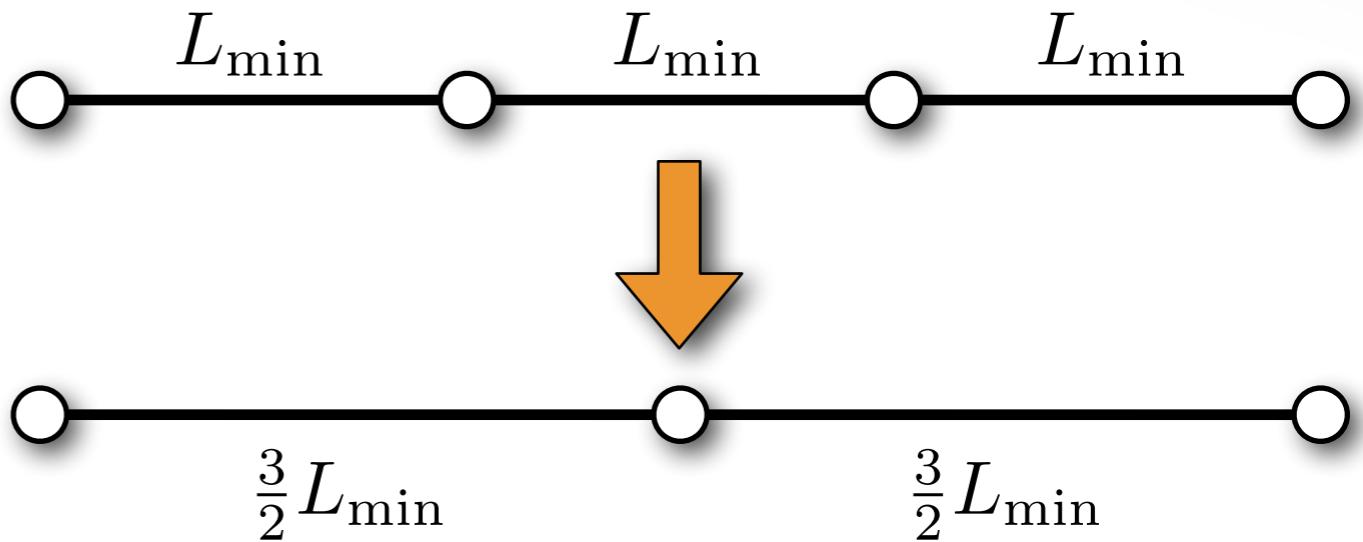
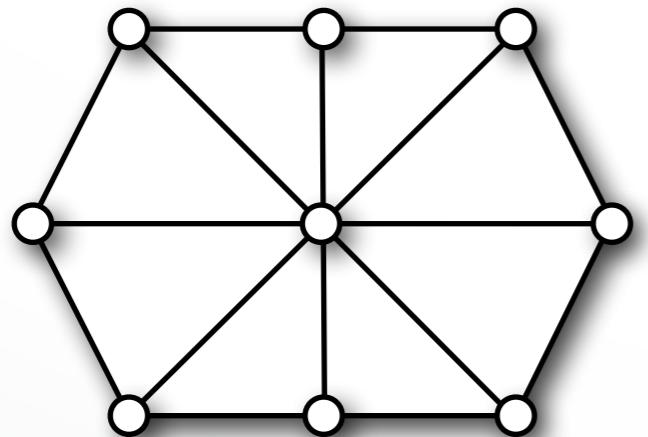
$$\begin{aligned}|L_{\max} - L| &= \left| \frac{1}{2}L_{\max} - L \right| \\ \Rightarrow L_{\max} &= \frac{4}{3}L\end{aligned}$$

Split edges longer than **L_{max}**

Edge collapse



Edge
Collapse



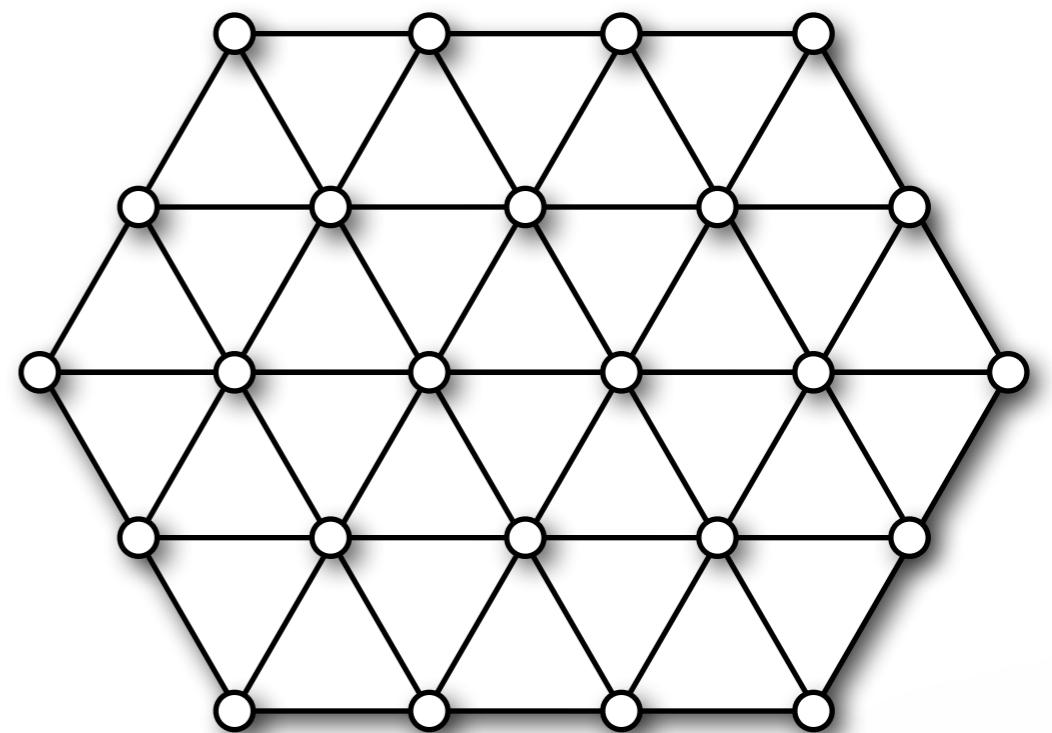
$$\begin{aligned}|L_{\min} - L| &= \left| \frac{3}{2}L_{\min} - L \right| \\ \Rightarrow L_{\min} &= \frac{4}{5}L\end{aligned}$$

Collapse edges shorter than L_{\min}

Edge flip

Optimal valence

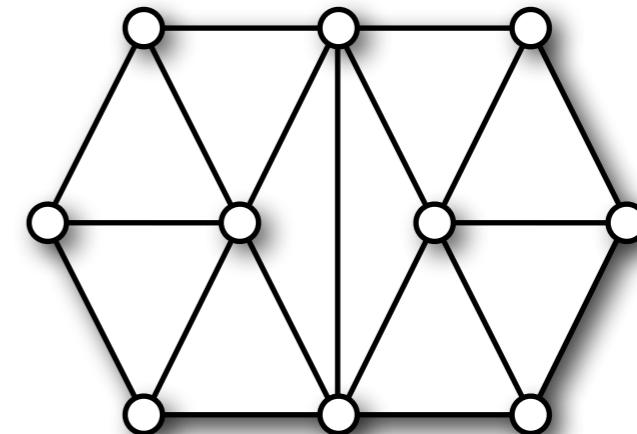
- 6 for interior vertices
- 4 for boundary vertices



Edge flip

Optimal valence

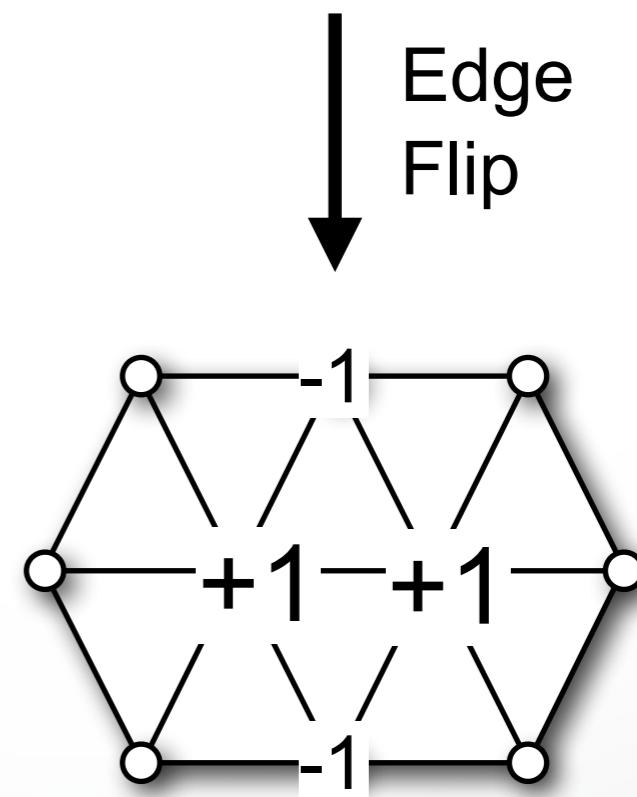
- 6 for interior vertices
- 4 for boundary vertices



Improve valences

- Minimize valence excess

$$\sum_{i=1}^4 (\text{valence}(v_i) - \text{opt_valence}(v_i))^2$$

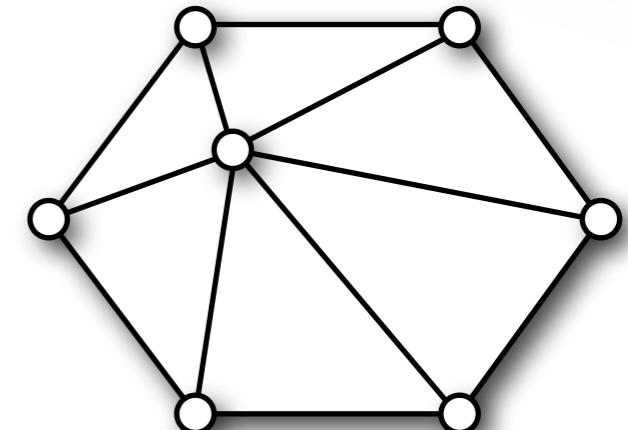


Vertex shift

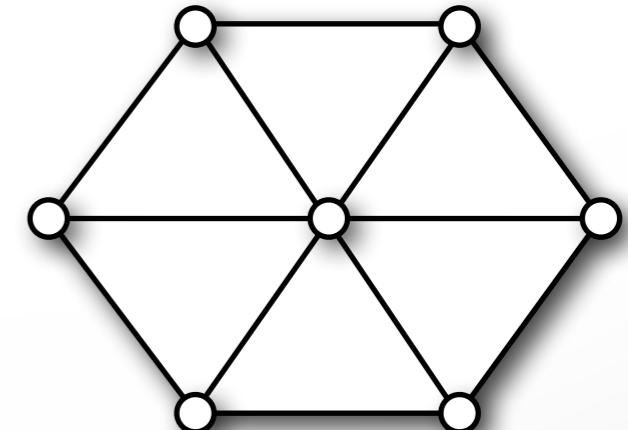
Local “spring” relaxation

- Uniform Laplacian smoothing
- Barycenter of one-ring neighborhood

$$\mathbf{c}_i = \frac{1}{\text{valence}(v_i)} \sum_{j \in N(v_i)} \mathbf{p}_j$$



Vertex
Shift

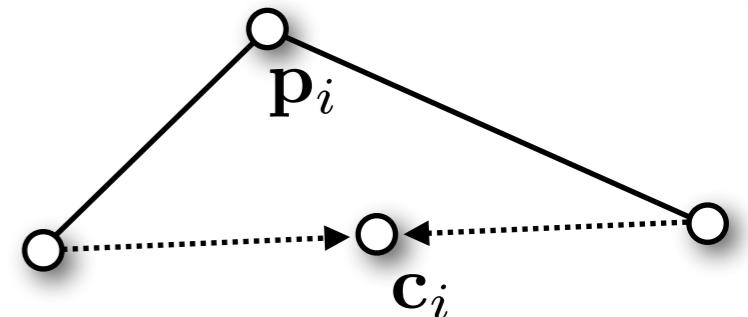


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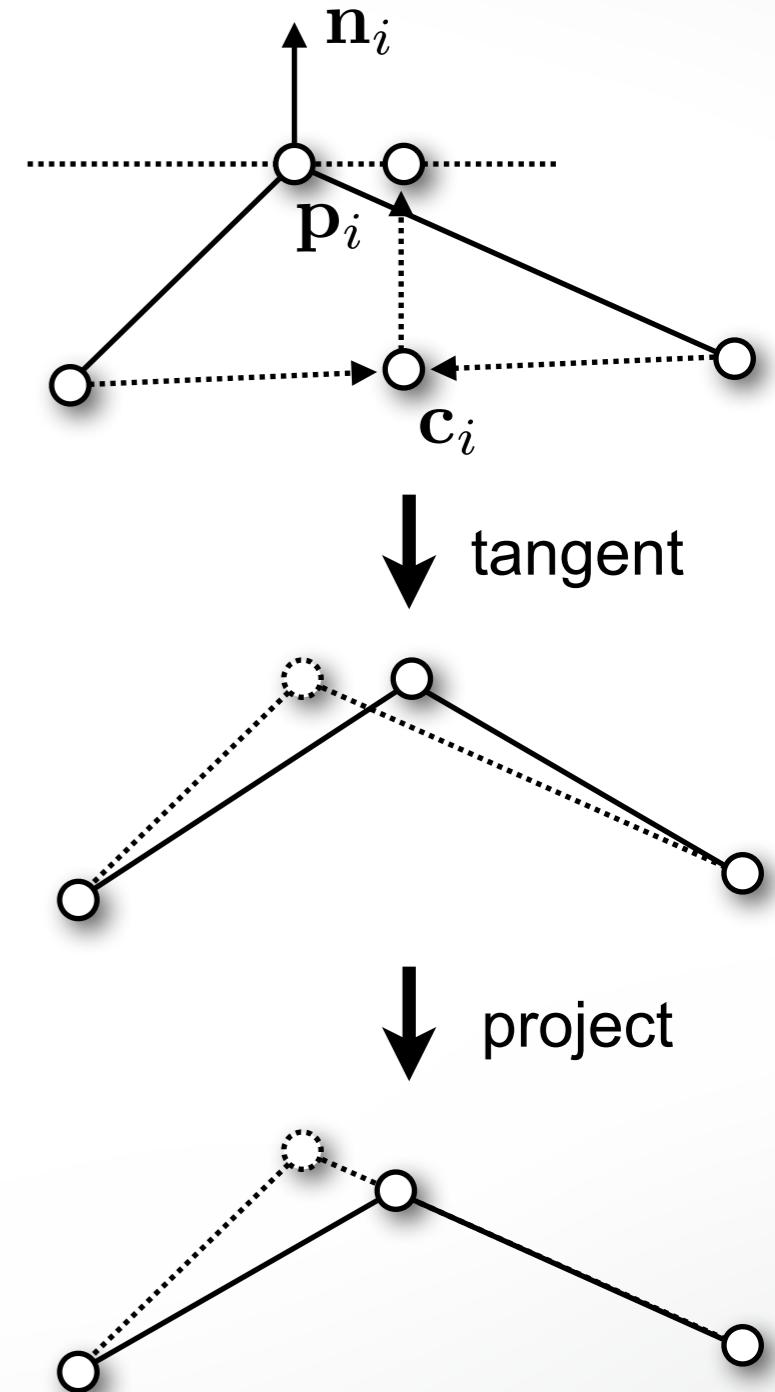


Vertex shift

Local “spring” relaxation

- Uniform Laplacian smoothing
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Keep vertex (approx.) on surface

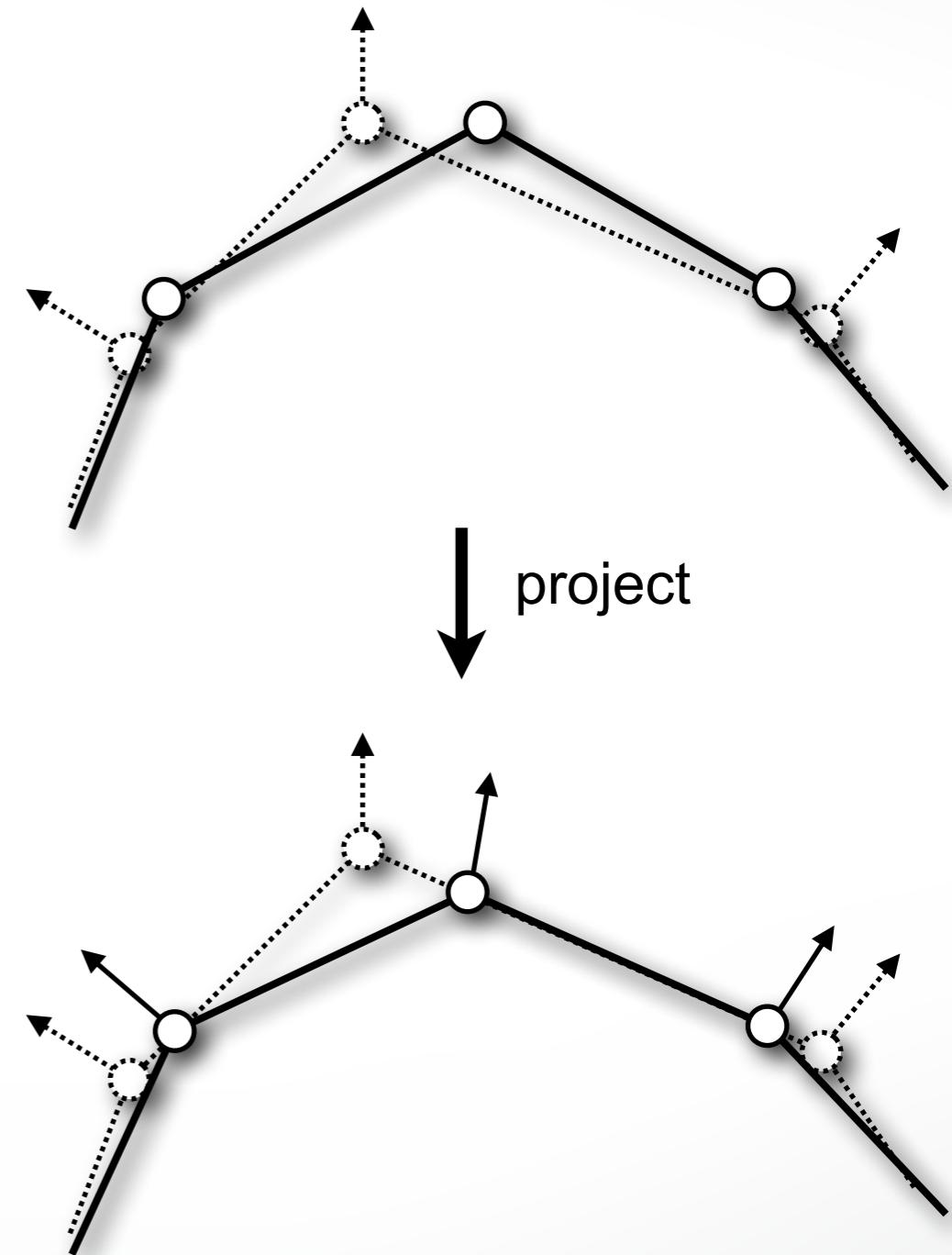
- Restrict movement to tangent plane

$$\mathbf{p}_i \leftarrow \mathbf{p}_i + \lambda (\mathbf{I} - \mathbf{n}_i \mathbf{n}_i^T) (\mathbf{c}_i - \mathbf{p}_i)$$

Vertex projection

Onto original reference mesh

- Find closest triangle
- Use BSP to accelerate $\rightarrow O(\log n)$
- Barycentric interpolation to compute position & normal



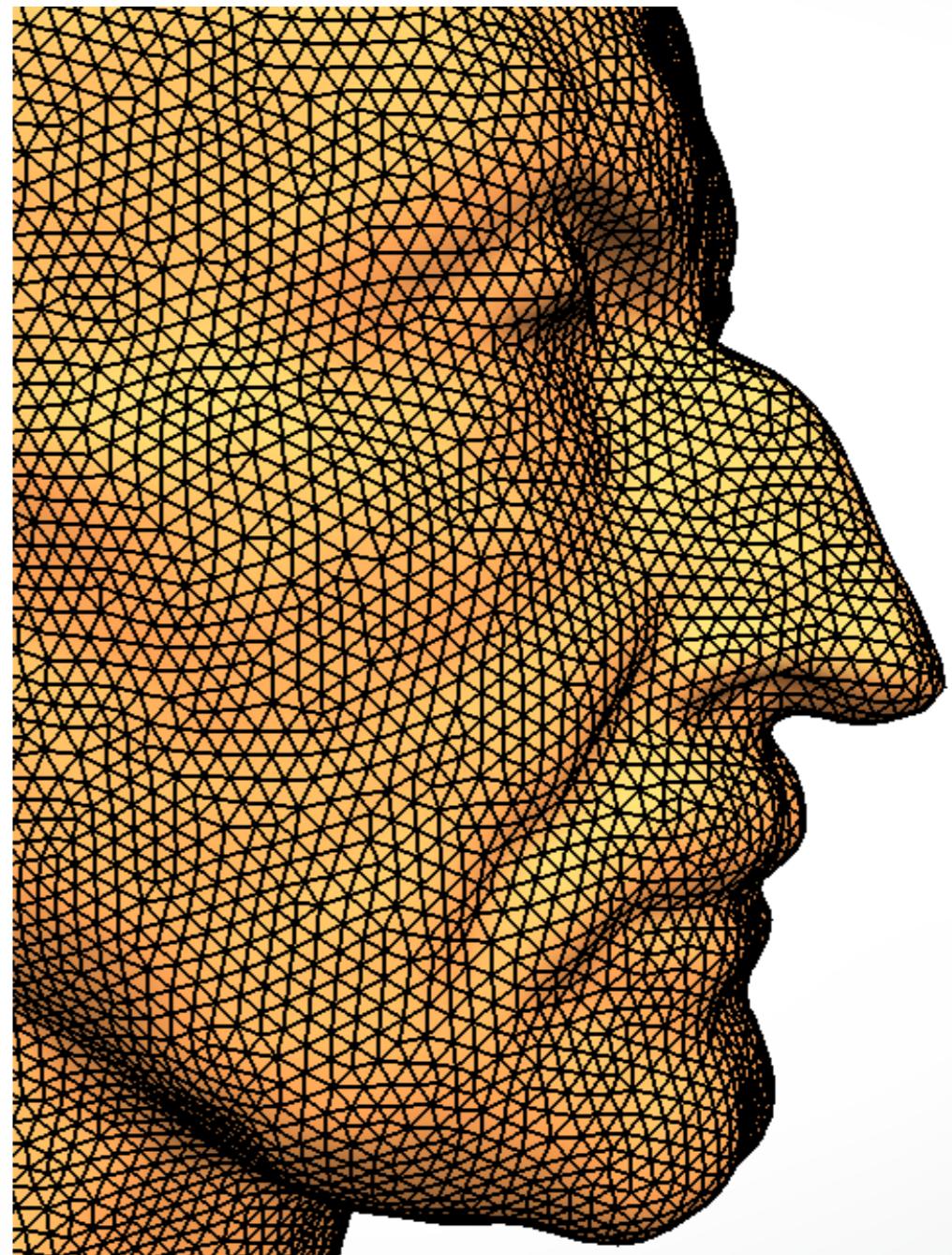
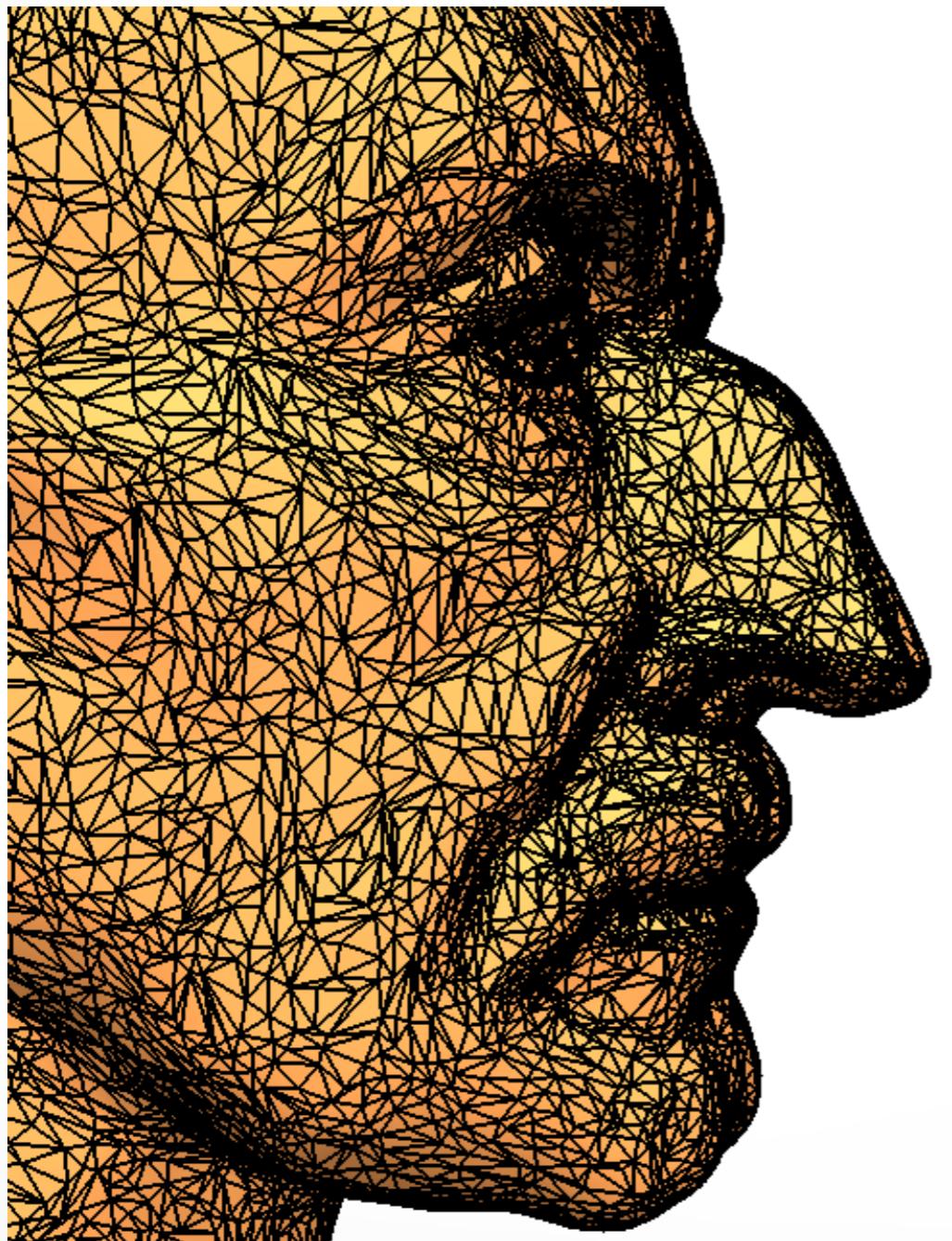
Incremental remeshing

Specify target edge length L

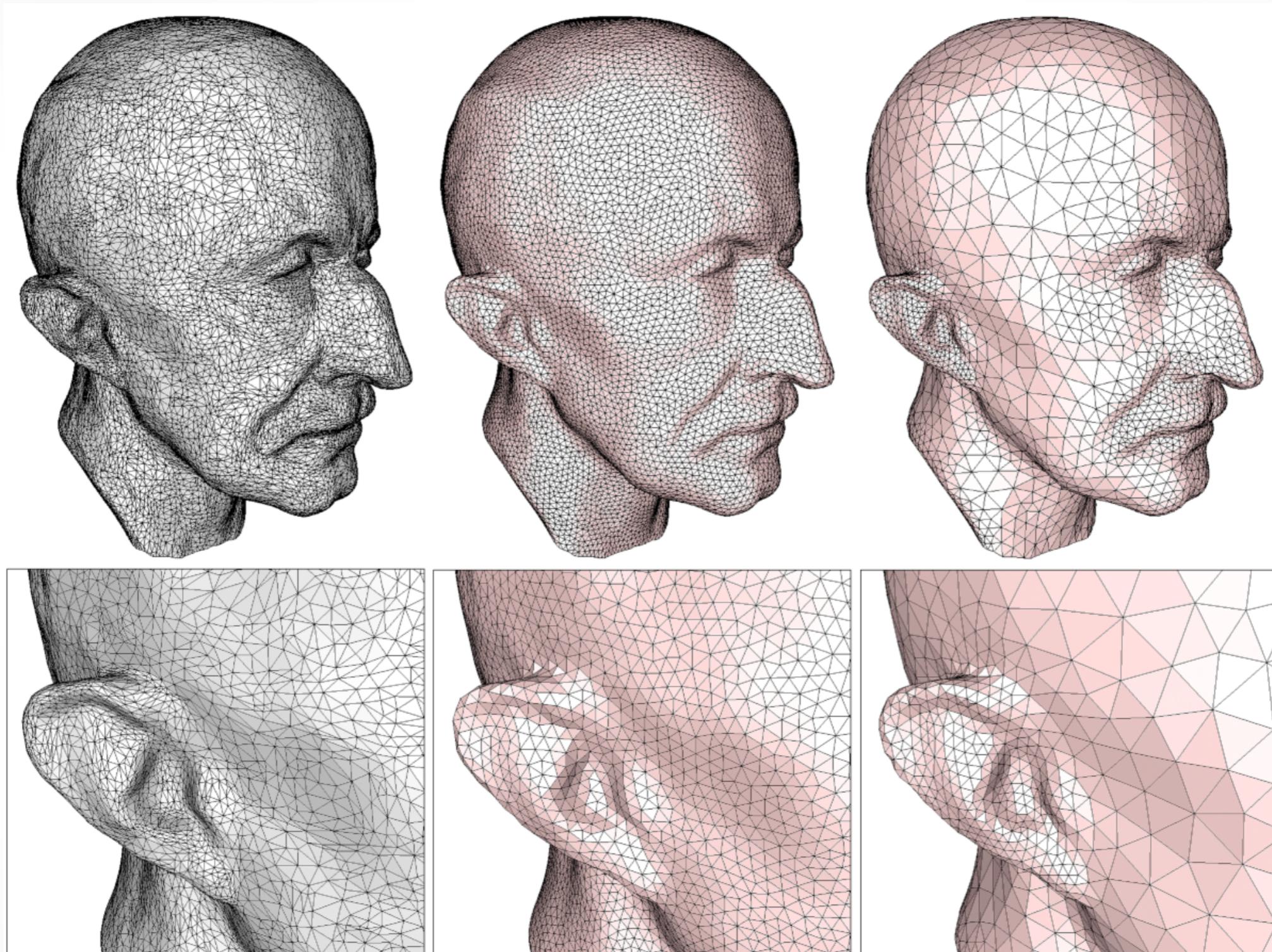
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Remeshing result

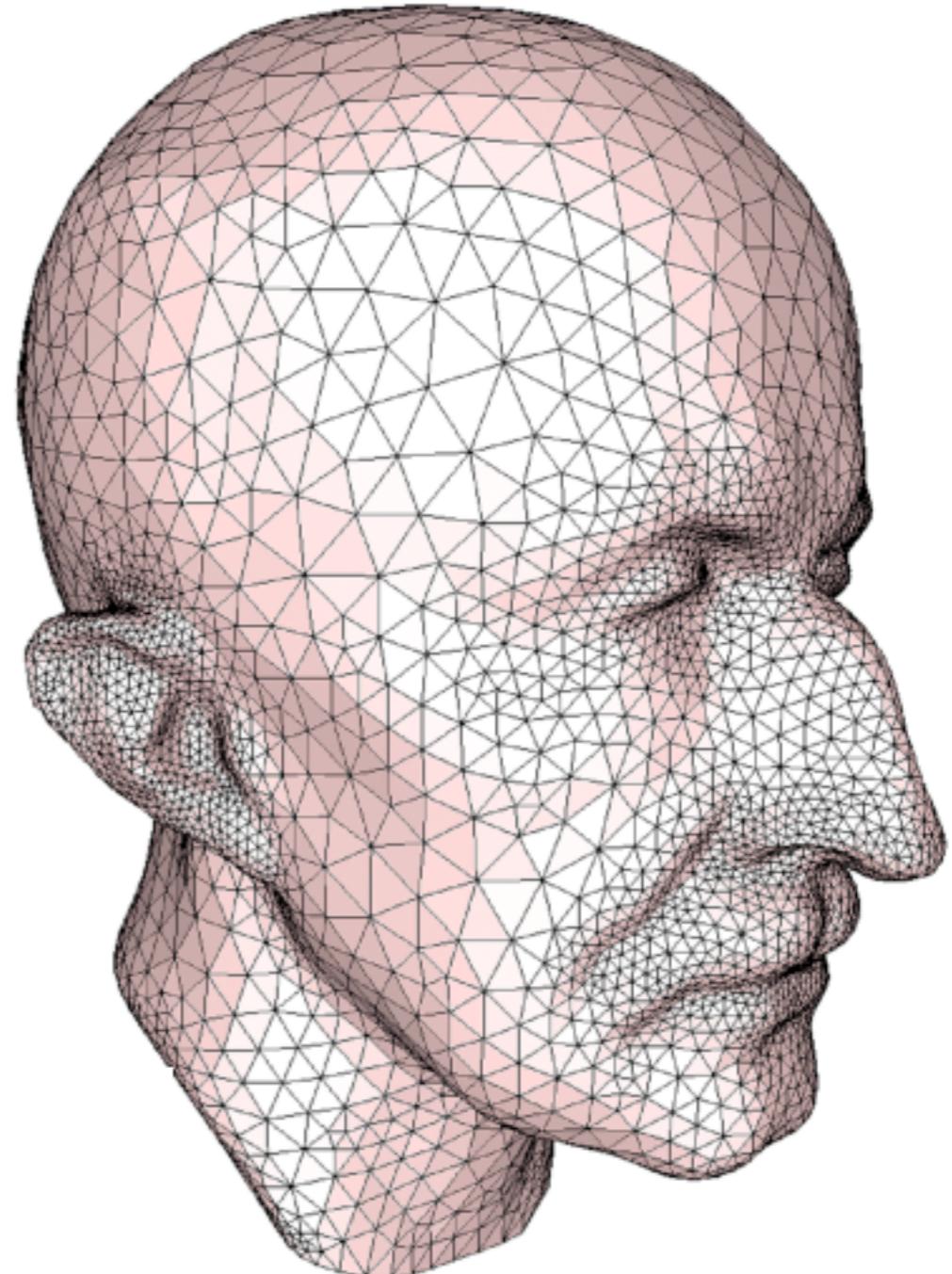


Adaptive remeshing

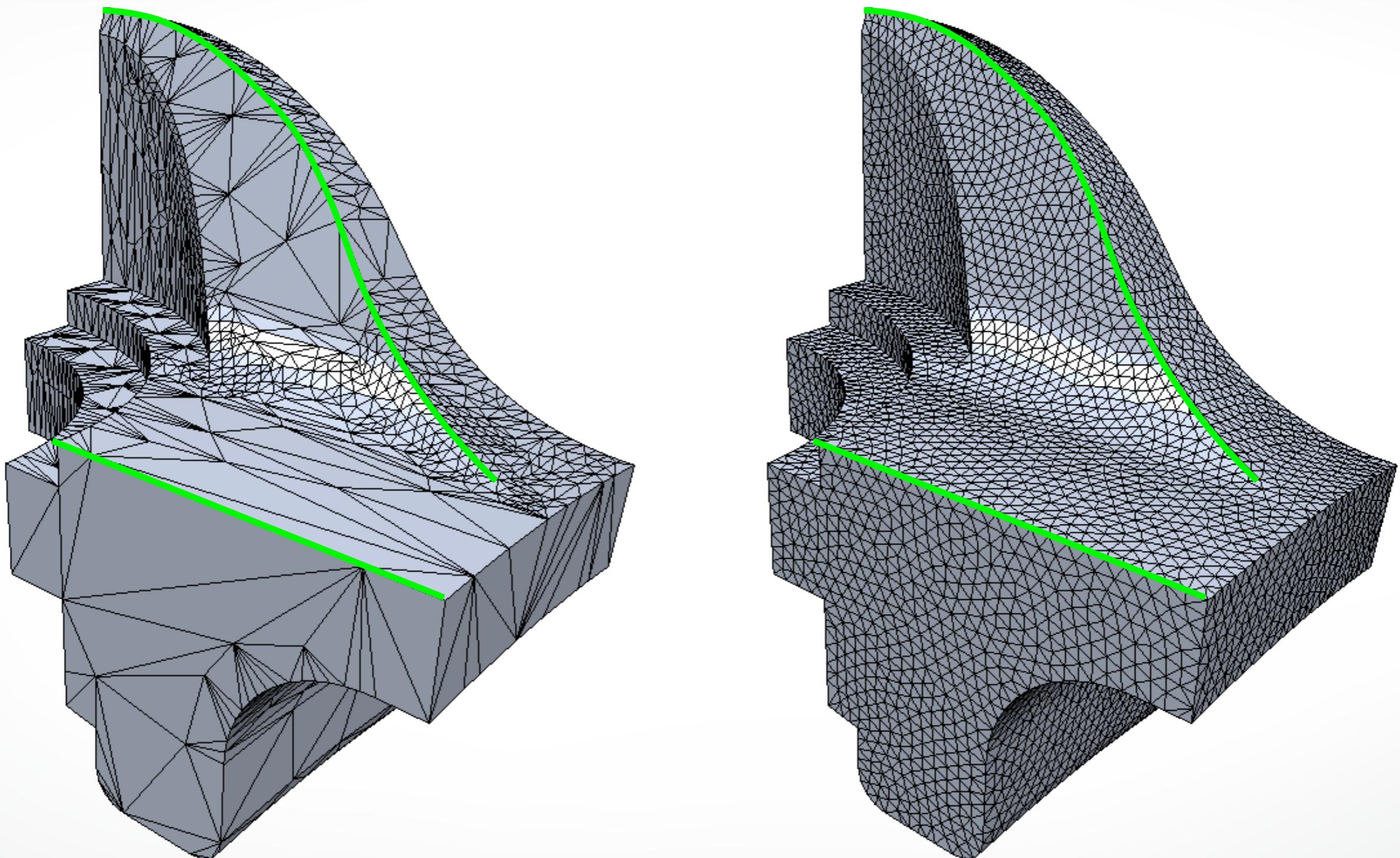


Adaptive remeshing

- Compute maximum principle curvature on reference mesh
- Determine local target edge length from max-curvature
- Adjust edge split / collapse criteria accordingly



Feature preservation



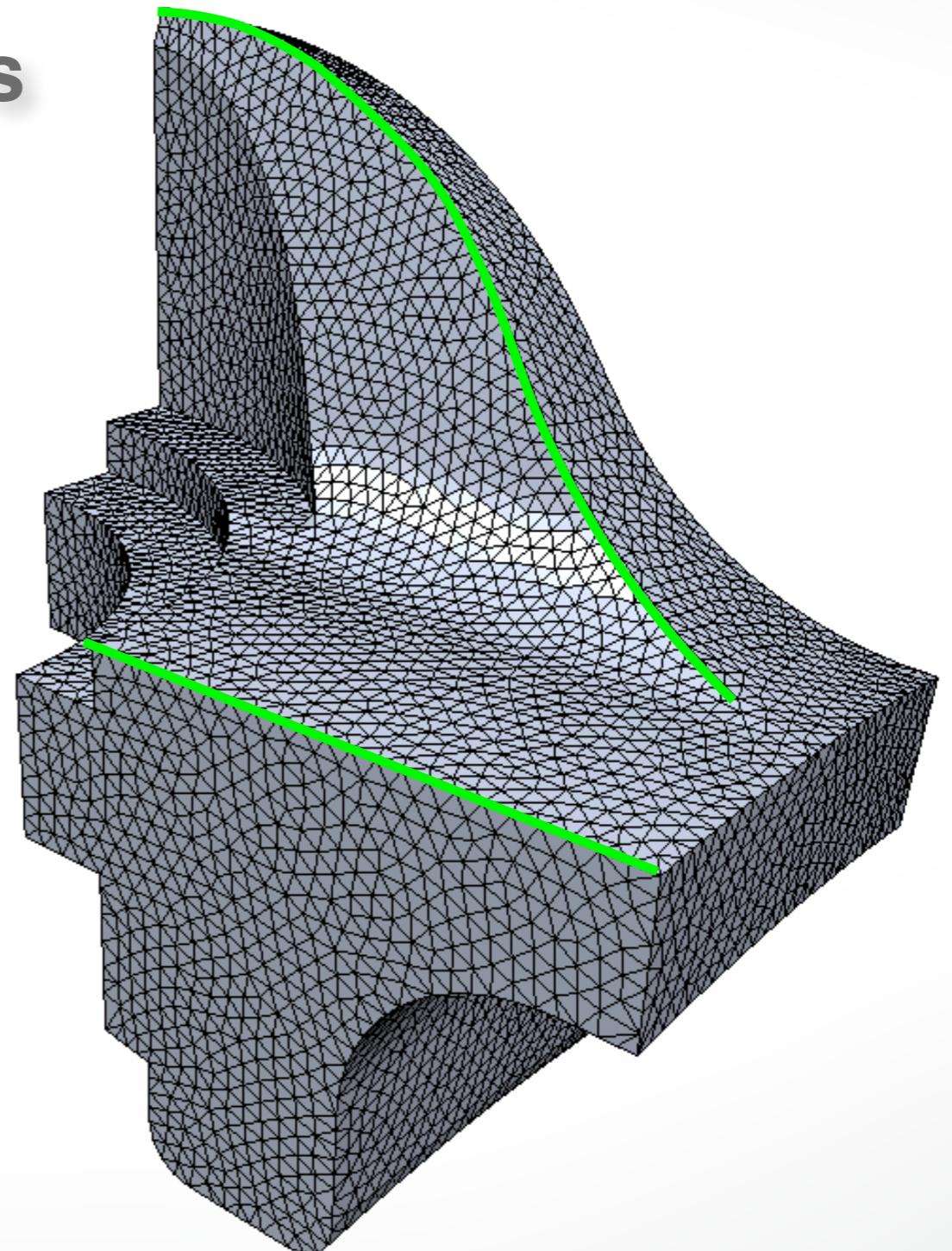
Feature preservation

Define feature edges / vertices

- Large dihedral angles
- Material boundaries

Adjust local operators

- Do not touch corner vertices
- Do not flip feature edges
- Collapse along features
- Univariate smoothing
- Project to feature curves



Isotropic remeshing

Incremental remeshing

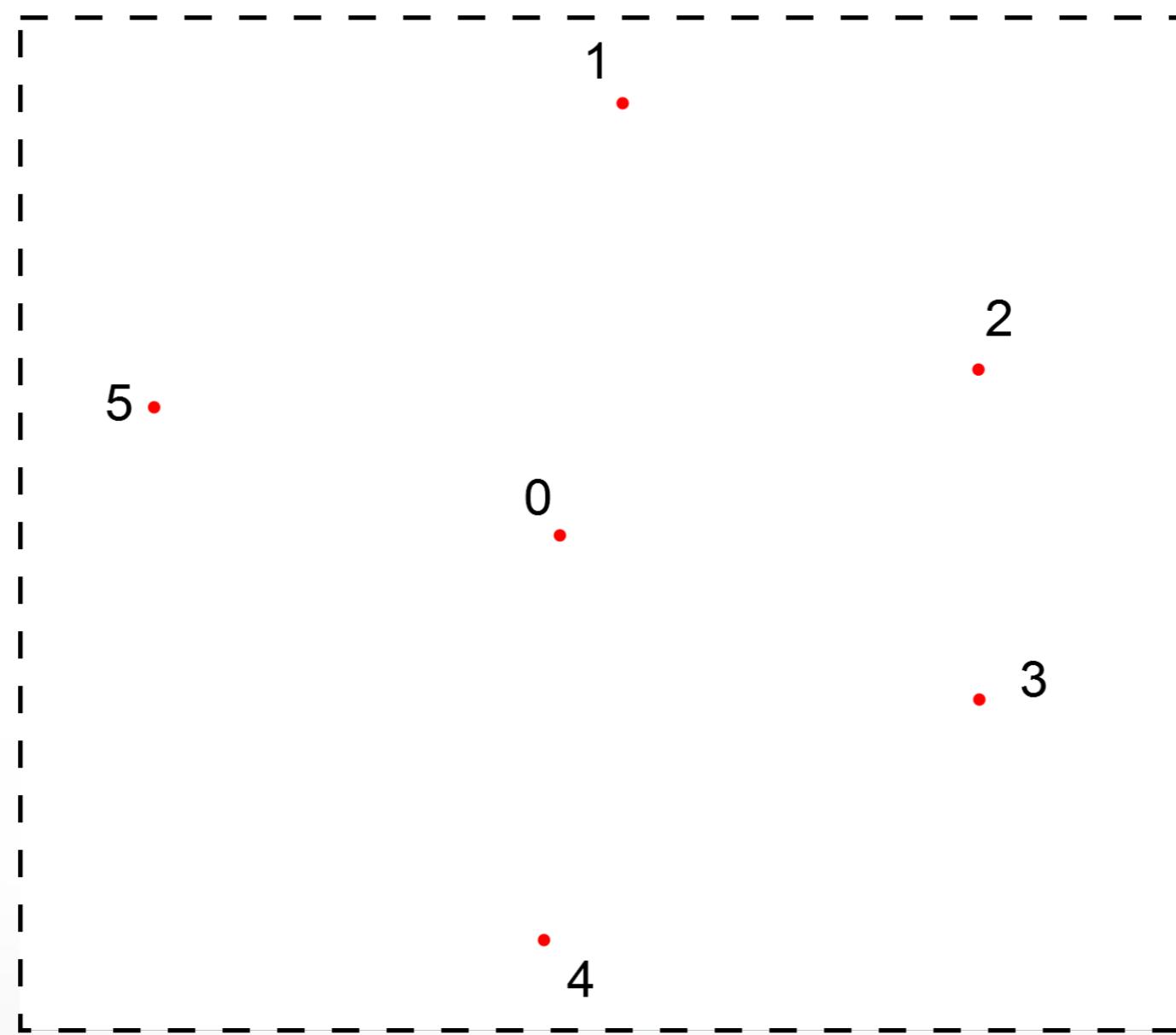
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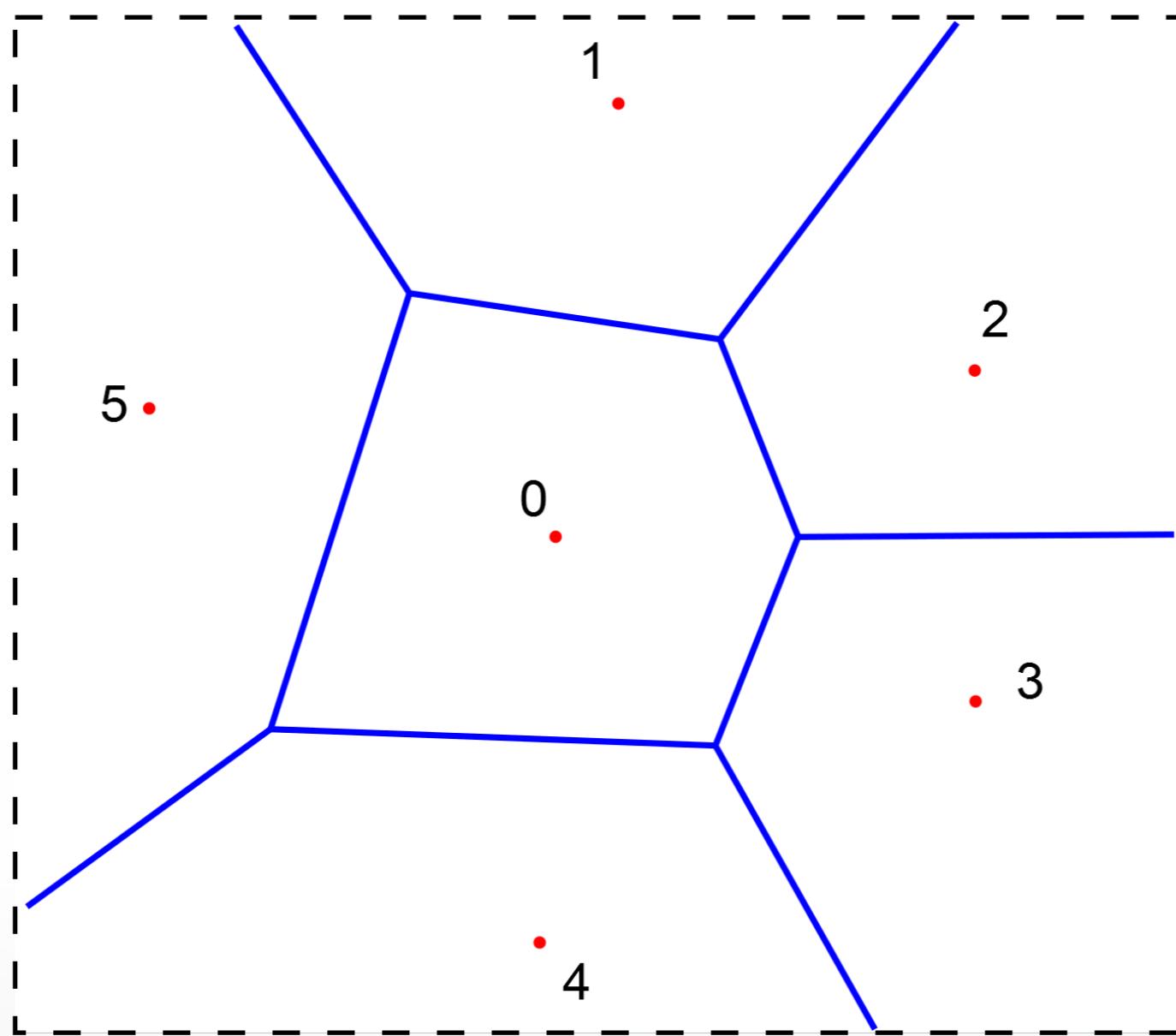
Greedy remeshing

Voronoi Diagram



Voronoi Diagram

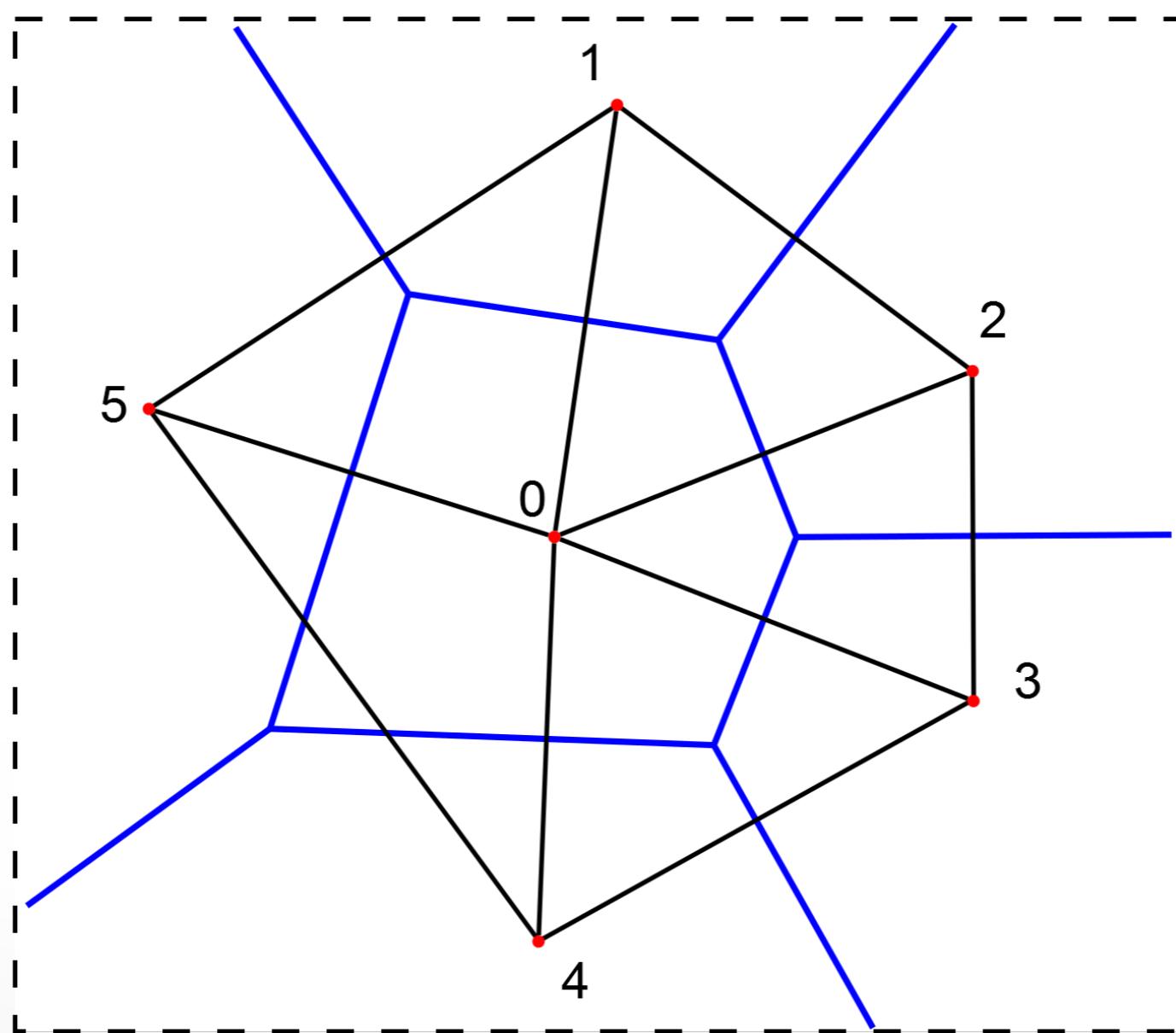
Divide space into a number of cells



Voronoi Diagram

Divide space into a number of cells

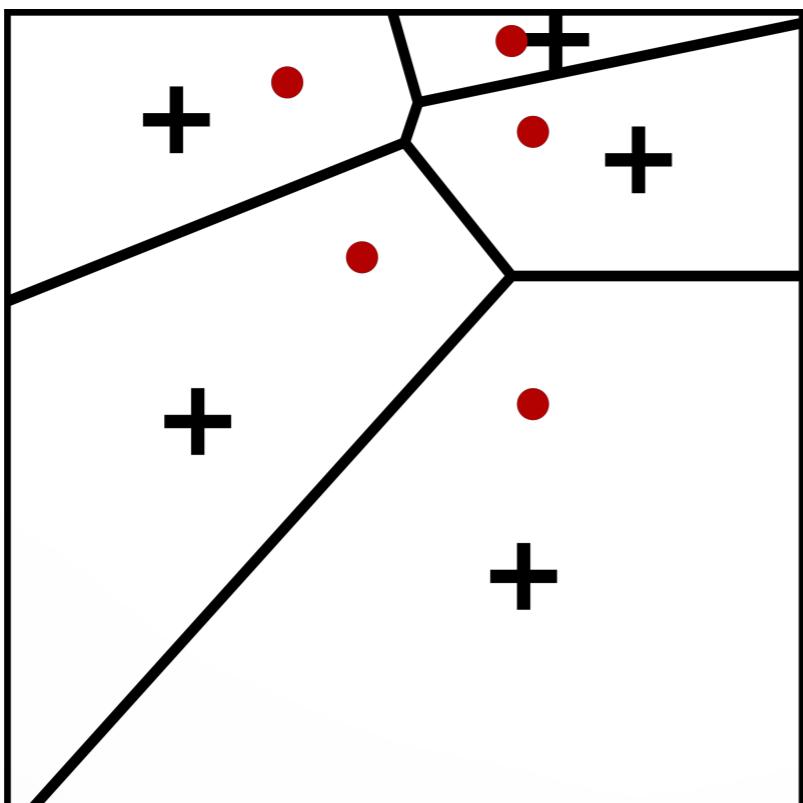
Dual graph: Delaunay triangulation



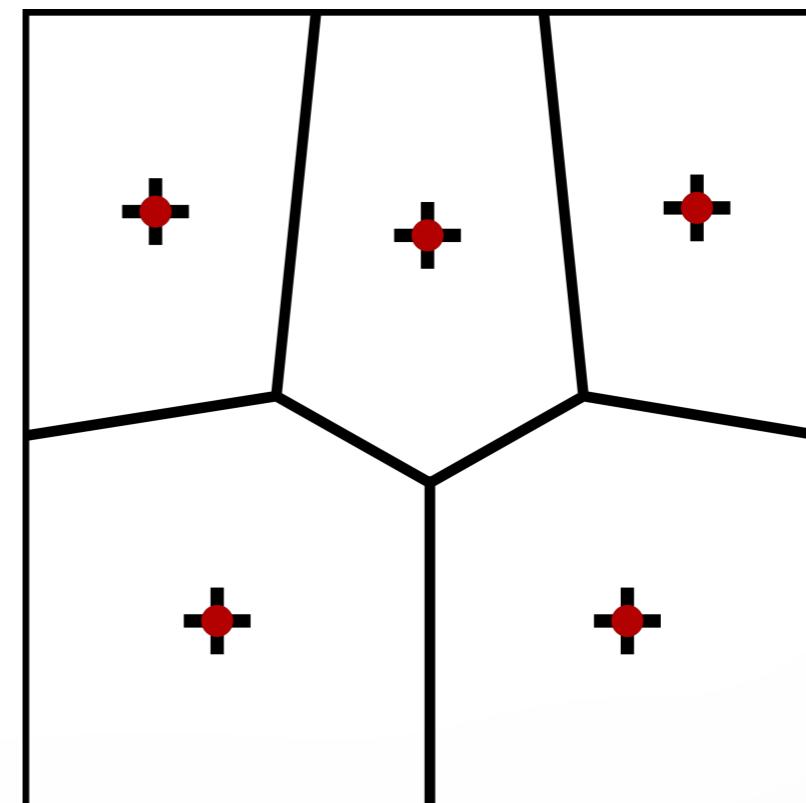
Centroidal Voronoi Diagram

For each cell

The generating point ● = mass of center +



non CVD



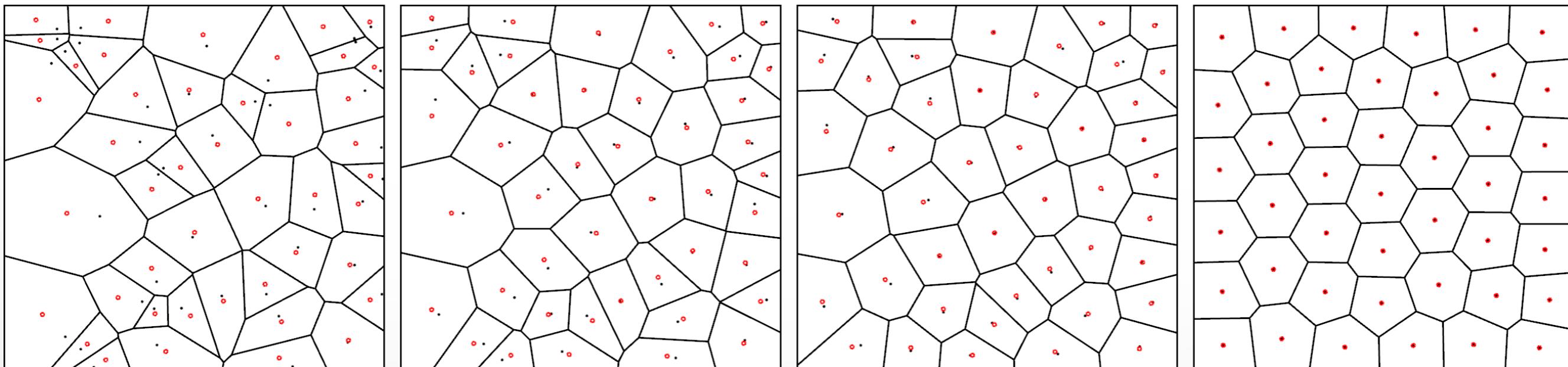
CVD

Centroidal Voronoi Diagram

Compute CVD by Lloyd relaxation

1. Compute Voronoi diagram of given points \mathbf{p}_i
2. Move points \mathbf{p}_i to centroids \mathbf{c}_i of their Voronoi cells V_i
3. Repeat steps 1 and 2 until satisfactory convergence

$$\mathbf{p}_i \leftarrow \mathbf{c}_i = \frac{\int_{V_i} \mathbf{x} \cdot \rho(\mathbf{x}) \, d\mathbf{x}}{\int_{V_i} \rho(\mathbf{x}) \, d\mathbf{x}}$$



Centroidal Voronoi Diagram

Compute CVD by Lloyd relaxation

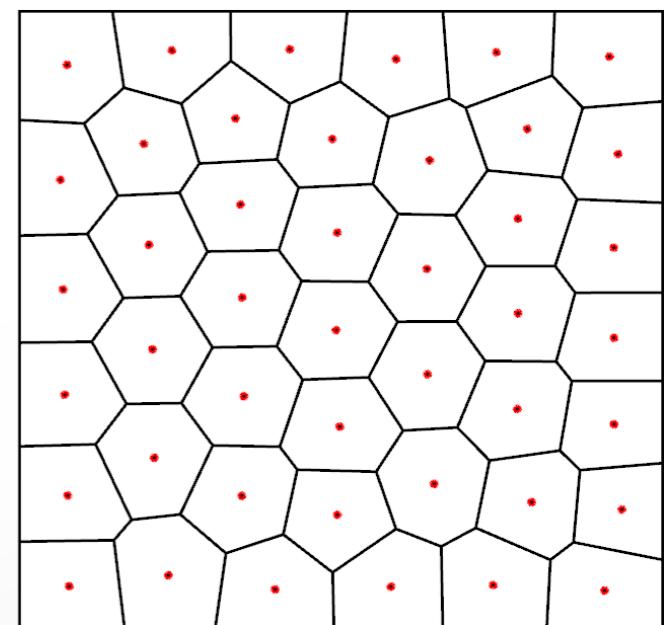
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CVD maximizes compactness

- Minimize the energy:

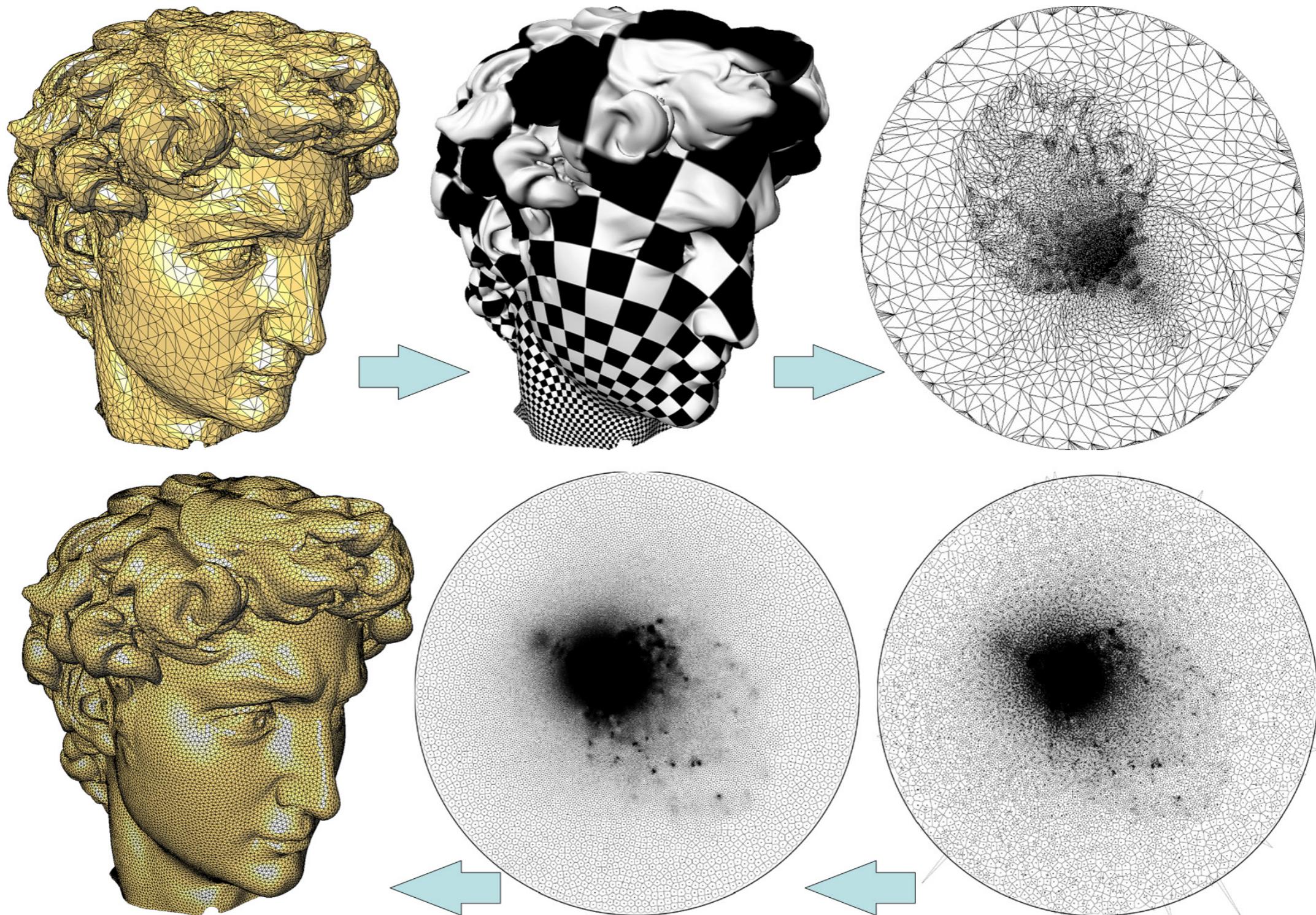
$$\sum_i \int_{V_i} \rho(\mathbf{x}) \|\mathbf{x} - \mathbf{p}_i\|^2 \, d\mathbf{x} \rightarrow \min$$



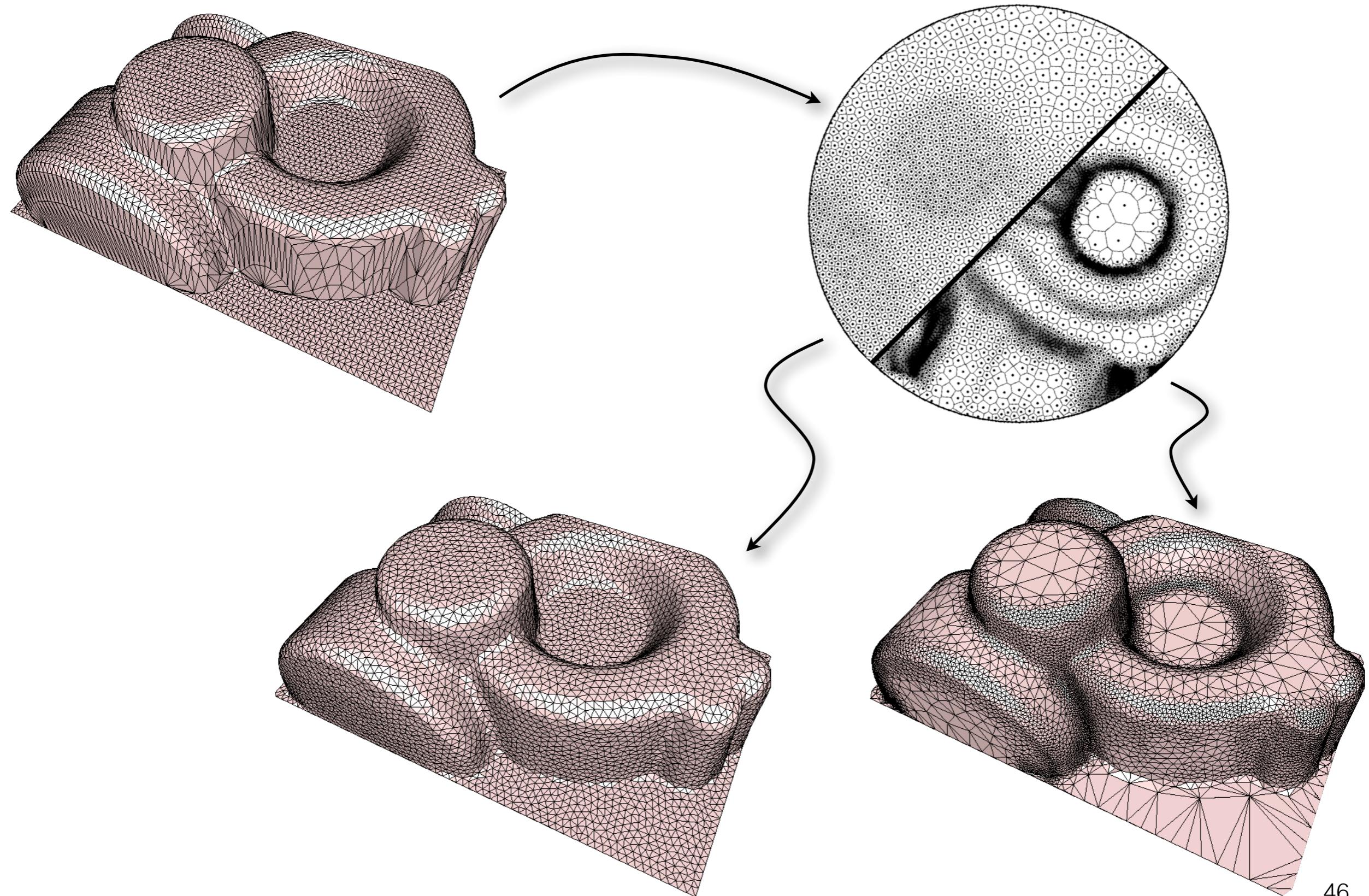
Variational remeshing

- 1. Conformal parameterization of input mesh**
- 2. Compute local density**
- 3. Perform in 2D parameter space**
 - A. Randomly sample according to local density
 - B. Compute CVD by Lloyd relaxation
- 4. Lift 2D Delaunay triangulation to 3D**

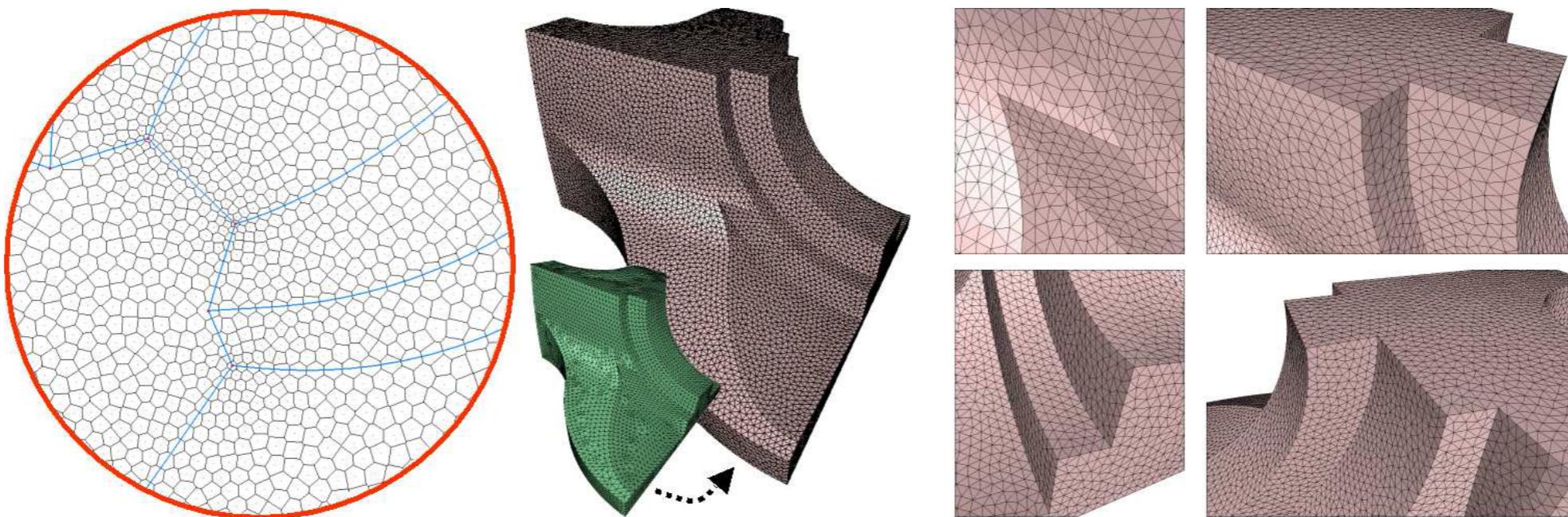
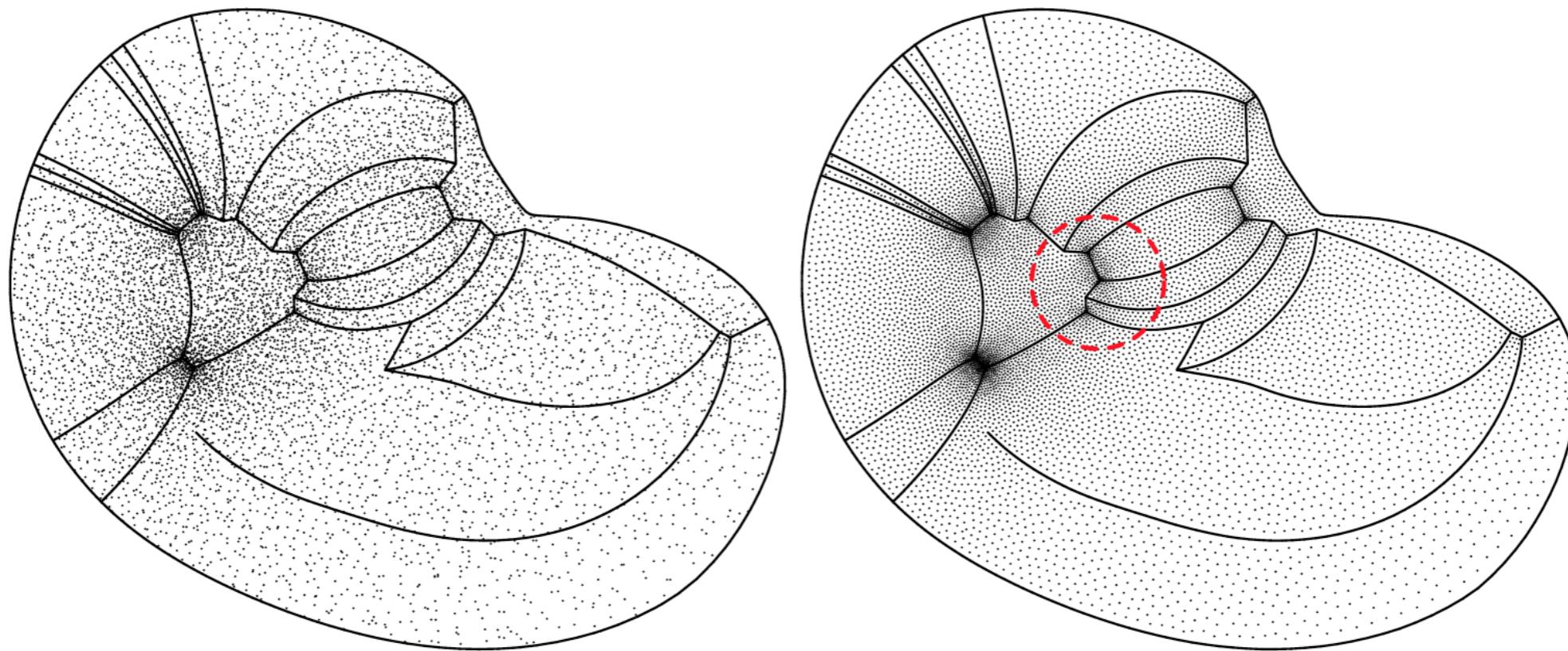
Variational remeshing



Adaptive remeshing



Feature preservation



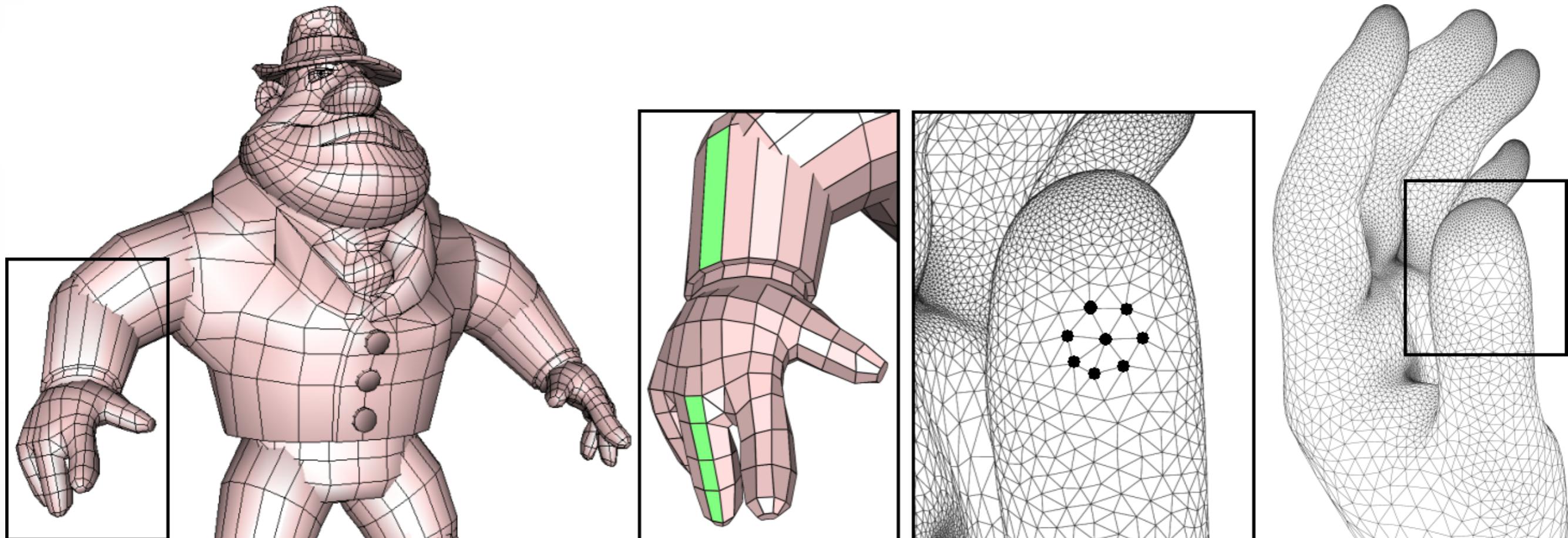
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 - Isotropic remeshing
 - **Anisotropic remeshing**

Anisotropic remeshing

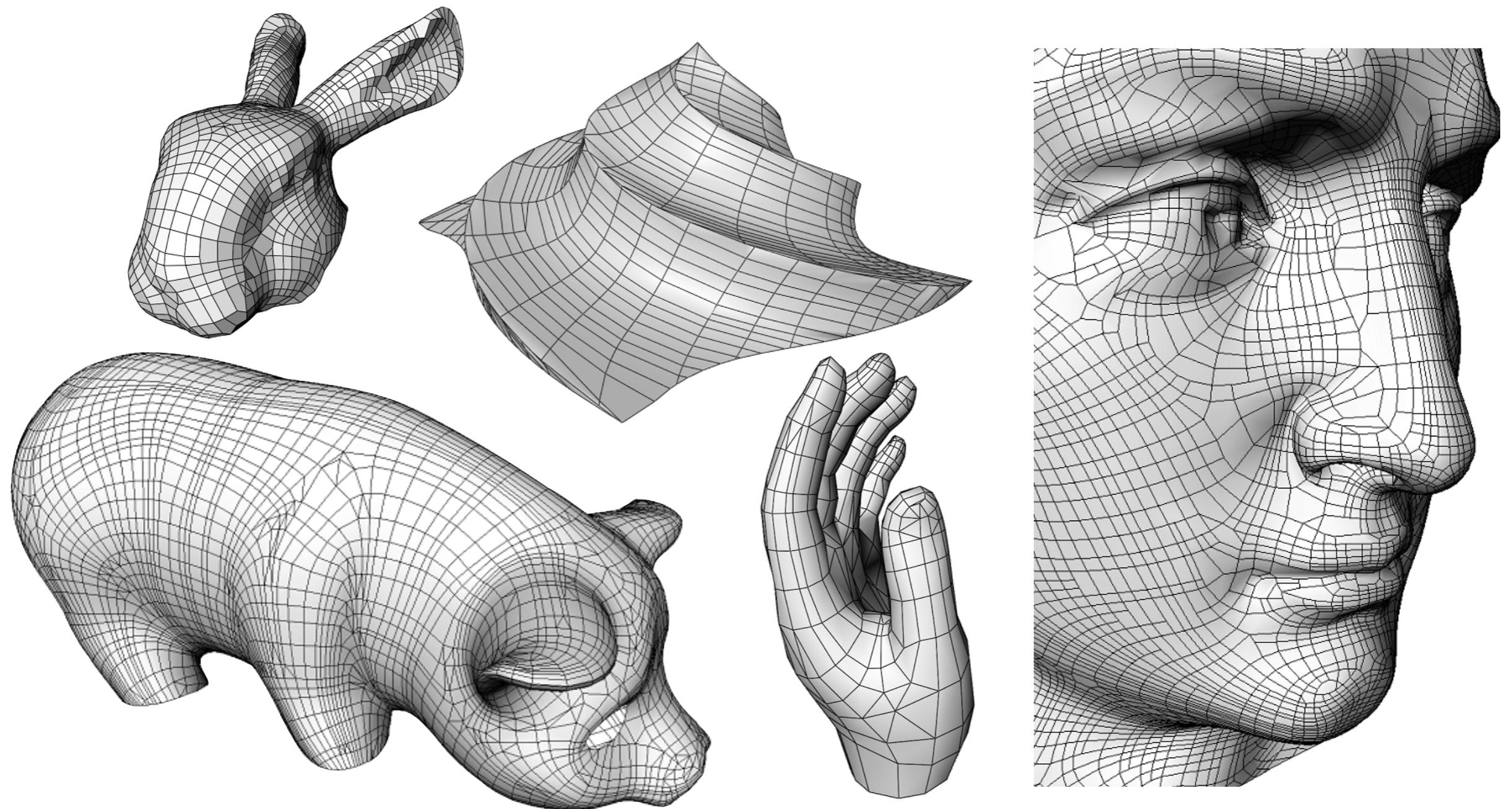
Artist-designed models

- Conform to the anisotropy of a surface



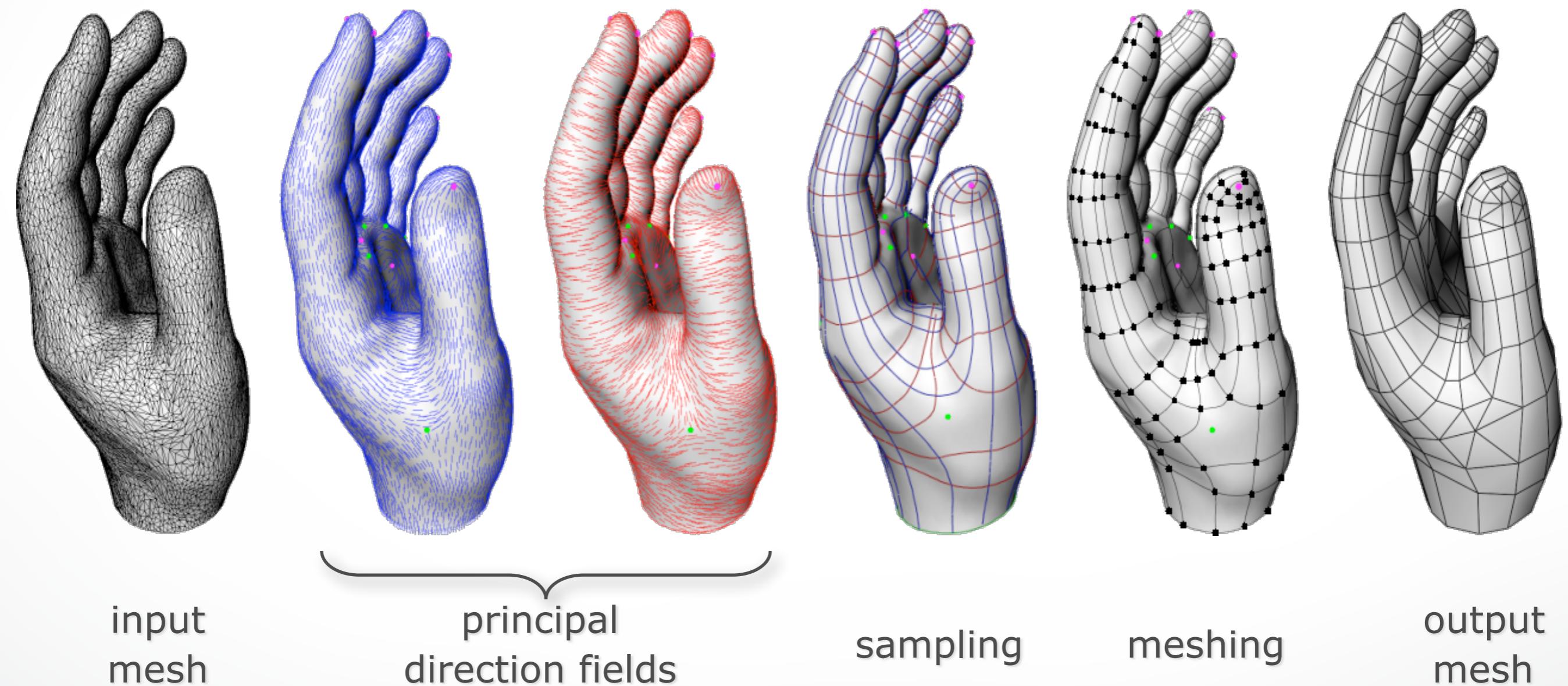
Anisotropic remeshing

[Alliez et al. 2003] *Anisotropic Polygonal Remeshing.*



Anisotropic remeshing

[Alliez et al. 2003] *Anisotropic Polygonal Remeshing.*



input
mesh

principal
direction fields

sampling

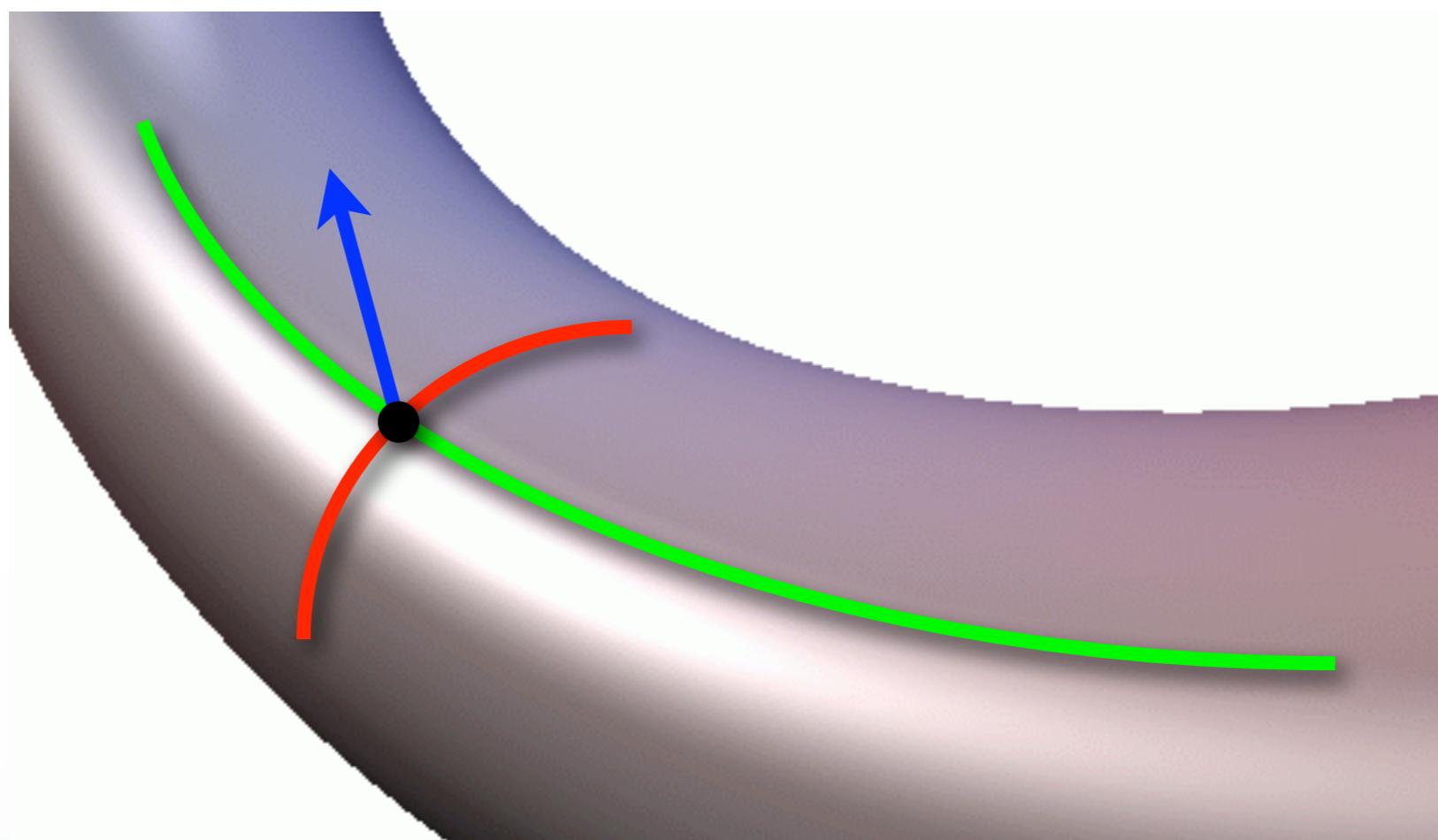
meshing

output
mesh

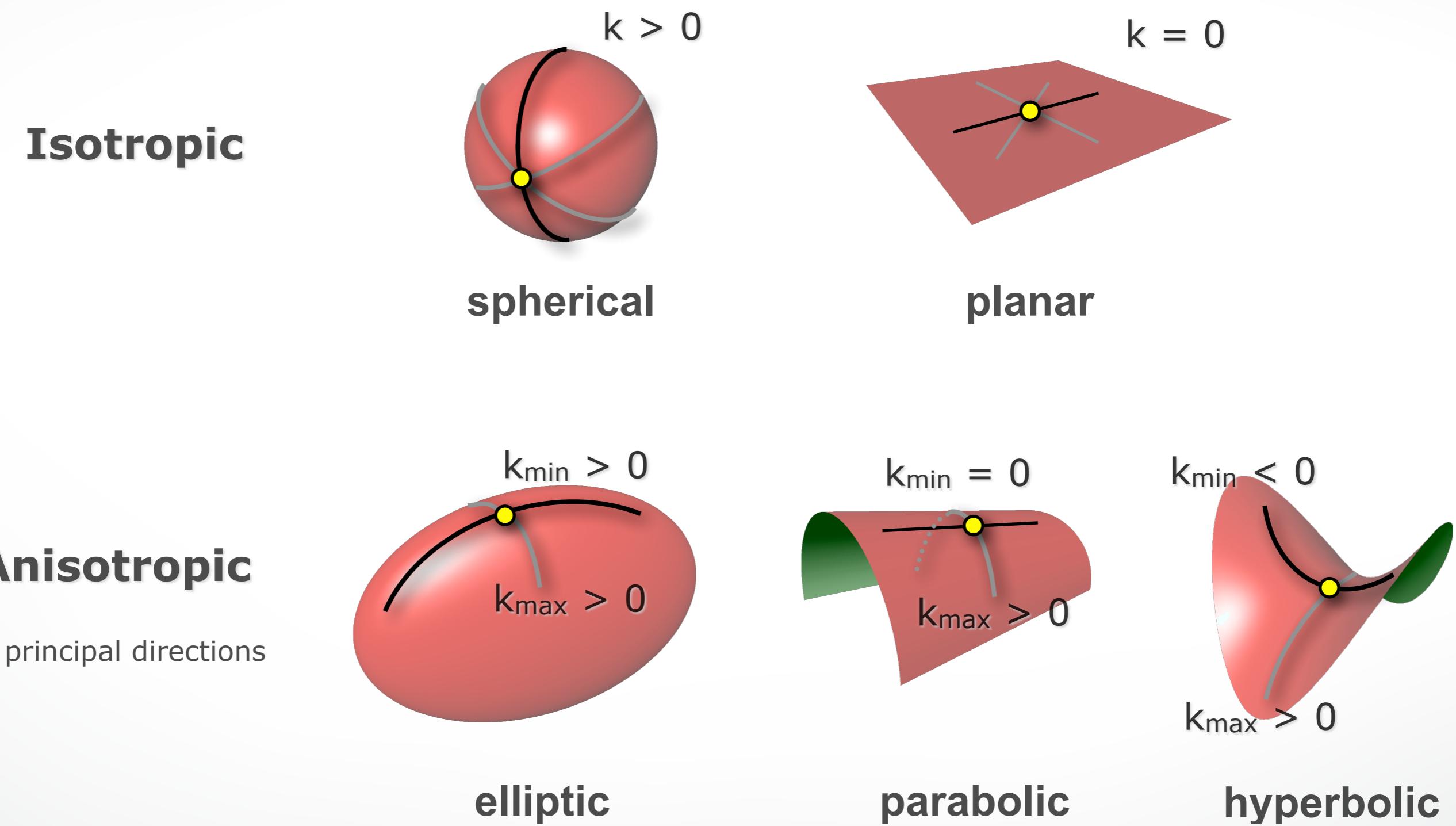
Anisotropy

Differential geometry

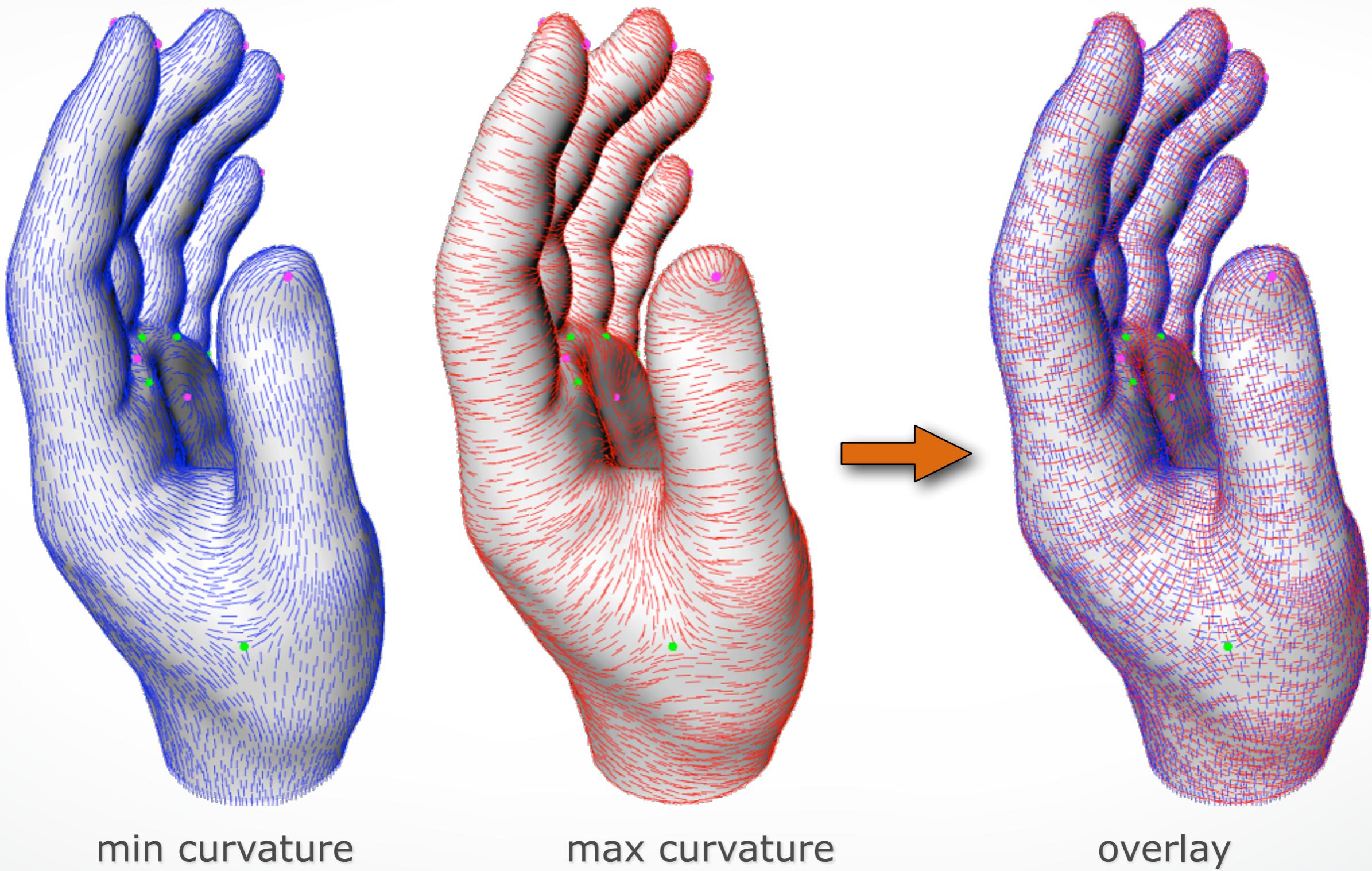
- A local *orthogonal* frame: min/max curvature directions and normal



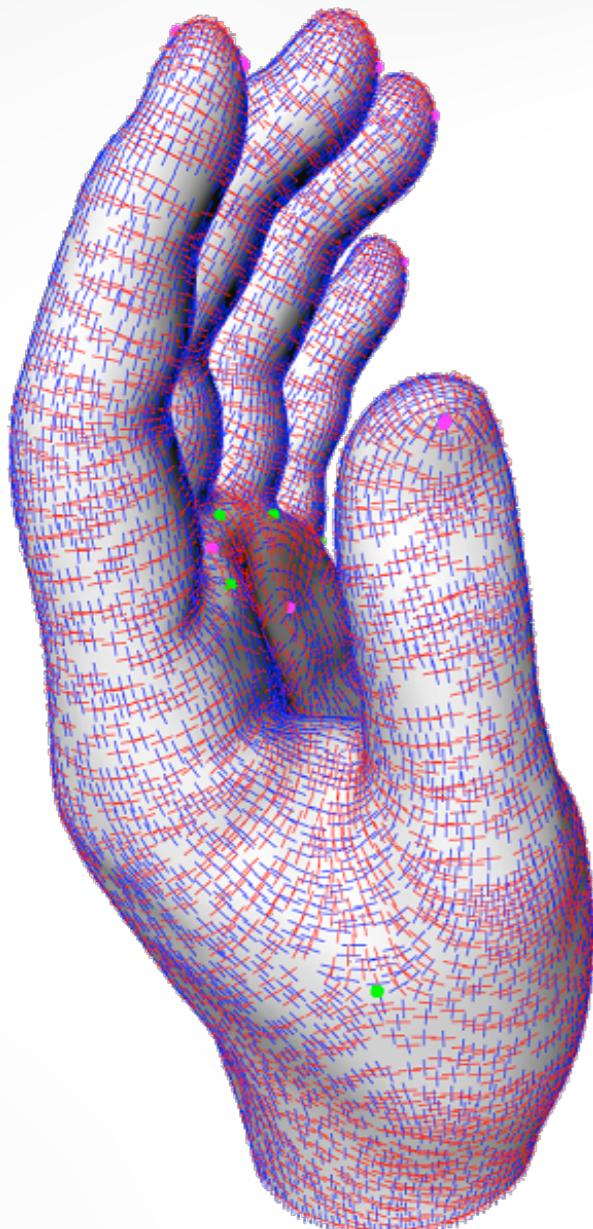
3D curvature tensor



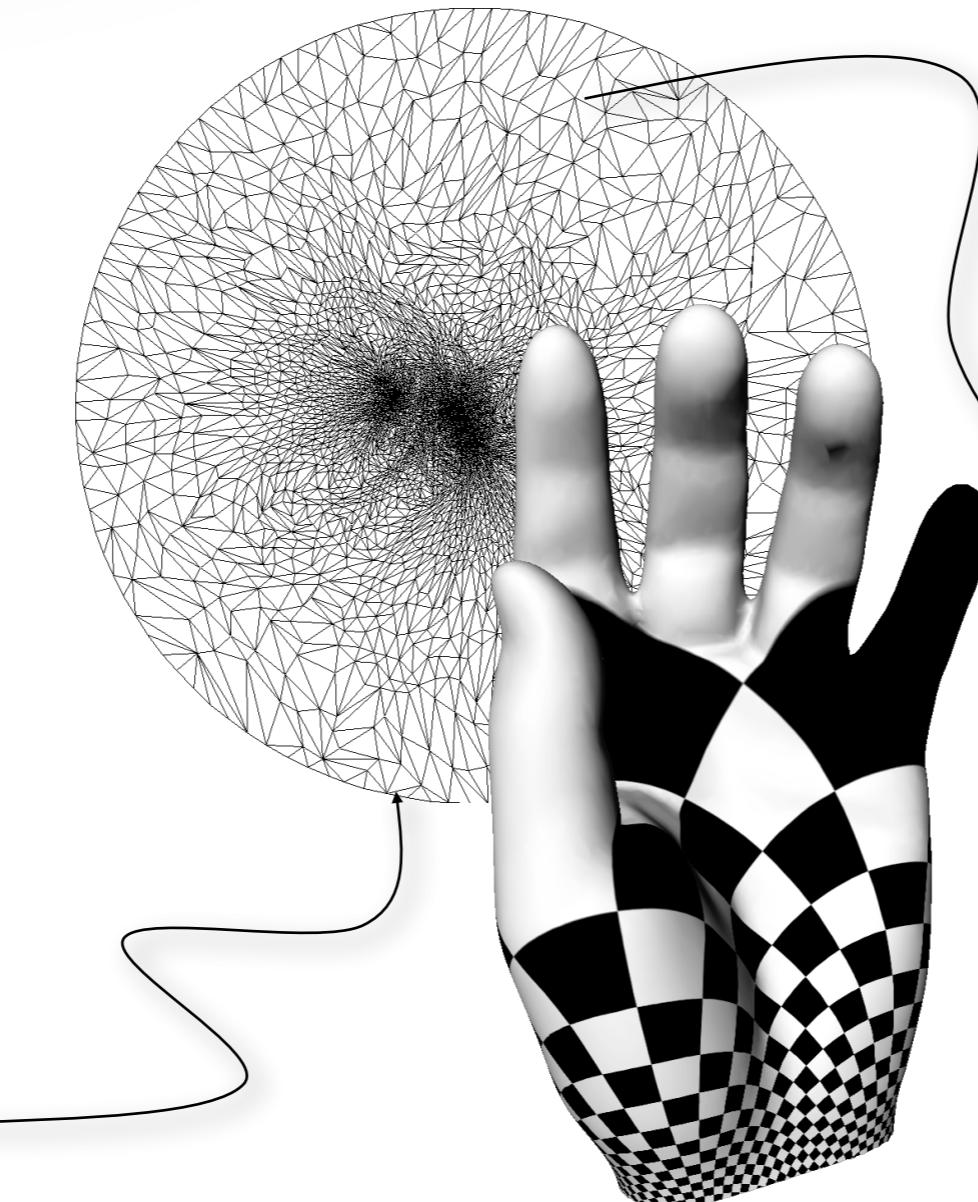
Principal direction fields



Flattening to 2D

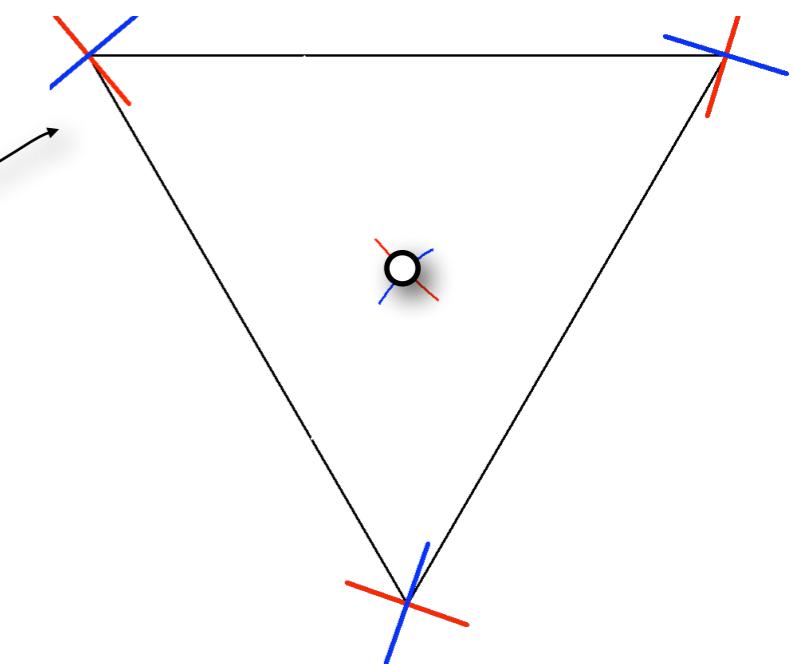


one 3D tensor
per vertex



discrete conformal
parameterization

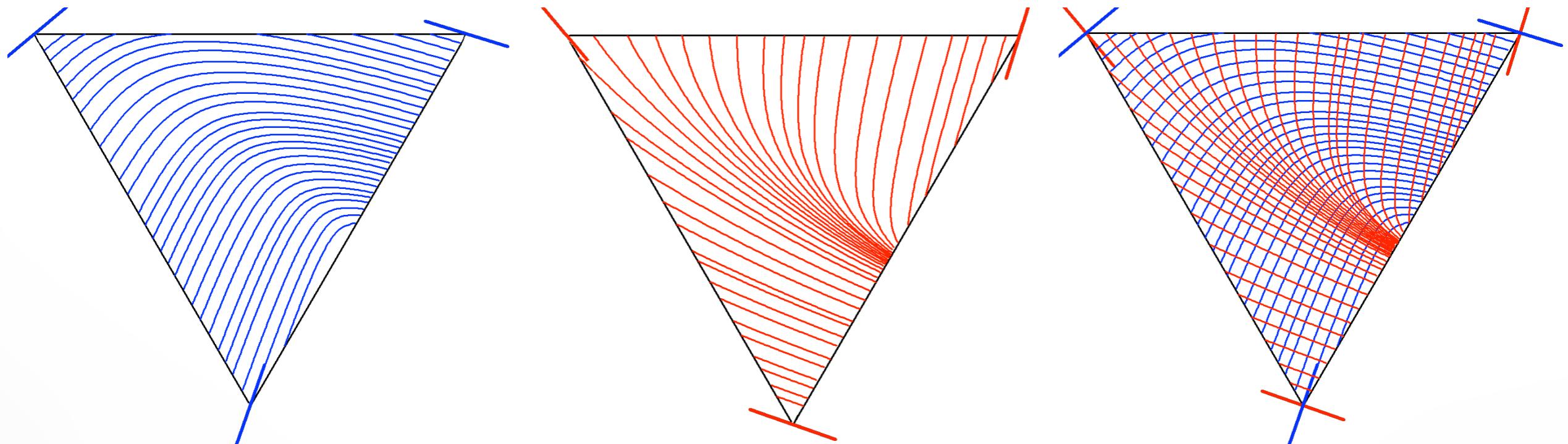
piecewise linear
interpolation of
2D tensors



2D tensor **field**
using barycentric
coordinates

2D direction fields

- Regular case



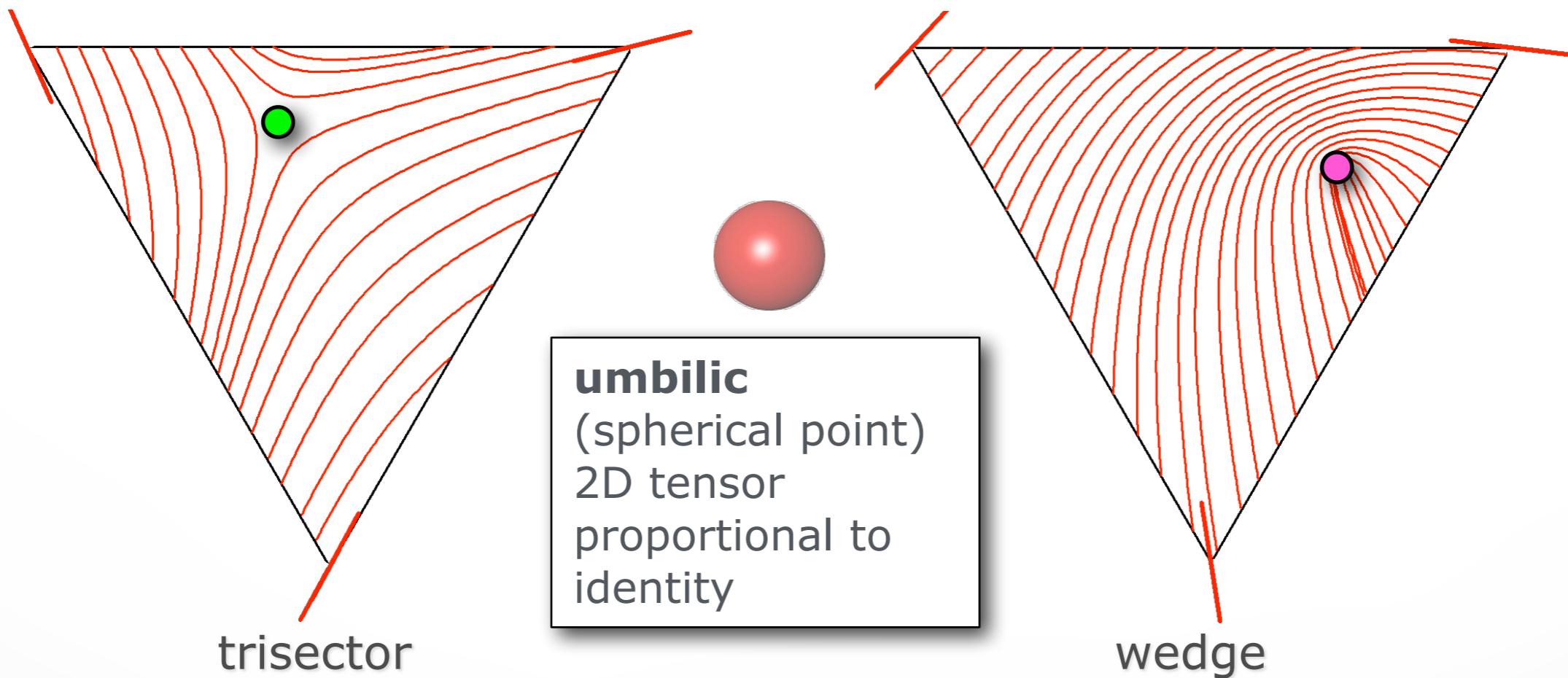
minor foliation

major foliation

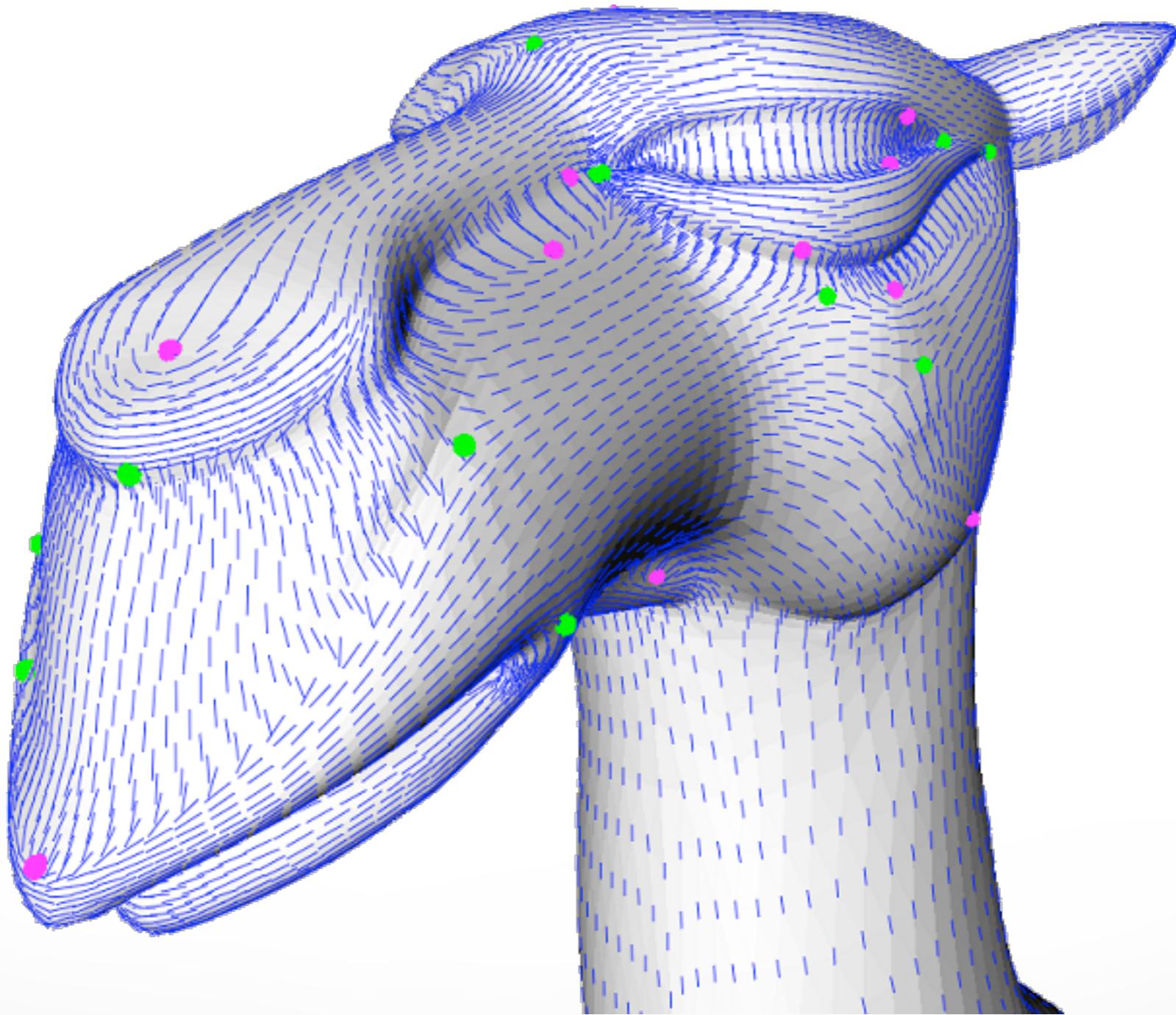
principal foliations

2D direction fields

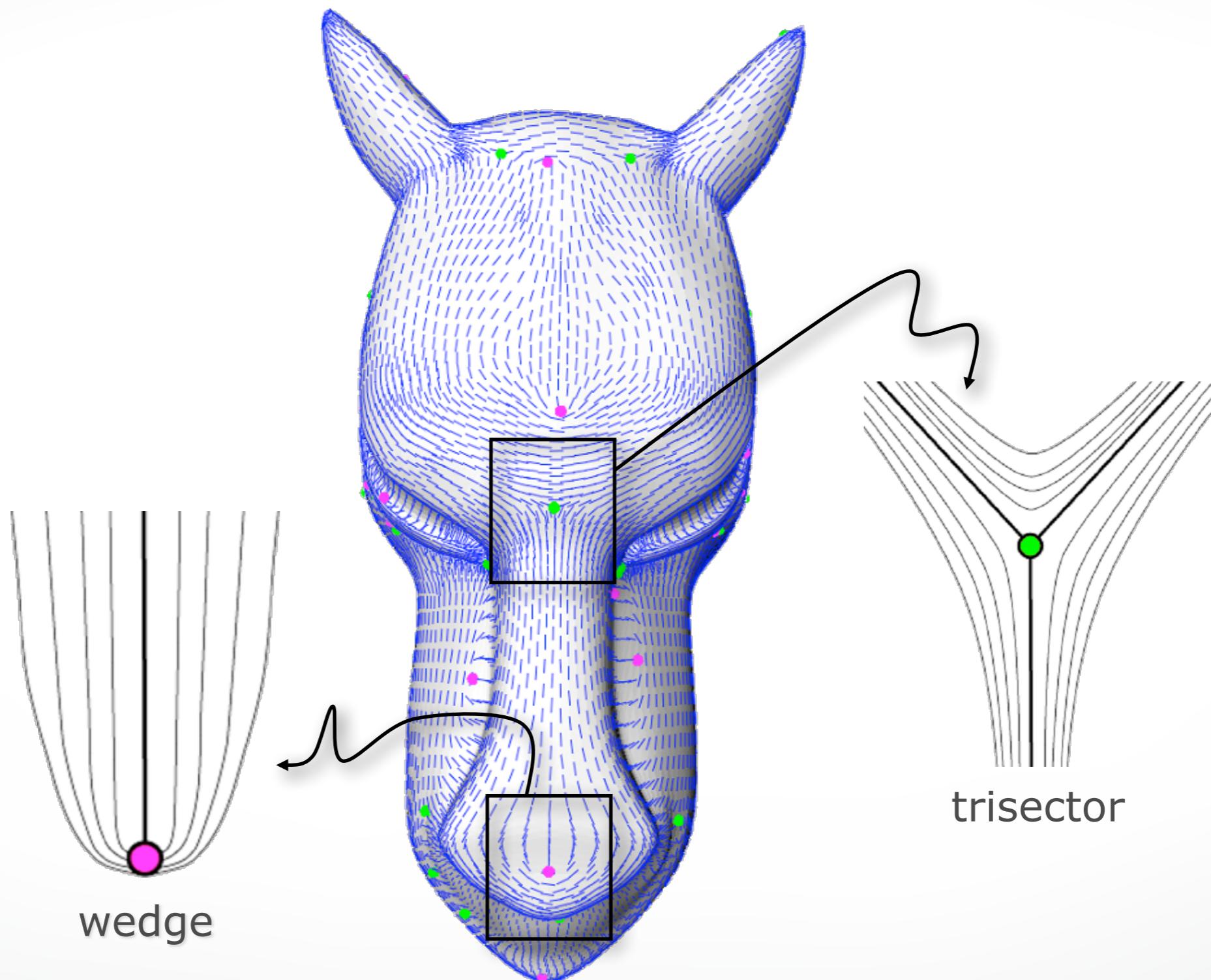
- Singularities



Umbilics



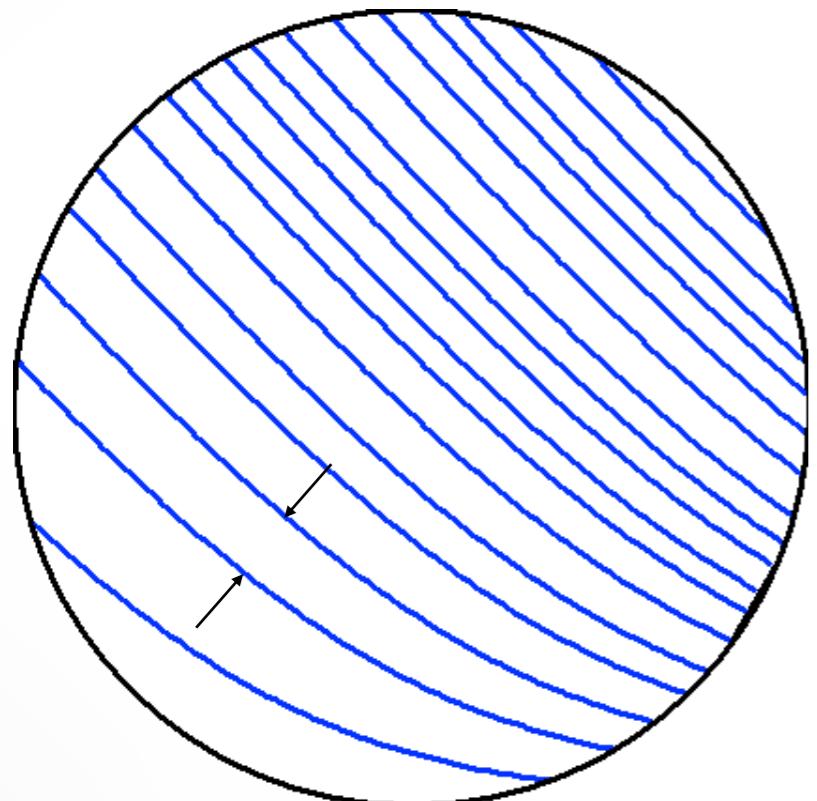
Umbilics



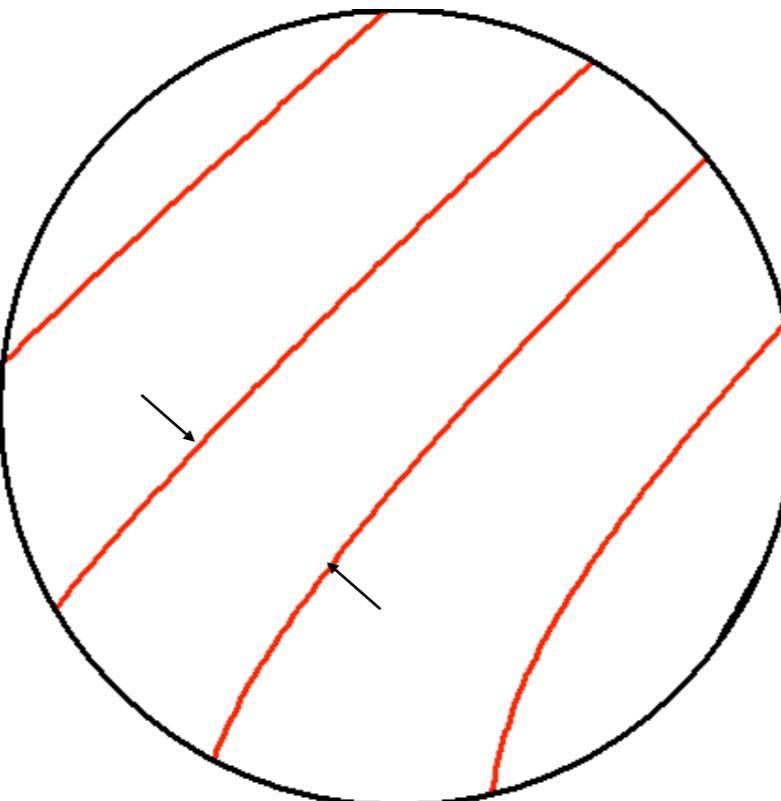
trisector

wedge

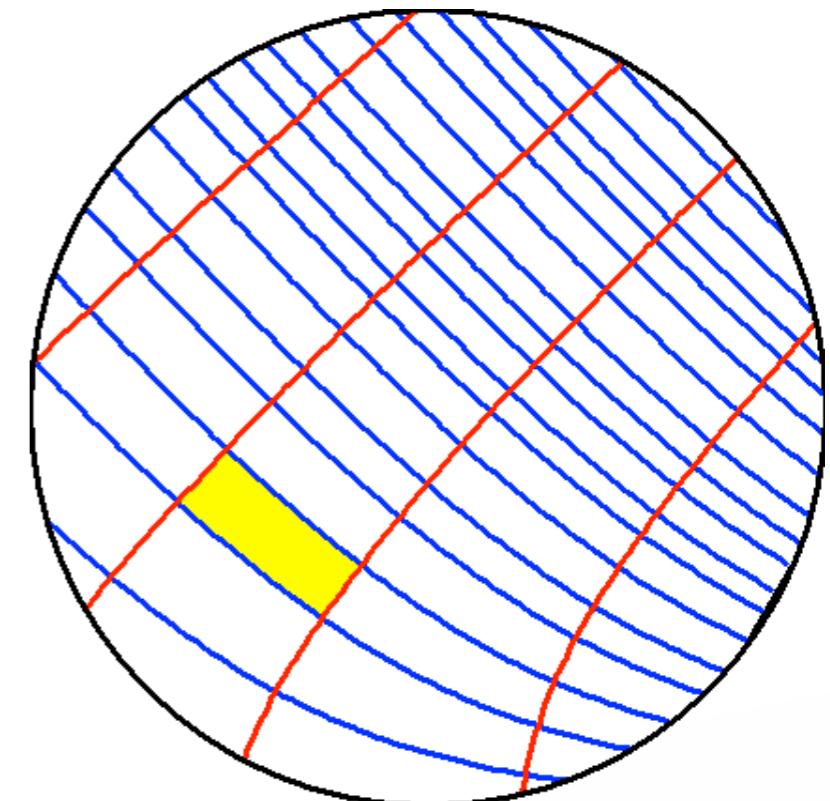
Lines of curvature



minor net

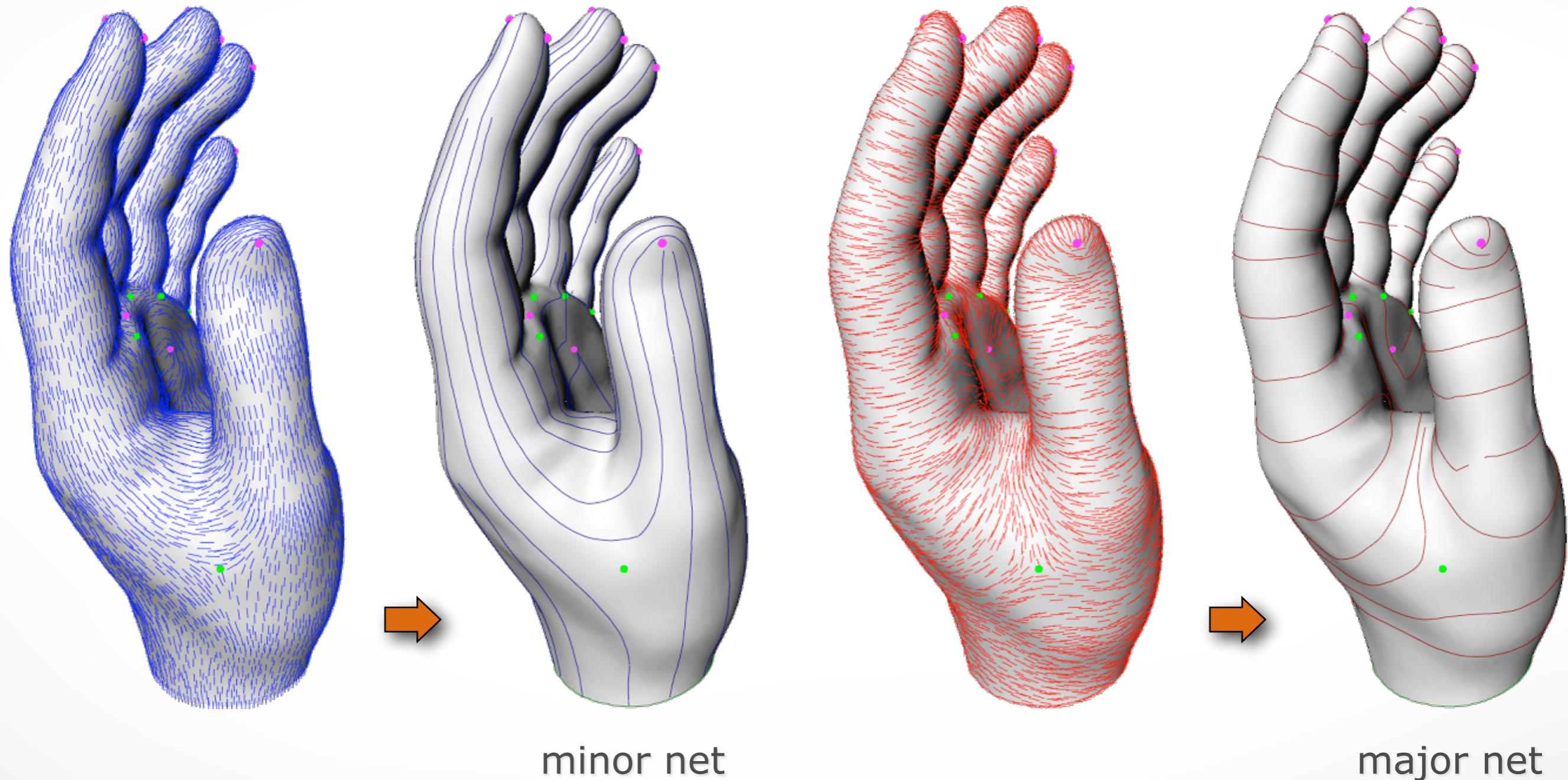


major net



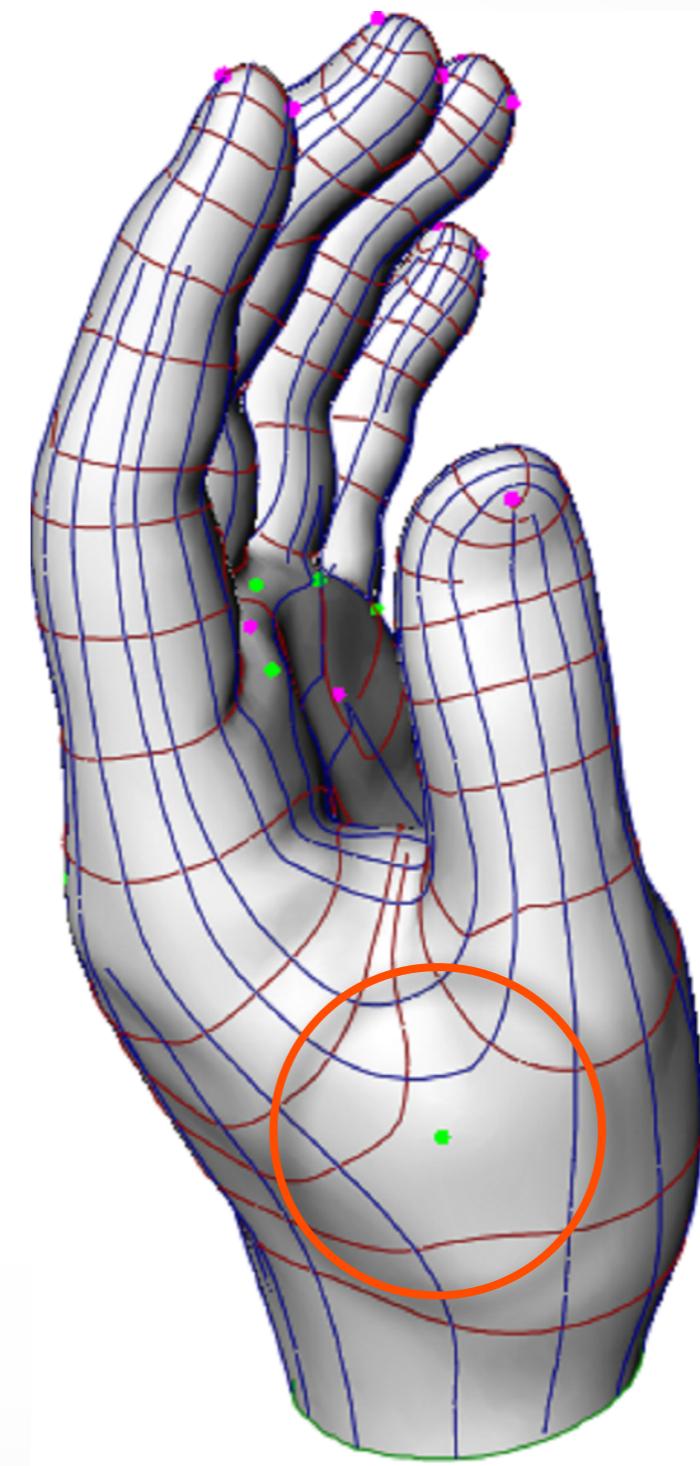
overlay

Lines of curvature

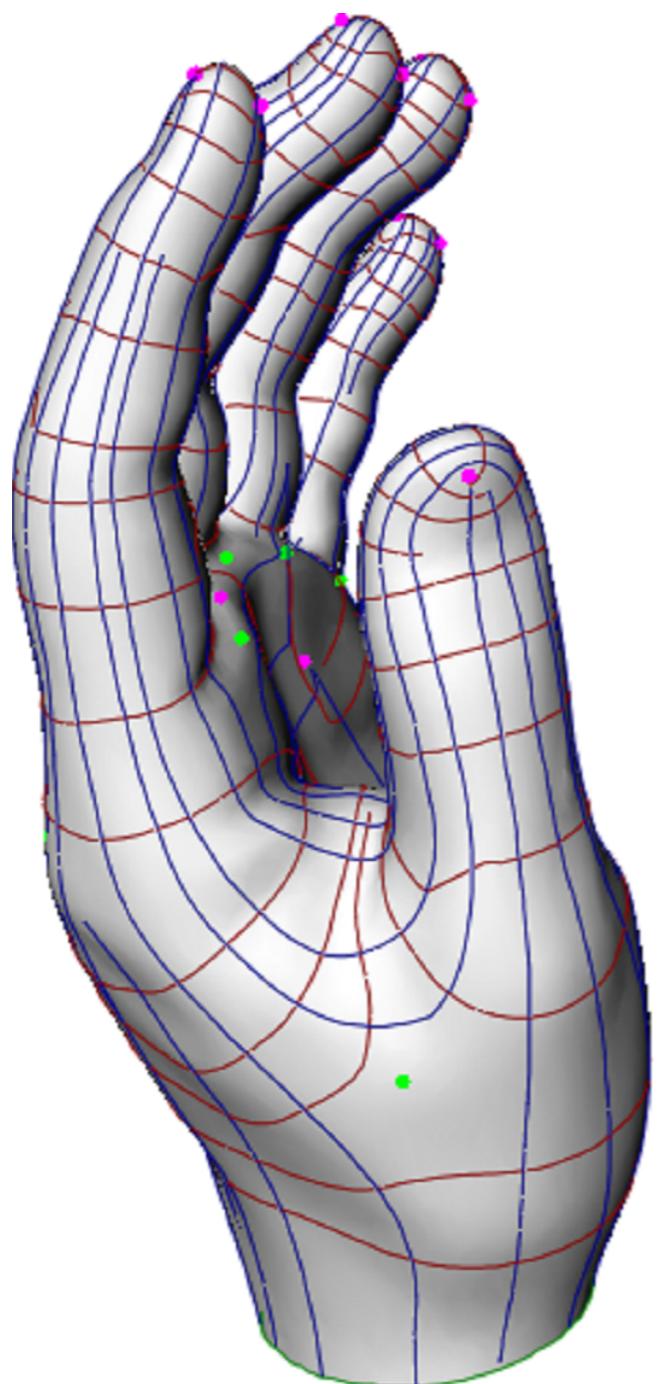


Overlay

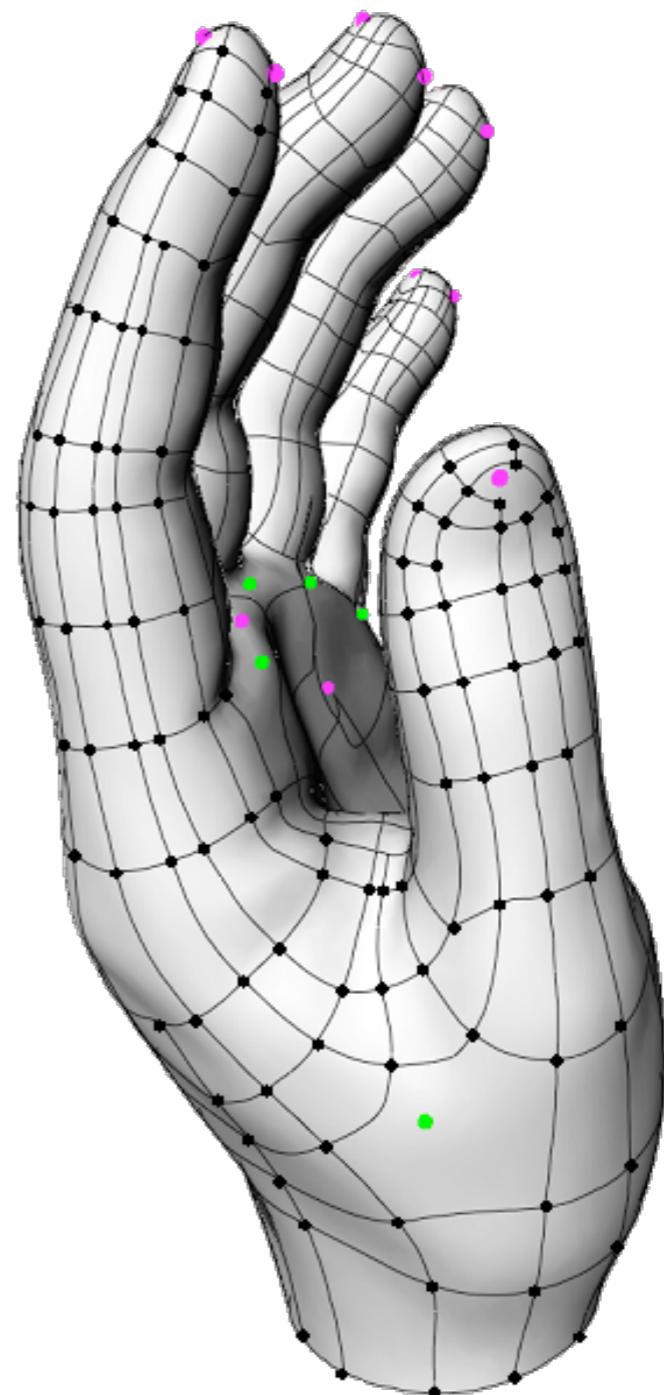
- Overlay curvature lines in anisotropic regions
- Add umbilical points in isotropic regions



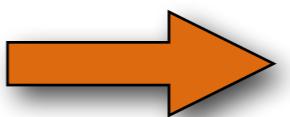
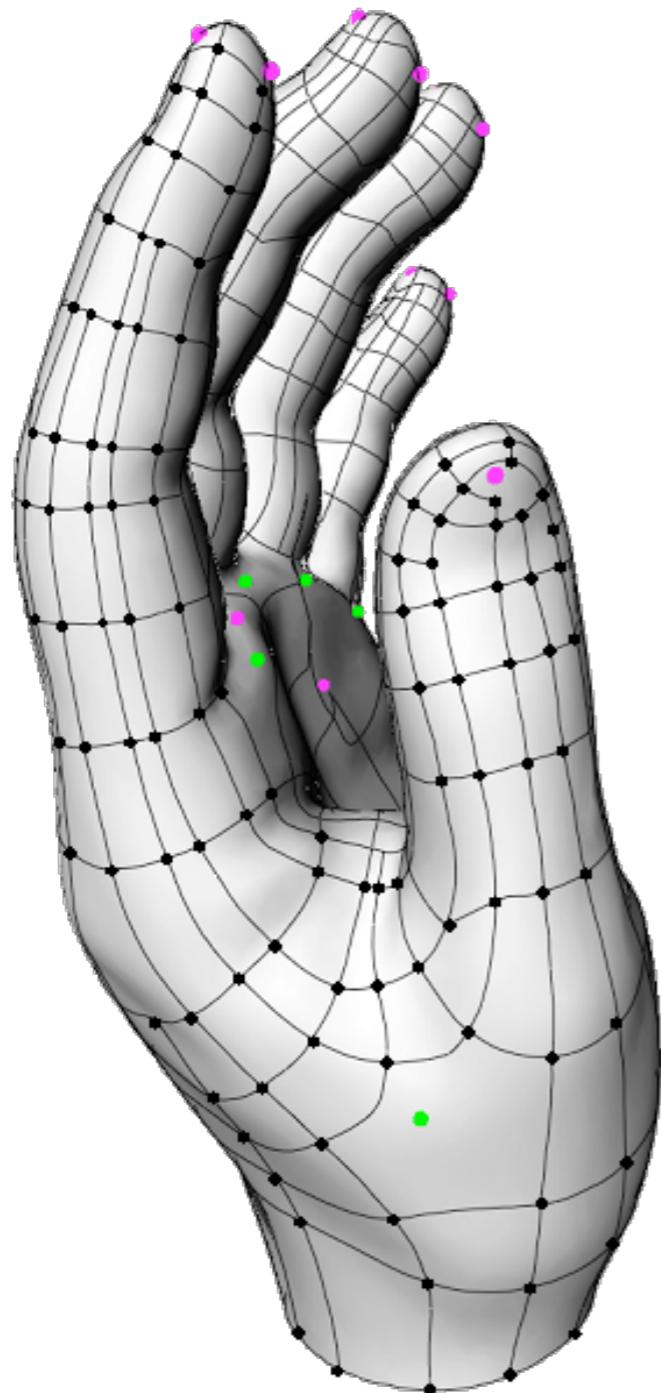
Vertices



intersect lines of
curvatures



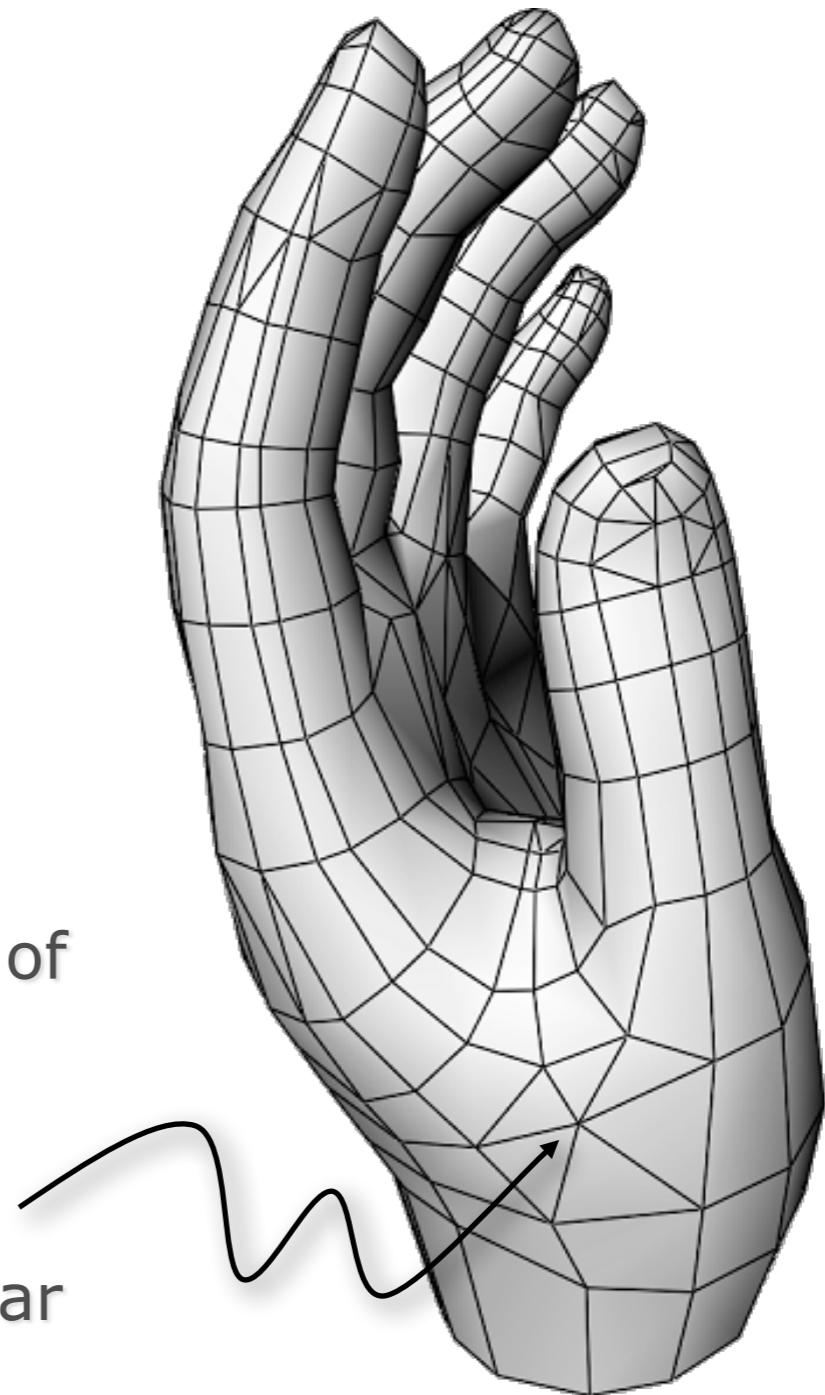
Edges



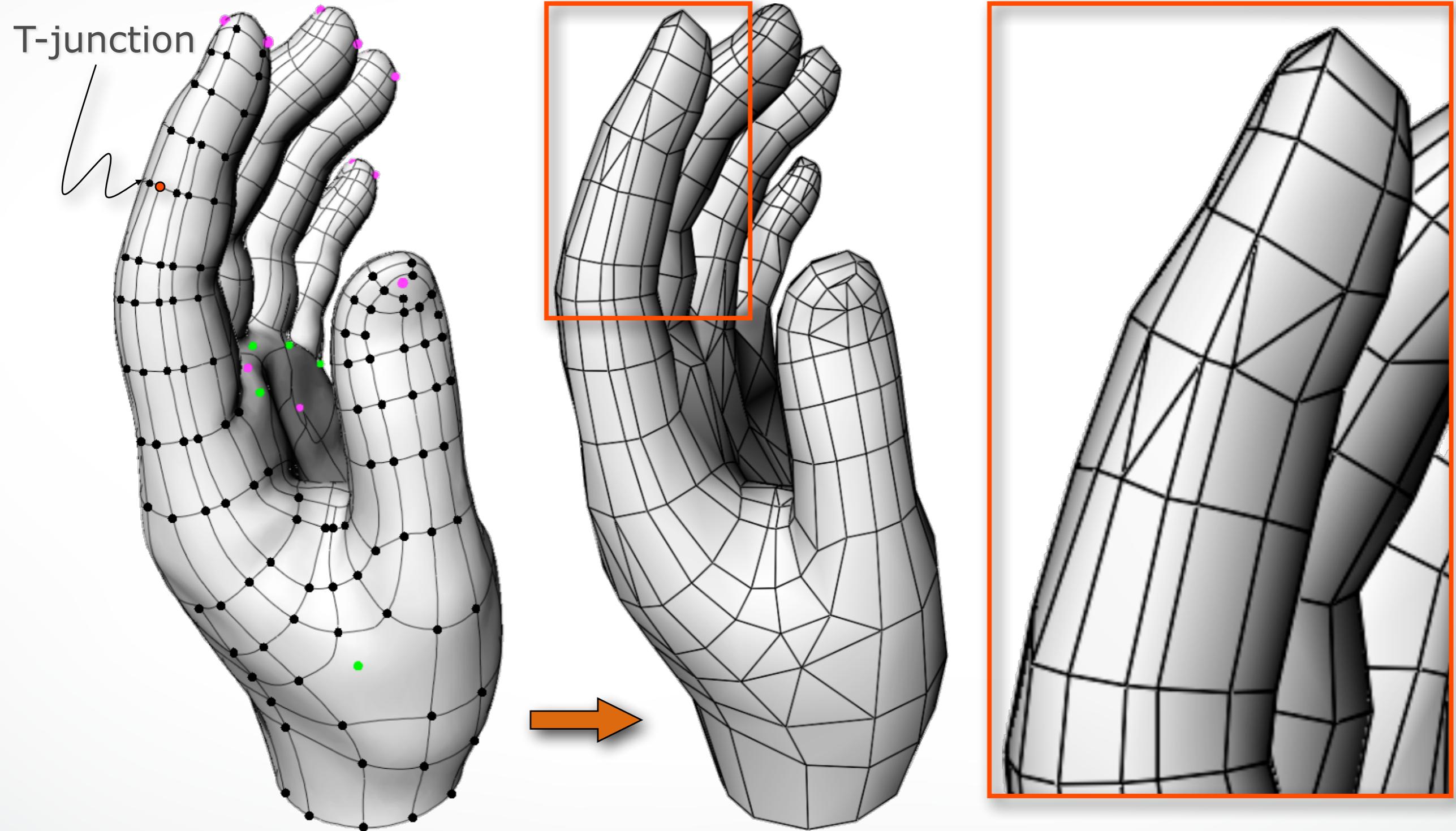
straighten lines of
curvatures

+

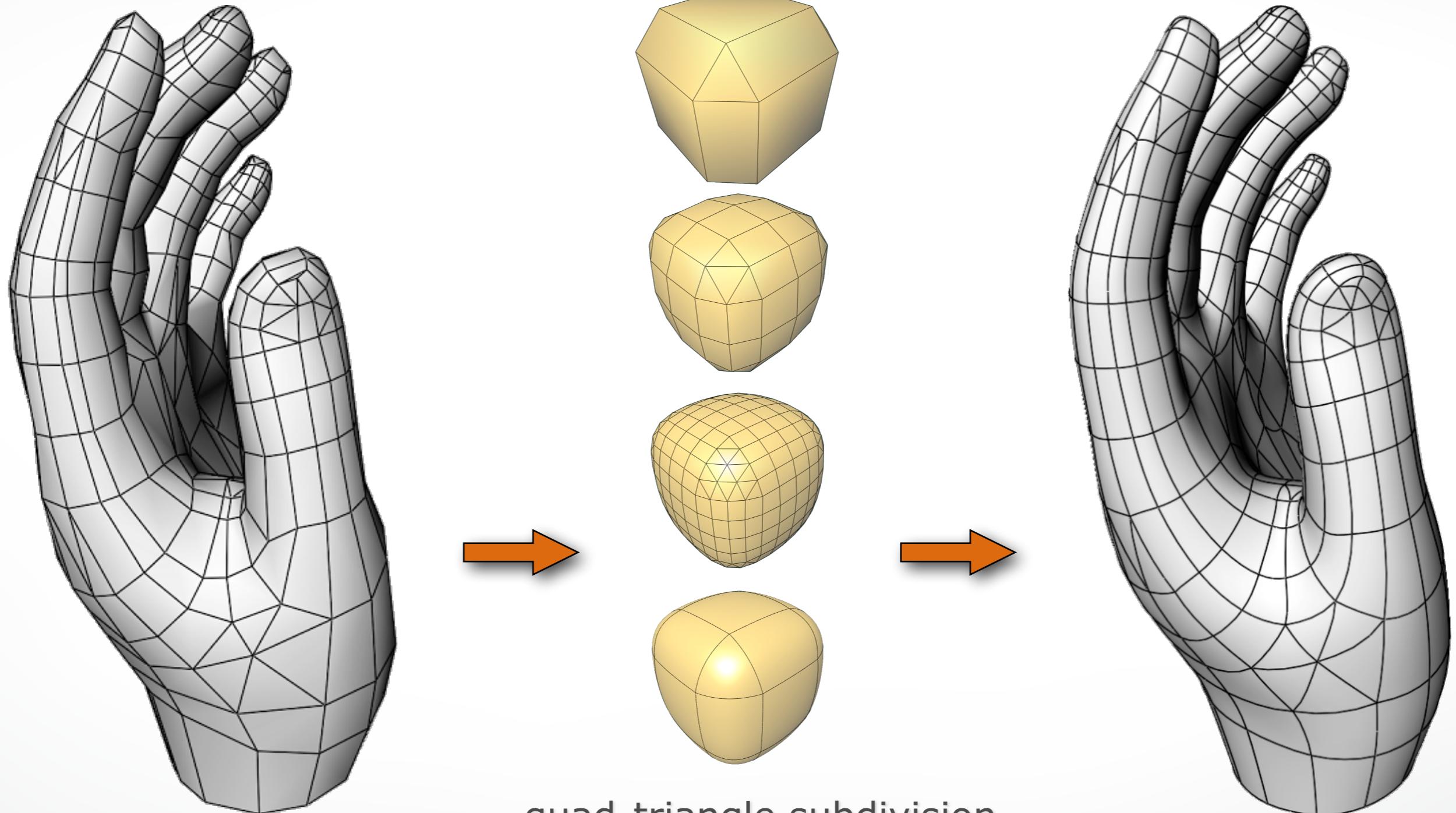
Delaunay
triangulation near
umbilics



Resolve T-junctions

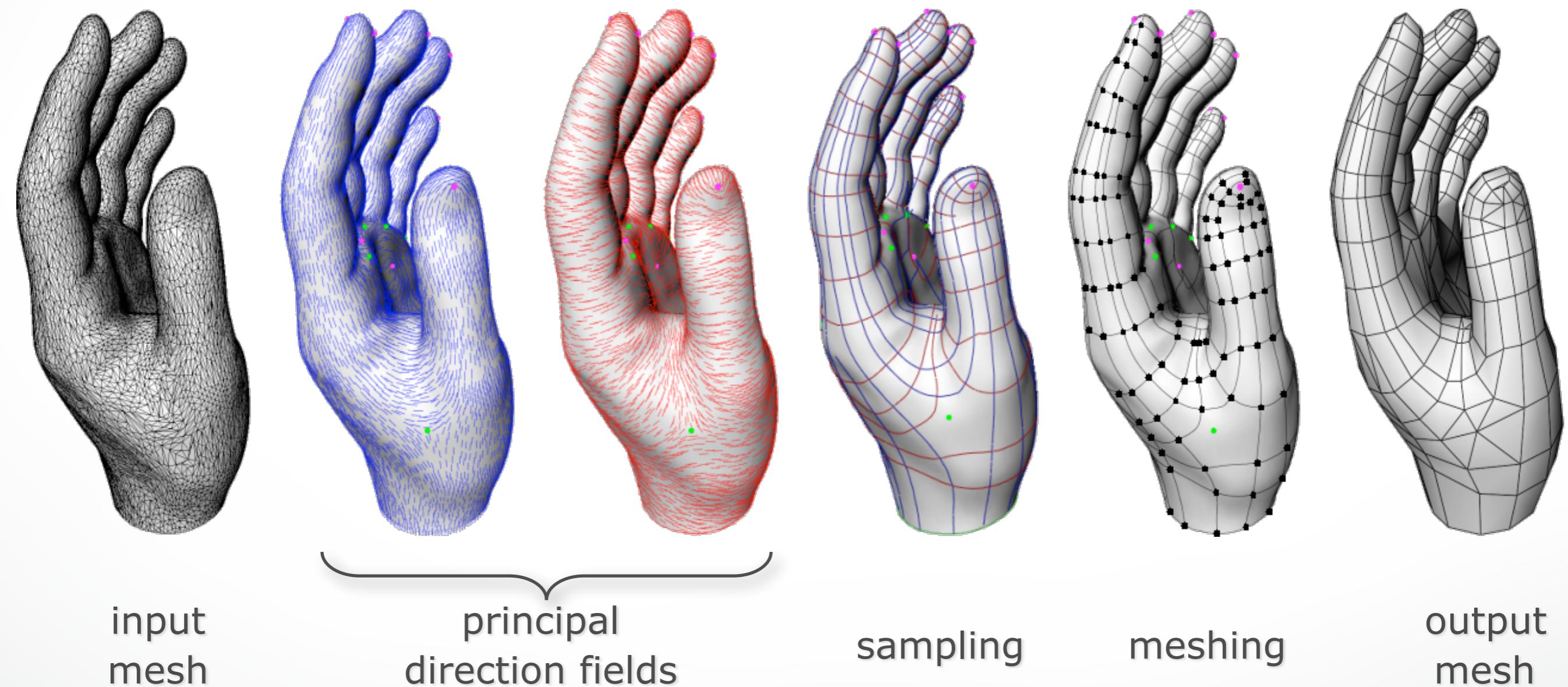


Smoothing



Anisotropic remeshing

[Alliez et al. 2003] *Anisotropic Polygonal Remeshing.*



input
mesh

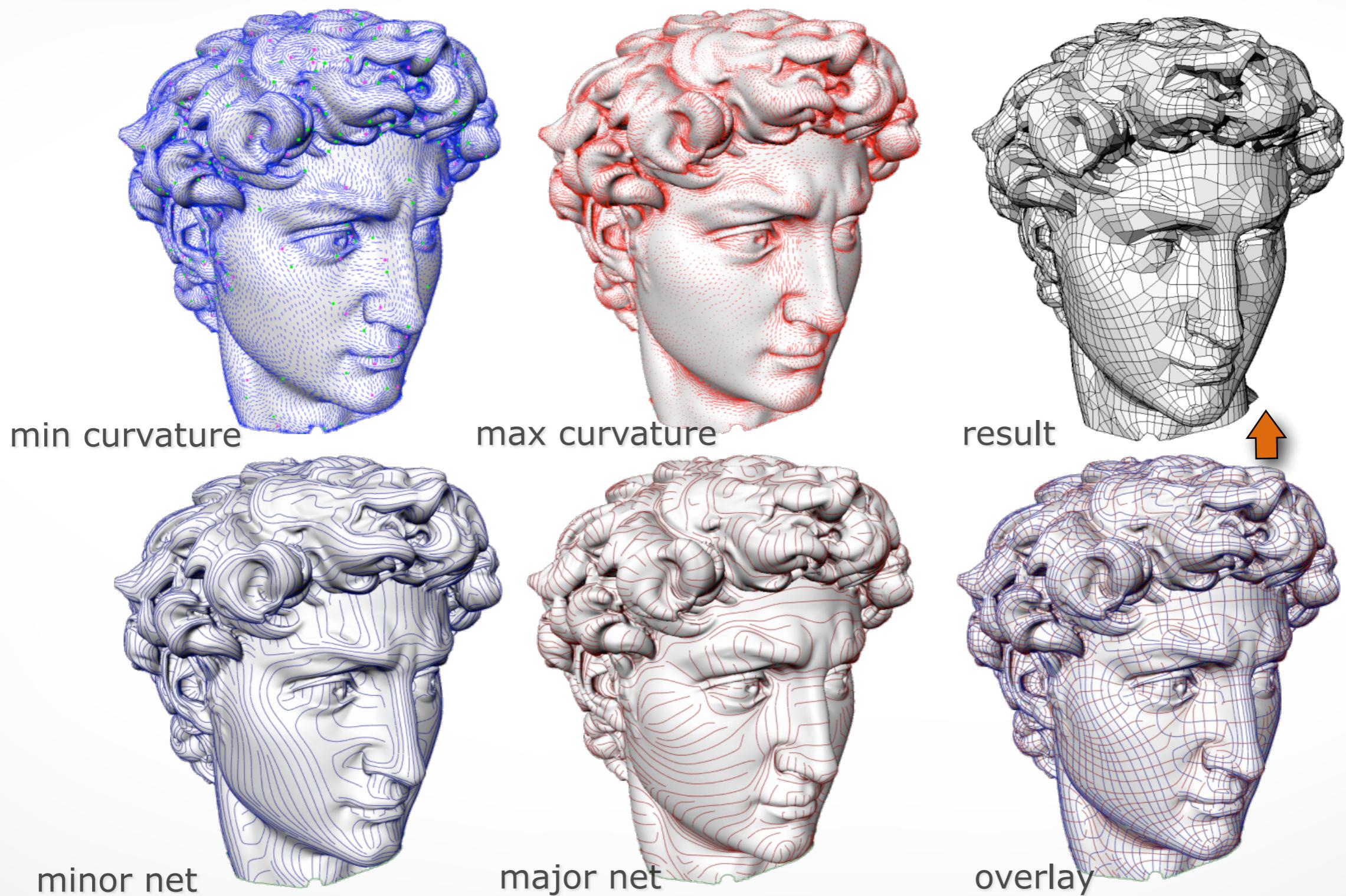
principal
direction fields

sampling

meshing

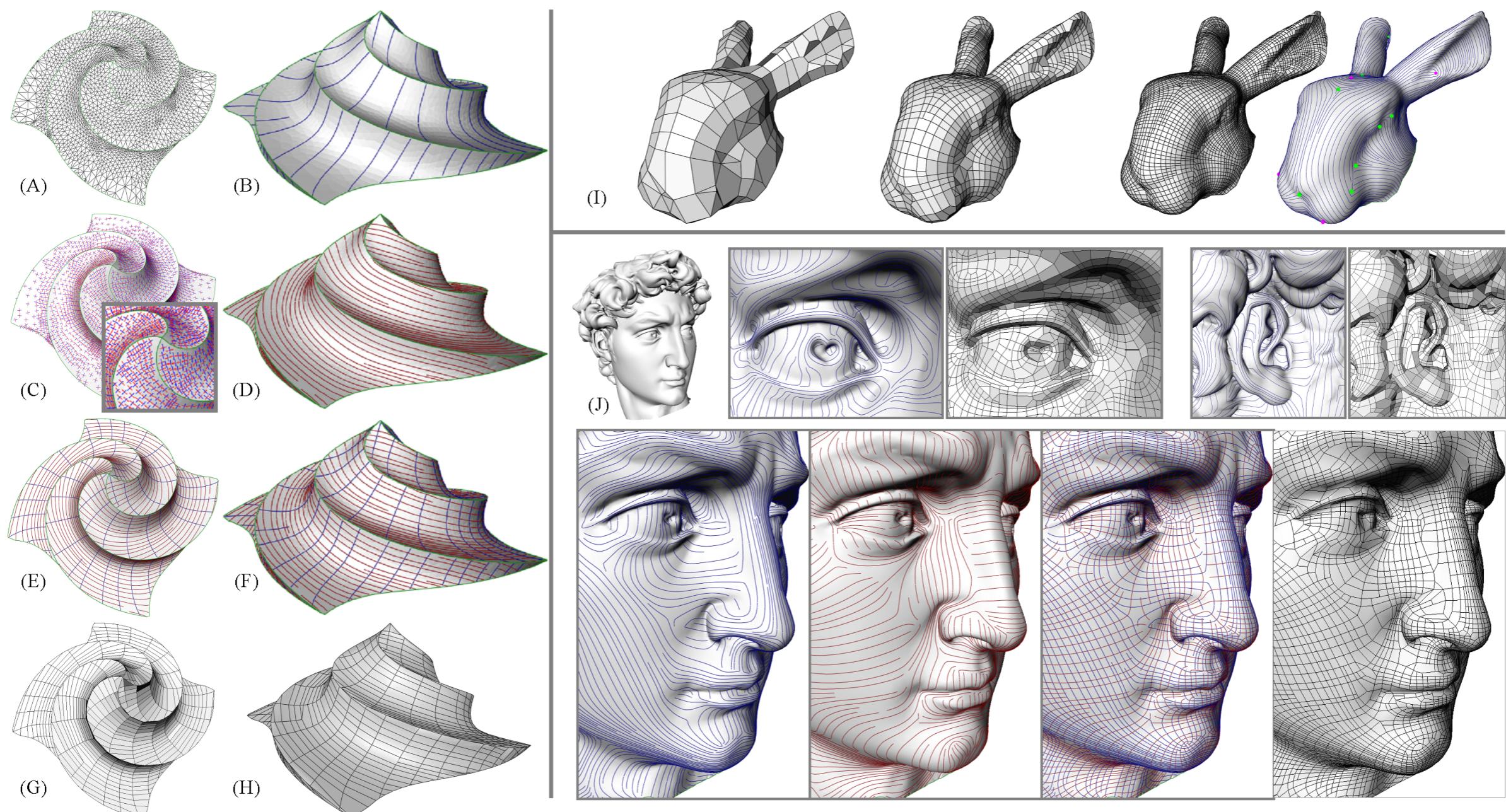
output
mesh

Remeshing results



Remeshing results

[Alliez et al. 2003] *Anisotropic Polygonal Remeshing.*



Tools

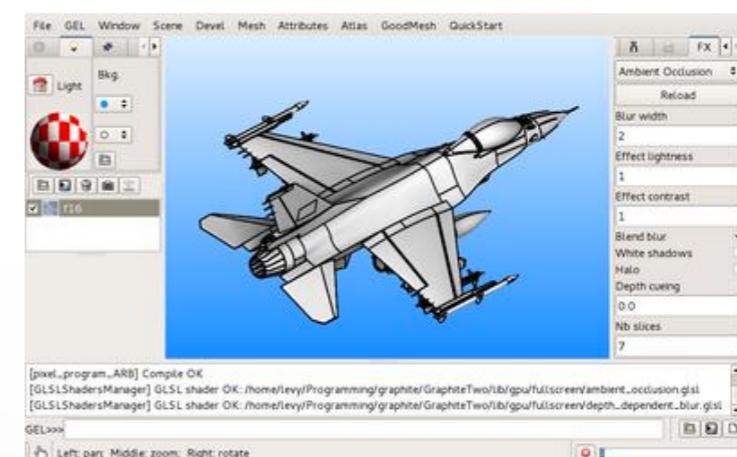
MeshLab

- meshlab.sourceforge.net
- open source
- available for Windows, MacOSX, and Linux



Graphite

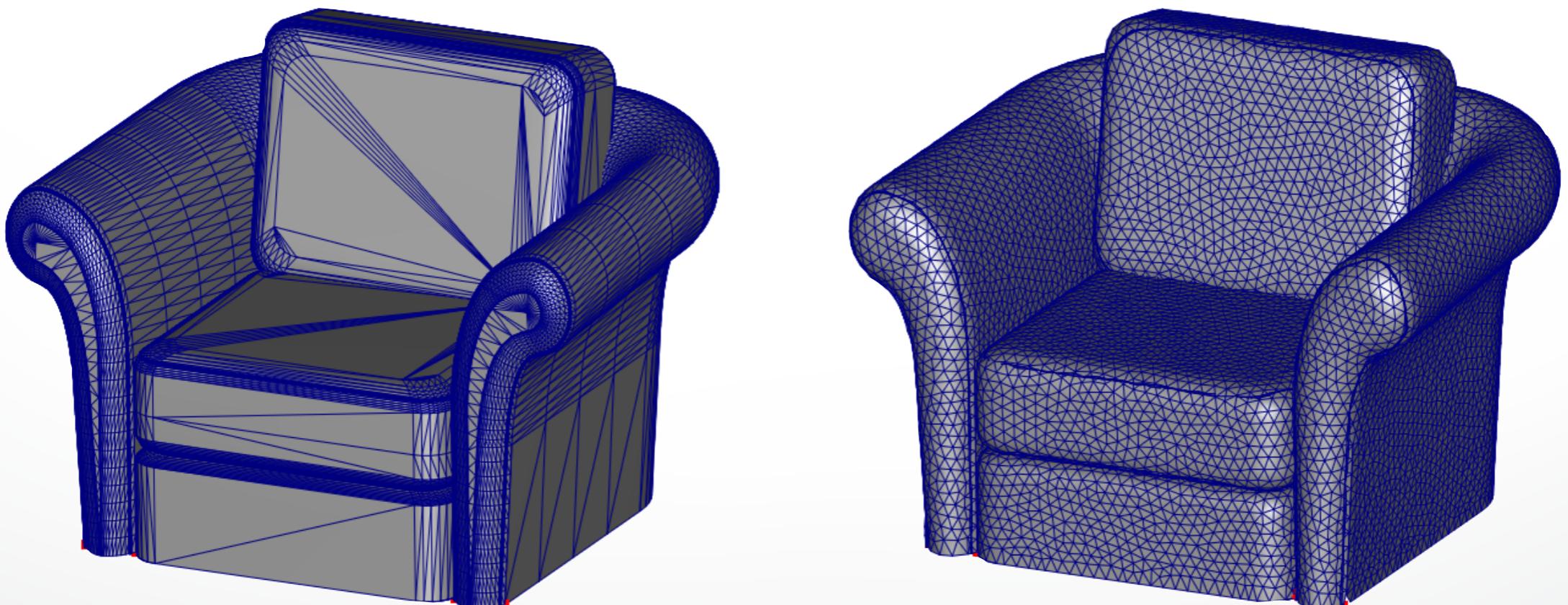
- <http://alice.loria.fr/index.php/software/3-platform/22-graphite.html>
- available for Windows
- MacOSX or Linux?



Remeshing via Graphite

“Mesh” → “remesh” → “pliant” →

- [Optional] flag border as feature
- [Optional] flag sharp edges as feature (dihedral angle)
- [Optional] estimate edge size (bounding box divisions)
- remesh (target edge length)



Literature

- Textbook: Chapter 6
- Alliez et al, “*Interactive geometry remeshing*”, SIGGRAPH 2002
- Alliez et al, “*Isotropic surface remeshing*”, SMI 2003
- Alliez et al, “*Anisotropic polygonal remeshing*”, SIGGRAPH 2003
- Vorsatz et al, “*Dynamic remeshing and applications*”, Solid Modeling 2003
- Botsch & Kobbelt, “*A remeshing approach to multiresolution modeling*”, Symp. on Geometry Processing 2004
- Marinov et al, “*Direct anisotropic quad-dominant remeshing*”, Pacific Graphics 2004
- Alliez et al, “*Recent advances in remeshing of surfaces*”, AIM@Shape state of the art report, 2006

<http://cs621.hao-li.com>

Thanks!

