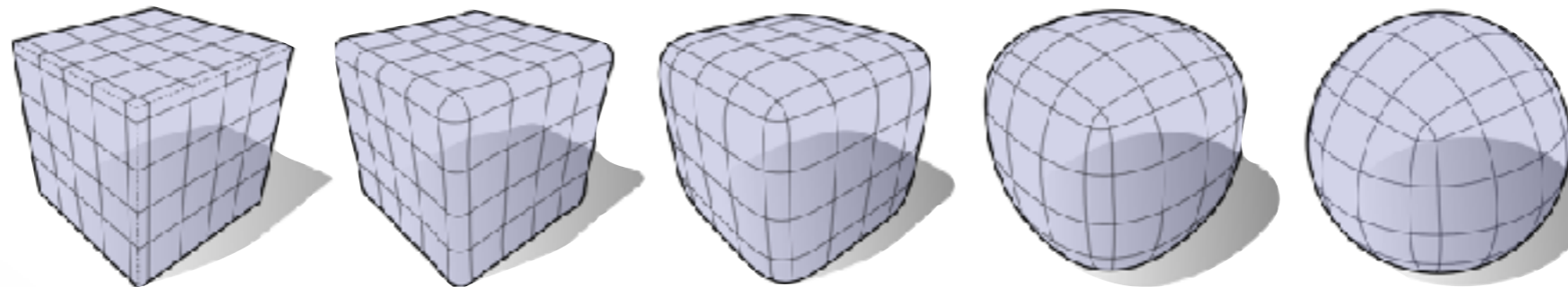


# 4.1 Classic Differential Geometry 2



Hao Li

<http://cs621.hao-li.com>

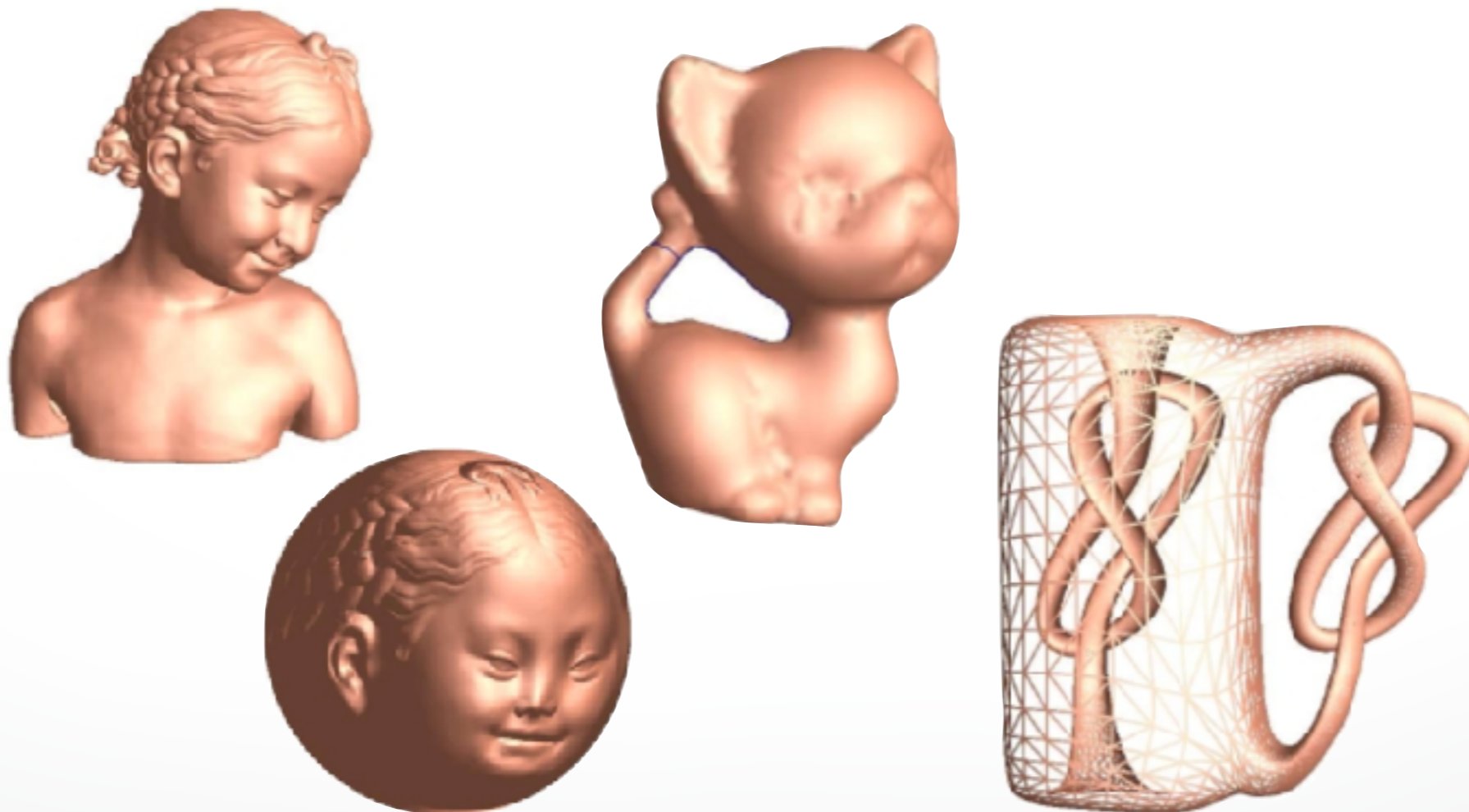
# Outline

- Parametric Curves
- **Parametric Surfaces**

# Surfaces

## What characterizes shape?

- shape does not depend on Euclidean motions
  - metric and curvatures
- smooth continuous notions to discrete notions



# Metric on Surfaces

## Measure Stuff

- angle, length, area
  - requires an inner product
- we have:
  - Euclidean inner product in domain
- we want to turn this into:
  - inner product on surface

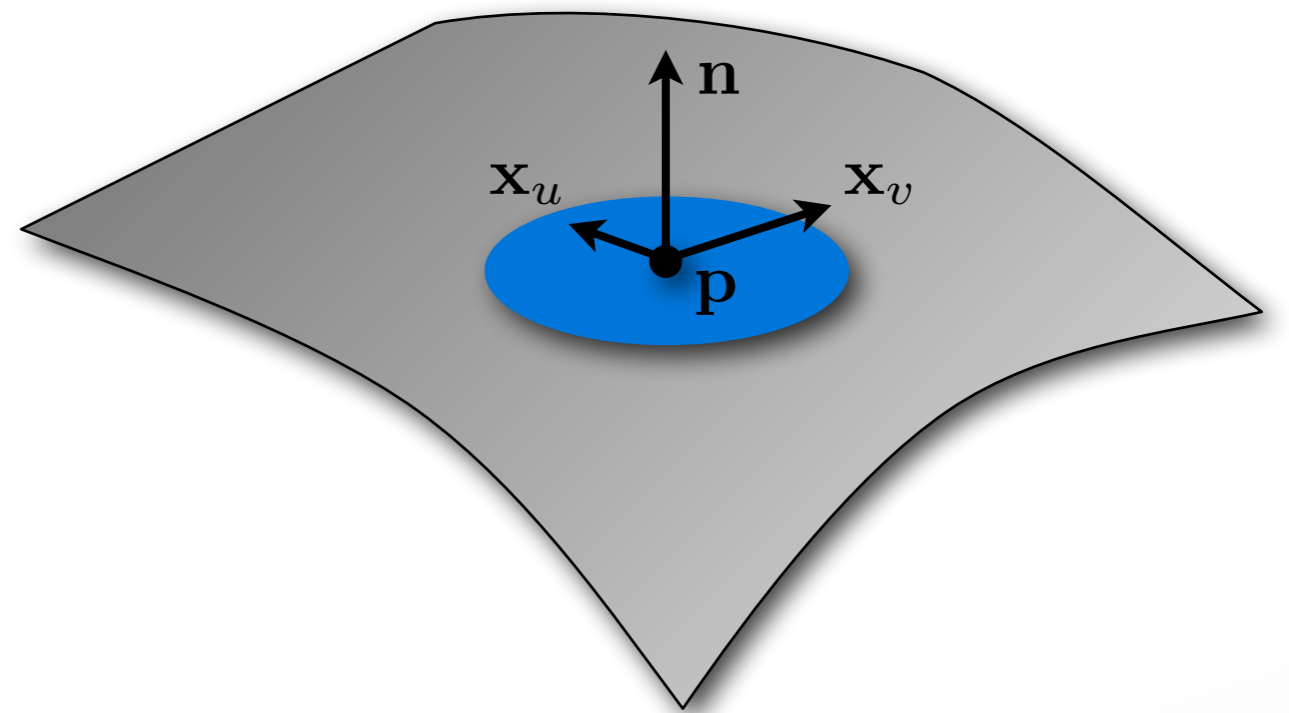
# Parametric Surfaces

## Continuous surface

$$\mathbf{x}(u, v) = \begin{pmatrix} x(u, v) \\ y(u, v) \\ z(u, v) \end{pmatrix}$$

## Normal vector

$$\mathbf{n} = \frac{\mathbf{x}_u \times \mathbf{x}_v}{\|\mathbf{x}_u \times \mathbf{x}_v\|}$$



Assume *regular* parameterization

$$\mathbf{x}_u \times \mathbf{x}_v \neq \mathbf{0} \quad \text{normal exists}$$

# Angles on Surface

**Curve**  $[u(t), v(t)]$  in  $uv$ -plane defines curve on the **surface**  $\mathbf{x}(u, v)$

$$\mathbf{c}(t) = \mathbf{x}(u(t), v(t))$$

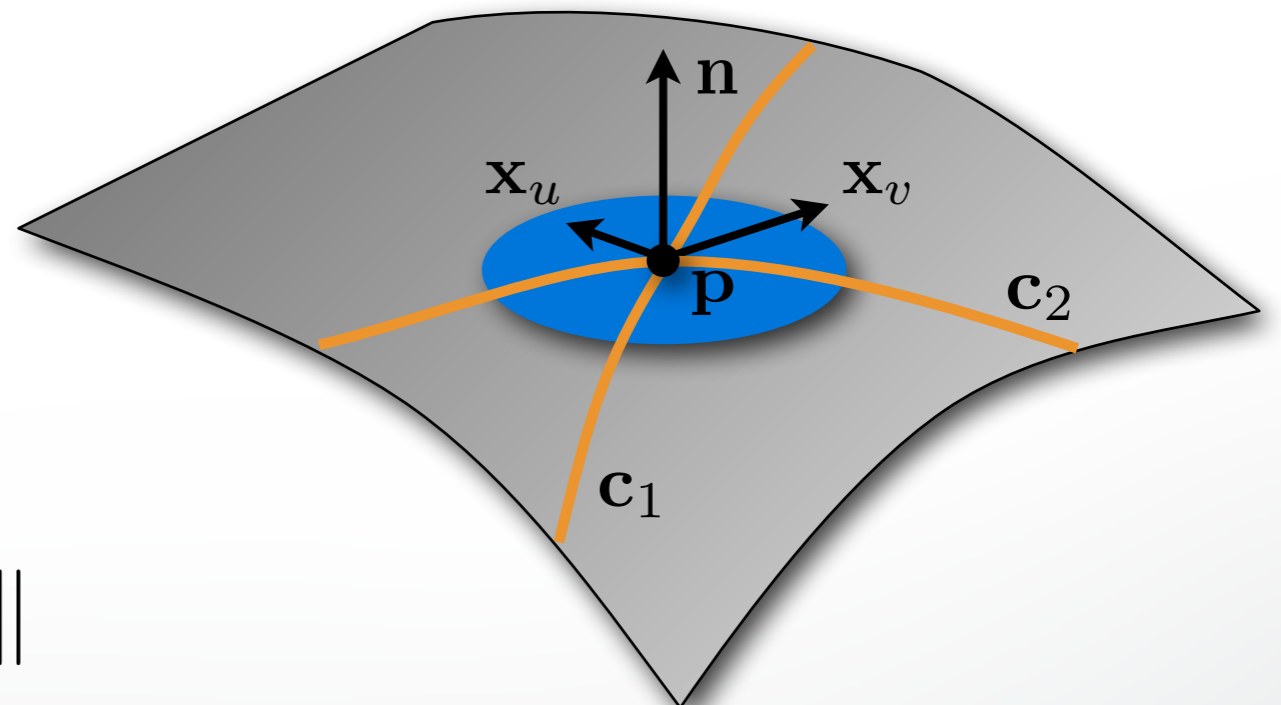
**Two curves**  $\mathbf{c}_1$  and  $\mathbf{c}_2$  intersecting at  $\mathbf{p}$

- angle of intersection?
- two tangents  $\mathbf{t}_1$  and  $\mathbf{t}_2$

$$\mathbf{t}_i = \alpha_i \mathbf{x}_u + \beta_i \mathbf{x}_v$$

- compute inner product

$$\mathbf{t}_1^T \mathbf{t}_2 = \cos \theta \|\mathbf{t}_1\| \|\mathbf{t}_2\|$$



# Angles on Surface

**Curve**  $[u(t), v(t)]$  in uv-plane defines curve on the surface  $\mathbf{x}(u, v)$

$$\mathbf{c}(t) = \mathbf{x}(u(t), v(t))$$

**Two curves**  $\mathbf{c}_1$  and  $\mathbf{c}_2$  intersecting at  $\mathbf{p}$

$$\begin{aligned} \mathbf{t}_1^T \mathbf{t}_2 &= (\alpha_1 \mathbf{x}_u + \beta_1 \mathbf{x}_v)^T (\alpha_2 \mathbf{x}_u + \beta_2 \mathbf{x}_v) \\ &= \alpha_1 \alpha_2 \mathbf{x}_u^T \mathbf{x}_u + (\alpha_1 \beta_2 + \alpha_2 \beta_1) \mathbf{x}_u^T \mathbf{x}_v + \beta_1 \beta_2 \mathbf{x}_v^T \mathbf{x}_v \\ &= (\alpha_1, \beta_1) \begin{pmatrix} \mathbf{x}_u^T \mathbf{x}_u & \mathbf{x}_u^T \mathbf{x}_v \\ \mathbf{x}_u^T \mathbf{x}_v & \mathbf{x}_v^T \mathbf{x}_v \end{pmatrix} \begin{pmatrix} \alpha_2 \\ \beta_2 \end{pmatrix} \end{aligned}$$

# First Fundamental Form

## First fundamental form

$$\mathbf{I} = \begin{pmatrix} E & F \\ F & G \end{pmatrix} := \begin{pmatrix} \mathbf{x}_u^T \mathbf{x}_u & \mathbf{x}_u^T \mathbf{x}_v \\ \mathbf{x}_u^T \mathbf{x}_v & \mathbf{x}_v^T \mathbf{x}_v \end{pmatrix}$$

## Defines inner product on tangent space

$$\left\langle \begin{pmatrix} \alpha_1 \\ \beta_1 \end{pmatrix}, \begin{pmatrix} \alpha_2 \\ \beta_2 \end{pmatrix} \right\rangle := \begin{pmatrix} \alpha_1 \\ \beta_1 \end{pmatrix}^T \mathbf{I} \begin{pmatrix} \alpha_2 \\ \beta_2 \end{pmatrix}$$



# First Fundamental Form

First fundamental form **I** allows to measure  
(w.r.t. surface metric)

Angles  $\mathbf{t}_1^\top \mathbf{t}_2 = \langle (\alpha_1, \beta_1), (\alpha_2, \beta_2) \rangle$

Length  $ds^2 = \langle (du, dv), (du, dv) \rangle$   
 $= Edu^2 + 2Fdudv + Gdv^2$

squared  
infinitesimal  
length

Area  $dA = \|\mathbf{x}_u \times \mathbf{x}_v\| du dv$   
 $= \sqrt{\mathbf{x}_u^T \mathbf{x}_u \cdot \mathbf{x}_v^T \mathbf{x}_v - (\mathbf{x}_u^T \mathbf{x}_v)^2} du dv$   
 $= \sqrt{EG - F^2} du dv$

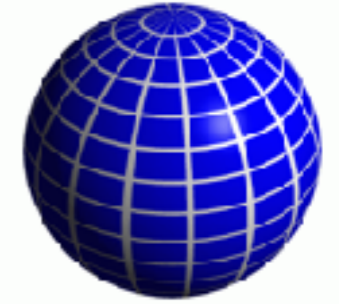
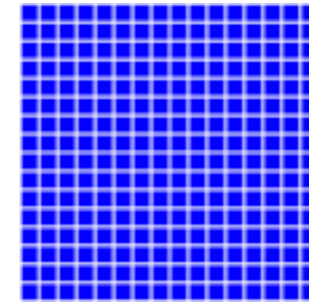
infinitesimal  
Area

cross product  $\rightarrow$  determinant with unit vectors  $\rightarrow$  area

# Sphere Example

## Spherical parameterization

$$\mathbf{x}(u, v) = \begin{pmatrix} \cos u \sin v \\ \sin u \sin v \\ \cos v \end{pmatrix}, \quad (u, v) \in [0, 2\pi) \times [0, \pi)$$



## Tangent vectors

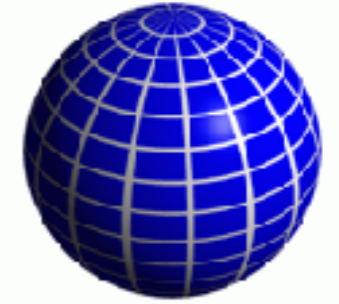
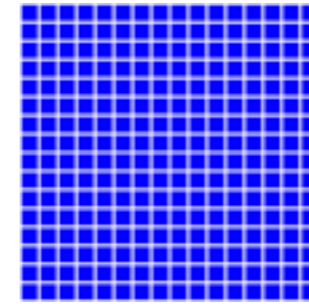
$$\mathbf{x}_u(u, v) = \begin{pmatrix} -\sin u \sin v \\ \cos u \sin v \\ 0 \end{pmatrix} \quad \mathbf{x}_v(u, v) = \begin{pmatrix} \cos u \cos v \\ \sin u \cos v \\ -\sin v \end{pmatrix}$$

## First fundamental Form

$$\mathbf{I} = \begin{pmatrix} \sin^2 v & 0 \\ 0 & 1 \end{pmatrix}$$

# Sphere Example

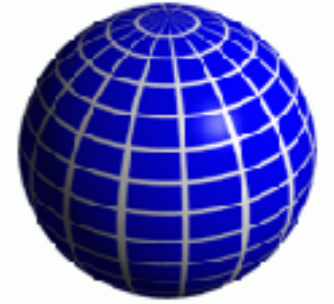
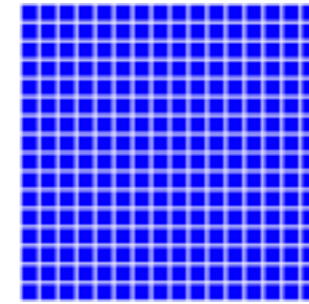
Length of equator  $\mathbf{x}(t, \pi/2)$



$$\begin{aligned}\int_0^{2\pi} 1 \, ds &= \int_0^{2\pi} \sqrt{E (u_t)^2 + 2F u_t v_t + G (v_t)^2} \, dt \\ &= \int_0^{2\pi} \sin v \, dt \\ &= 2\pi \sin v = 2\pi\end{aligned}$$

# Sphere Example

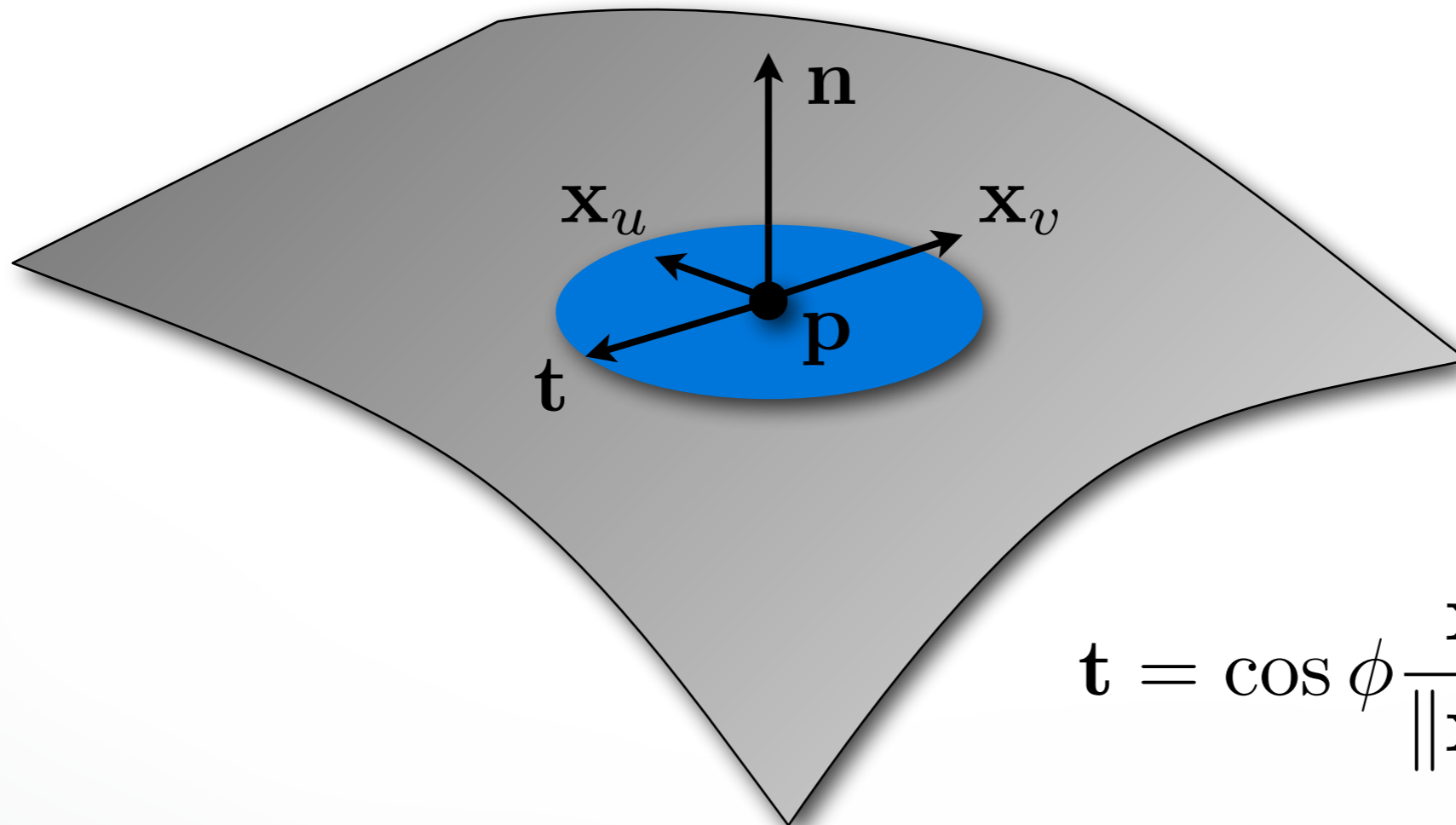
Area of a sphere



$$\begin{aligned}\int_0^\pi \int_0^{2\pi} 1 \, dA &= \int_0^\pi \int_0^{2\pi} \sqrt{EG - F^2} \, du \, dv \\ &= \int_0^\pi \int_0^{2\pi} \sin v \, du \, dv \\ &= 4\pi\end{aligned}$$

# Normal Curvature

Tangent vector  $\mathbf{t}$  ...



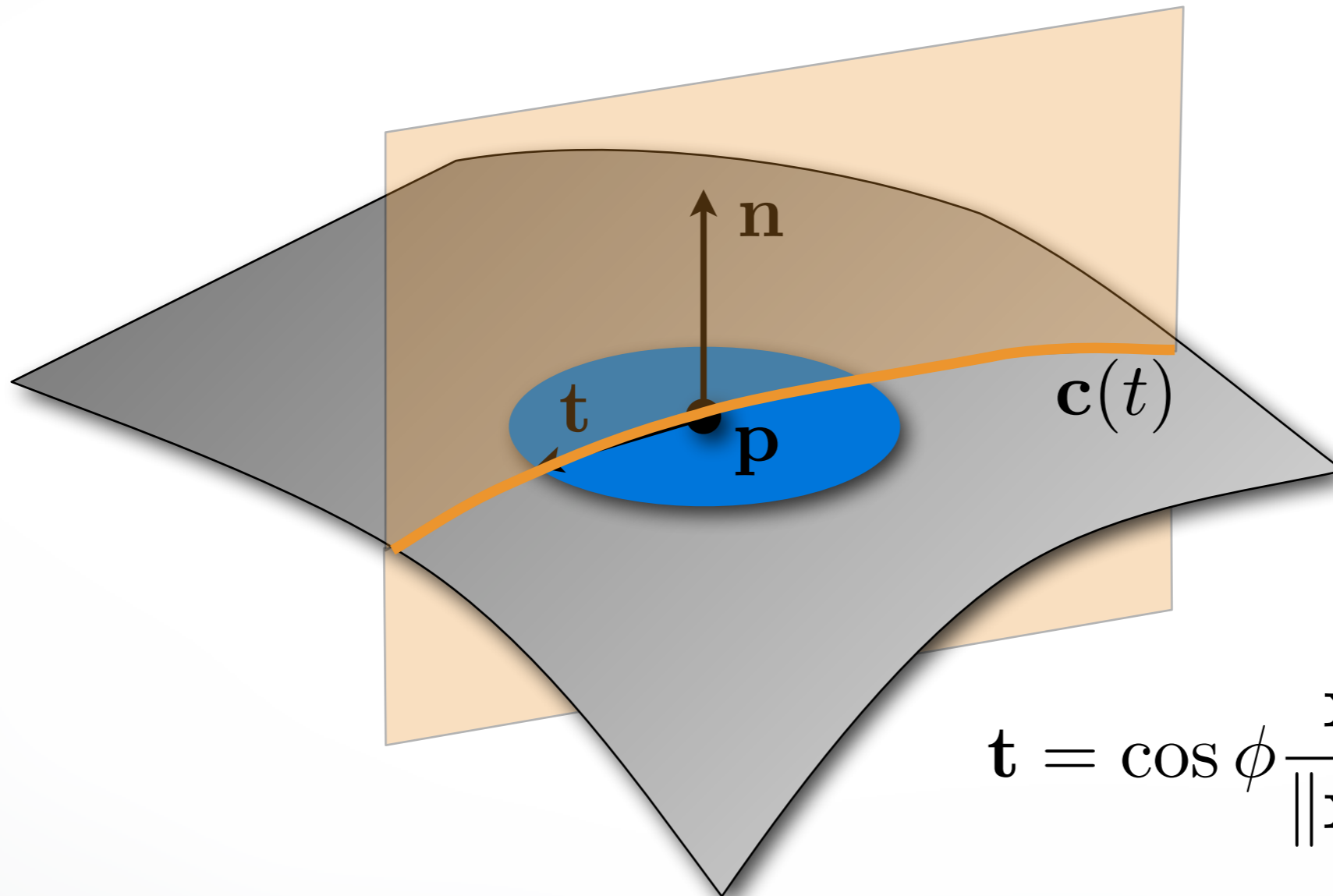
$$\mathbf{t} = \cos \phi \frac{\mathbf{x}_u}{\|\mathbf{x}_u\|} + \sin \phi \frac{\mathbf{x}_v}{\|\mathbf{x}_v\|}$$

unit vector

# Normal Curvature

... defines intersection plane, yielding curve  $\mathbf{c}(t)$

normal curve



$$\mathbf{t} = \cos \phi \frac{\mathbf{x}_u}{\|\mathbf{x}_u\|} + \sin \phi \frac{\mathbf{x}_v}{\|\mathbf{x}_v\|}$$

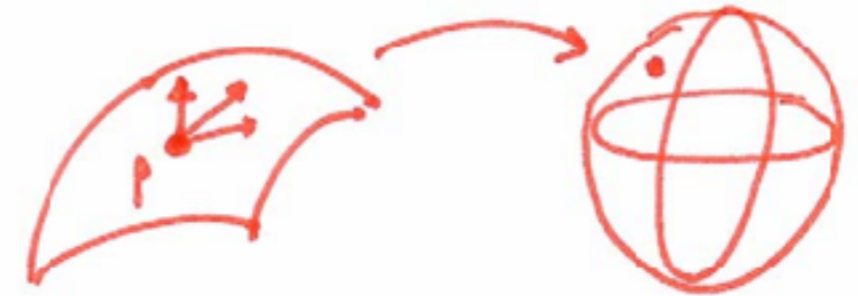
# Geometry of the Normal

## Gauss map

- normal at point

$$N(p) = \frac{S_{,u} \times S_{,v}}{|S_{,u} \times S_{,v}|}(p) \quad N : S \rightarrow S^2$$

- consider curve in surface again
  - study its curvature at p
  - normal “tilts” along curve



# Normal Curvature

Normal curvature  $\kappa_n(t)$  is defined as curvature of the normal curve  $\mathbf{c}(t)$  at point  $\mathbf{p}(t) = \mathbf{x}(u, v)$

With second fundamental form

$$\mathbf{II} = \begin{pmatrix} e & f \\ f & g \end{pmatrix} := \begin{pmatrix} \mathbf{x}_{uu}^T \mathbf{n} & \mathbf{x}_{uv}^T \mathbf{n} \\ \mathbf{x}_{uv}^T \mathbf{n} & \mathbf{x}_{vv}^T \mathbf{n} \end{pmatrix}$$

normal curvature can be computed as

$$\kappa_n(\bar{\mathbf{t}}) = \frac{\bar{\mathbf{t}}^T \mathbf{II} \bar{\mathbf{t}}}{\bar{\mathbf{t}}^T \mathbf{I} \bar{\mathbf{t}}} = \frac{ea^2 + 2fab + gb^2}{Ea^2 + 2Fab + Gb^2} \quad \begin{array}{l} \mathbf{t} = a\mathbf{x}_u + b\mathbf{x}_v \\ \bar{\mathbf{t}} = (a, b) \end{array}$$



# Surface Curvature(s)

## Principal curvatures

- Maximum curvature  $\kappa_1 = \max_{\phi} \kappa_n(\phi)$
- Minimum curvature  $\kappa_2 = \min_{\phi} \kappa_n(\phi)$
- Euler theorem  $\kappa_n(\phi) = \kappa_1 \cos^2 \phi + \kappa_2 \sin^2 \phi$
- Corresponding principal directions  $\mathbf{e}_1$ ,  $\mathbf{e}_2$  are orthogonal



# Surface Curvature(s)

## Principal curvatures

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## Special curvatures

- Mean curvature  $H = \frac{\kappa_1 + \kappa_2}{2}$  **extrinsic**
- Gaussian curvature  $K = \kappa_1 \cdot \kappa_2$  **intrinsic (only first FF)**

# Invariants

## Gaussian and mean curvature

- determinant and trace only

$$\det dN_p = \kappa_1 \kappa_2 = K$$
$$\operatorname{tr} dN_p = \kappa_1 + \kappa_2 = H$$

- eigenvalues and orthovectors

$$dN_p(e_1) = \kappa_1 e_1 \quad dN_p(e_2) = \kappa_2 e_2$$

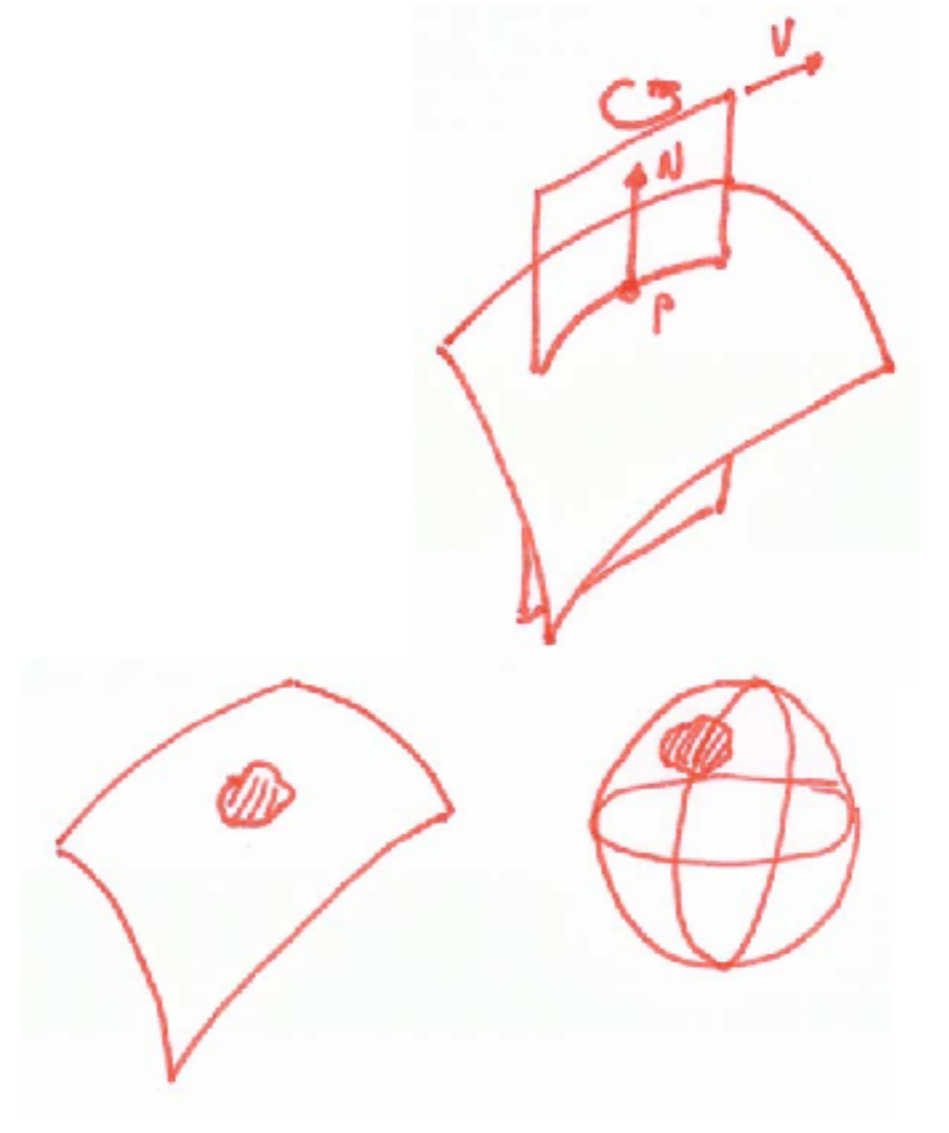
$$II_p|_{\mathcal{S} \subset T_p \mathcal{S}} \begin{cases} \max \rightarrow \kappa_1 \\ \min \rightarrow \kappa_2 \end{cases}$$

# Mean and Gaussian Curvature

## Integral representations

$$H_p/2 = \frac{1}{2\pi} \int_0^{2\pi} \kappa_n(\theta) d\theta$$

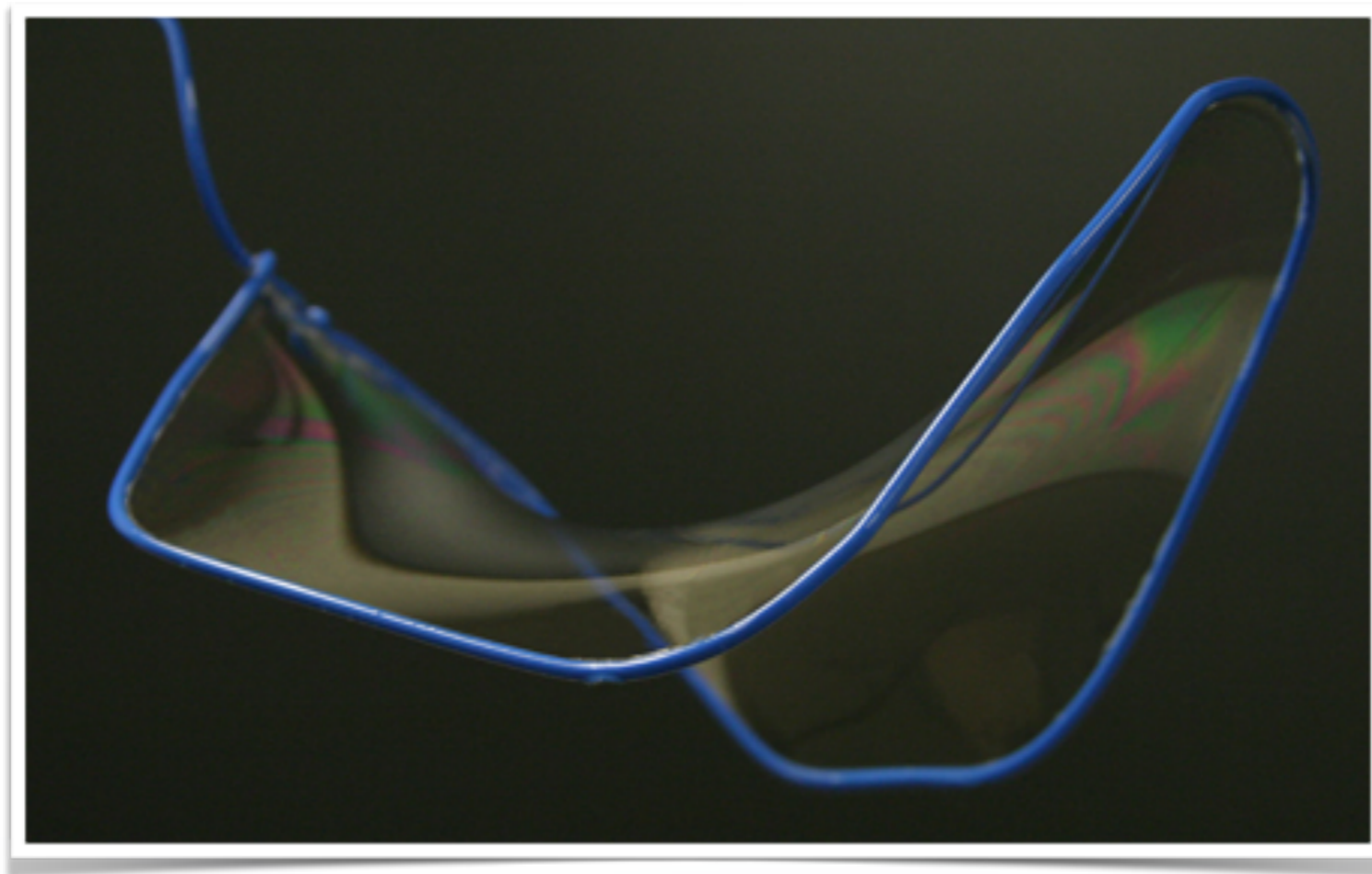
$$K_p = \lim_{A \rightarrow 0} \frac{A_G}{A}$$



# Curvature of Surfaces

Mean curvature  $H = \frac{\kappa_1 + \kappa_2}{2}$

- $H = 0$  everywhere  $\rightarrow$  minimal surface



soap film

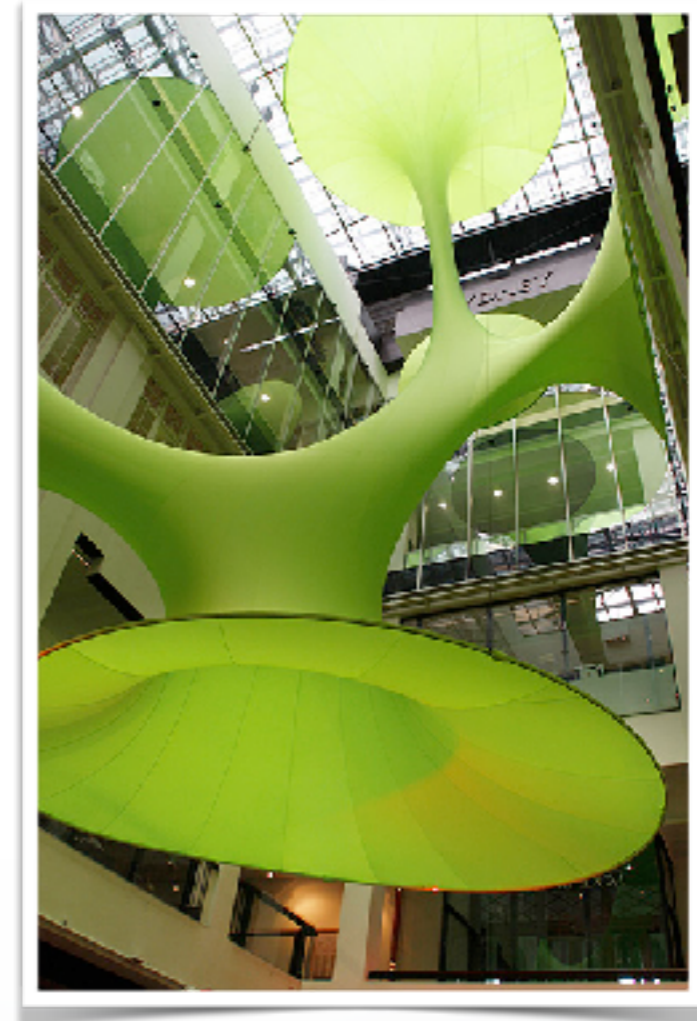
# Curvature of Surfaces

Mean curvature  $H = \frac{\kappa_1 + \kappa_2}{2}$

- $H = 0$  everywhere  $\rightarrow$  minimal surface



Green Void, Sydney  
Architects: Lava



# Curvature of Surfaces

**Gaussian curvature**  $K = \kappa_1 \cdot \kappa_2$

- $K = 0$  everywhere  $\rightarrow$  developable surface

**surface that can be flattened to a plane without distortion (stretching or compression)**



Disney, Concert Hall, L.A.  
Architects: Gehry Partners



Timber Fabric  
IBOIS, EPFL

# Shape Operator

## Derivative of Gauss map

- second fundamental form

$$II_p(v) = \langle dN_p(v), v \rangle$$

- local coordinates

$$II_p = - \begin{pmatrix} \langle N, S_{,uu} \rangle & \langle N, S_{,uv} \rangle \\ \langle N, S_{,vu} \rangle & \langle N, S_{,vv} \rangle \end{pmatrix} \begin{pmatrix} E & F \\ F & G \end{pmatrix}^{-1}$$

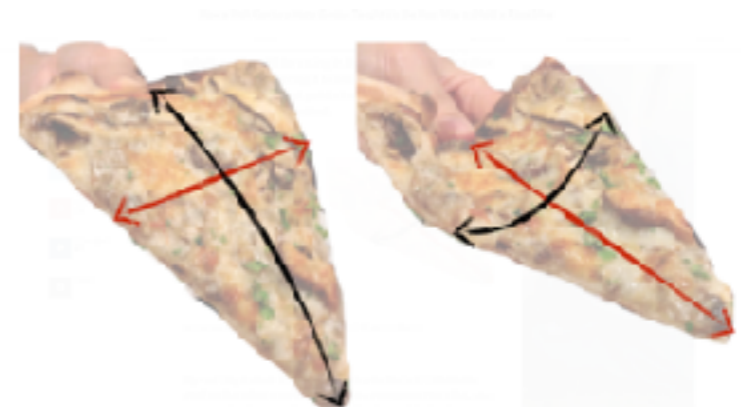


# Intrinsic Geometry

## Properties of the surface that only depend on the first fundamental form

- length
- angles
- Gaussian curvature (Theorema Egregium)  
**remarkable theorem (Gauss)**

$$K = \lim_{r \rightarrow 0} \frac{6\pi r - 3C(r)}{\pi r^3}$$



**Gaussian curvature of a surface is invariant under local isometry**

# Classification

**Point  $\mathbf{x}$  on the surface is called**

- elliptic, if  $K > 0$
- hyperbolic, if  $K < 0$
- parabolic, if  $K = 0$
- umbilic, if  $\kappa_1 = \kappa_2$  **or isotropic**

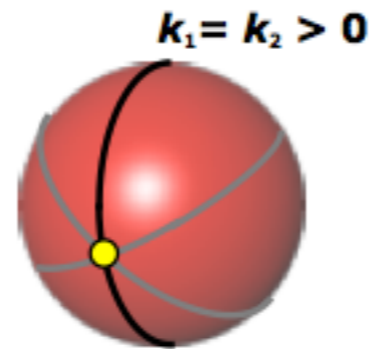
**Gaussian curvature  $K$**

# Classification

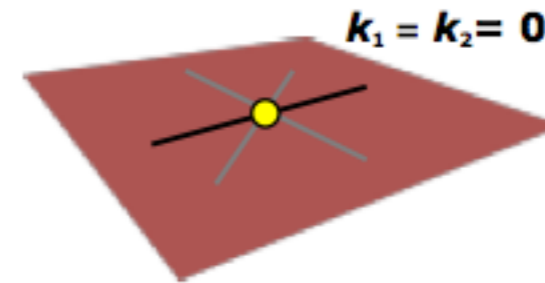
Point  $x$  on the surface is called

## Isotropic

Equal in all directions



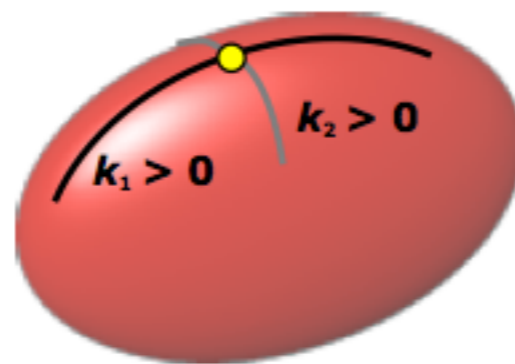
spherical



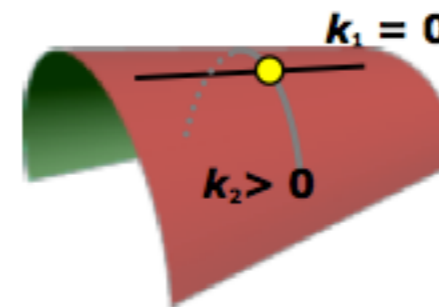
planar

## Anisotropic

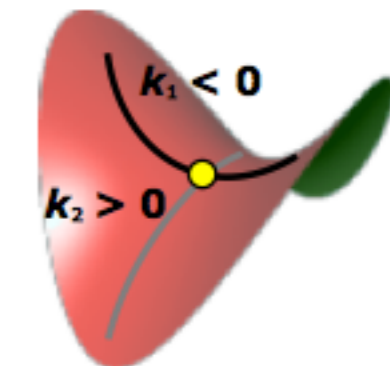
Distinct principal directions



elliptic  
 $K > 0$



parabolic  
 $K = 0$   
developable



hyperbolic  
 $K < 0$

# Gauss-Bonnet Theorem

For any closed manifold surface with Euler characteristic  $\chi = 2 - 2g$

$$\int K = 2\pi\chi$$

$$\int K(\text{👉}) = \int K(\text{🐮}) = \int K(\text{🌐}) = 4\pi$$

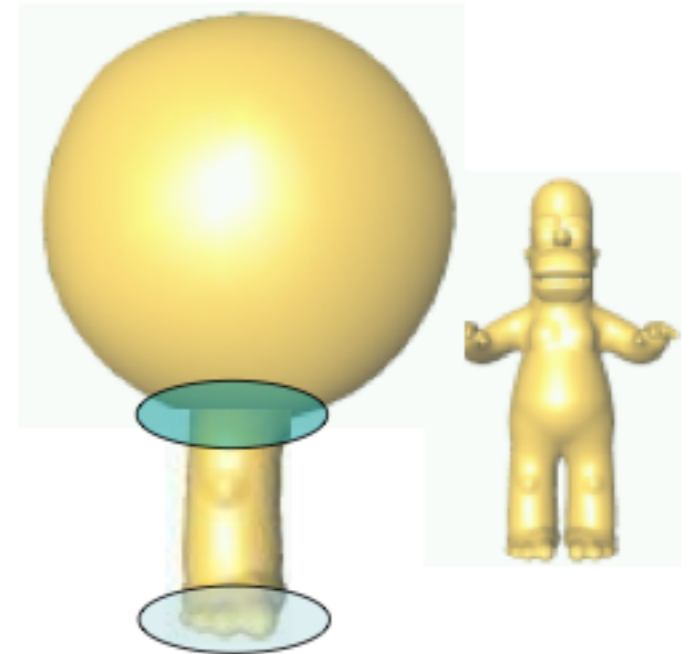
# Gauss-Bonnet Theorem

## Sphere

$$\kappa_1 = \kappa_2 = 1/r$$

$$K = \kappa_1 \kappa_2 = 1/r^2$$

$$\int K = 4\pi r^2 \cdot \frac{1}{r^2} = 4\pi$$



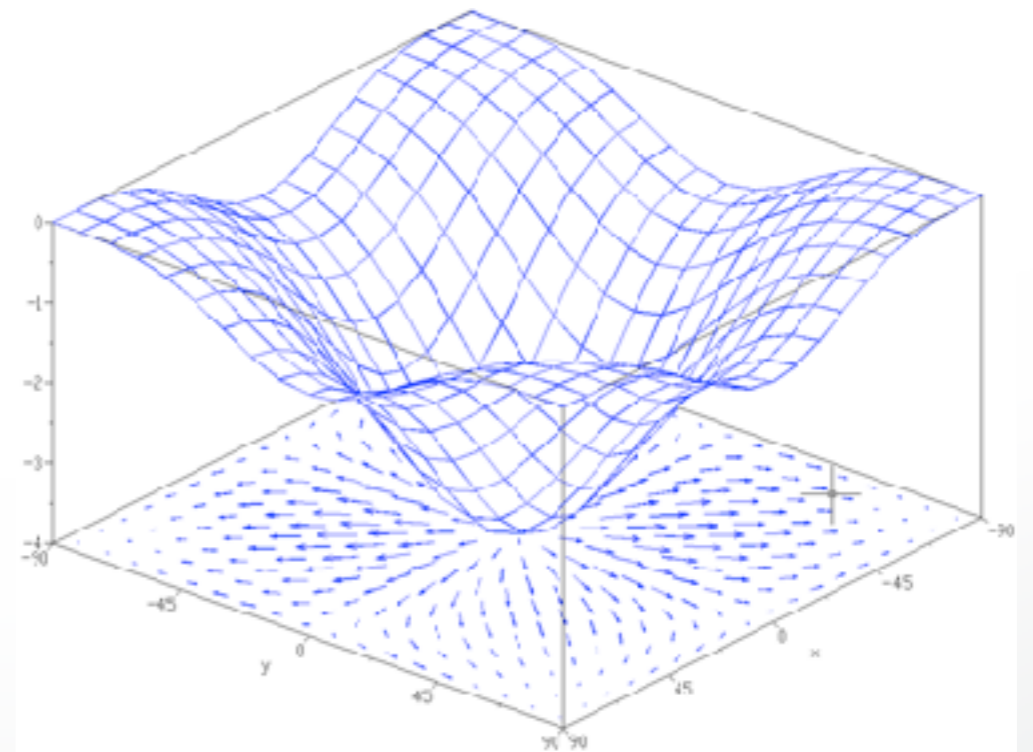
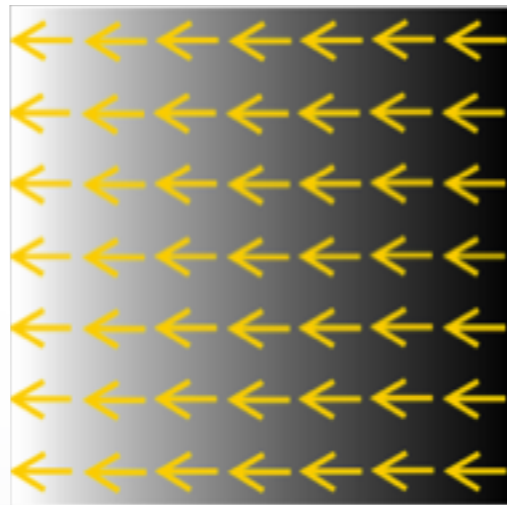
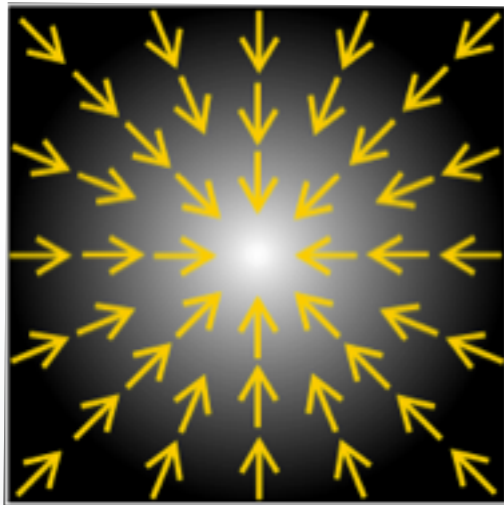
when sphere is deformed, new  
**positive and negative curvature cancel out**

# Differential Operators

## Gradient

$$\nabla f := \left( \frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n} \right)$$

- points in the direction of the steepest ascend



# Differential Operators

## Divergence

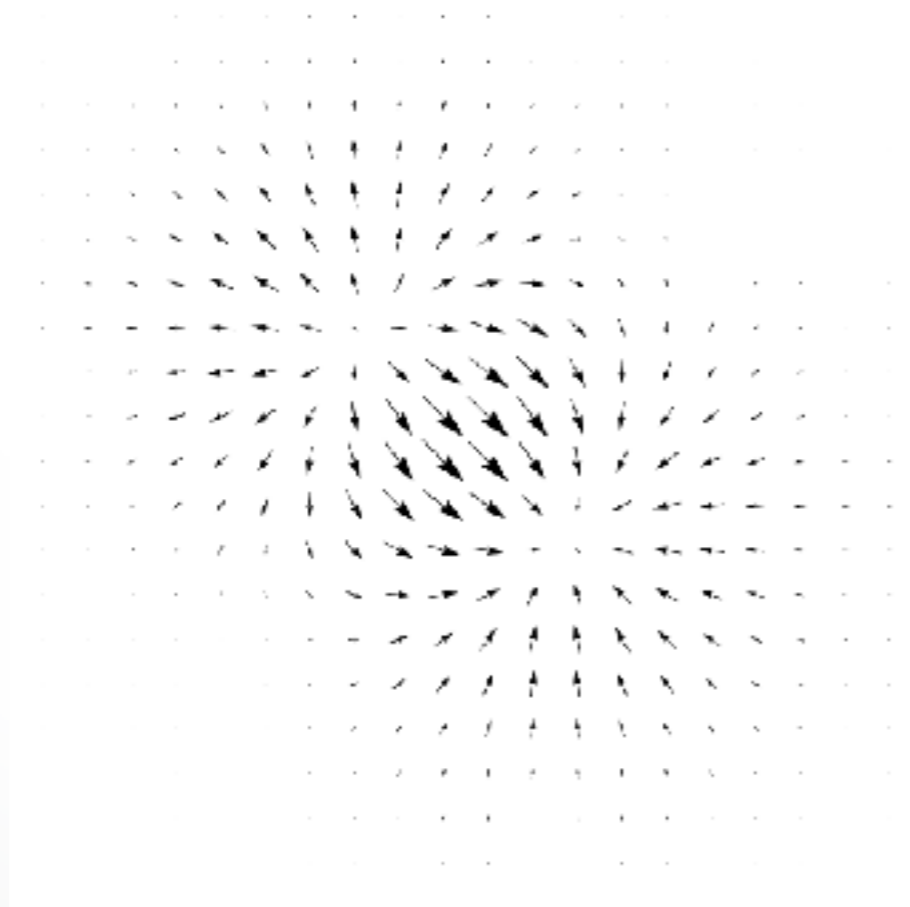
$$\operatorname{div} F = \nabla \cdot F := \frac{\partial F_1}{\partial x_1} + \dots + \frac{\partial F_n}{\partial x_n}$$

- volume density of outward flux of vector field
- magnitude of source or sink at given point
- Example: incompressible fluid
  - velocity field is divergence-free

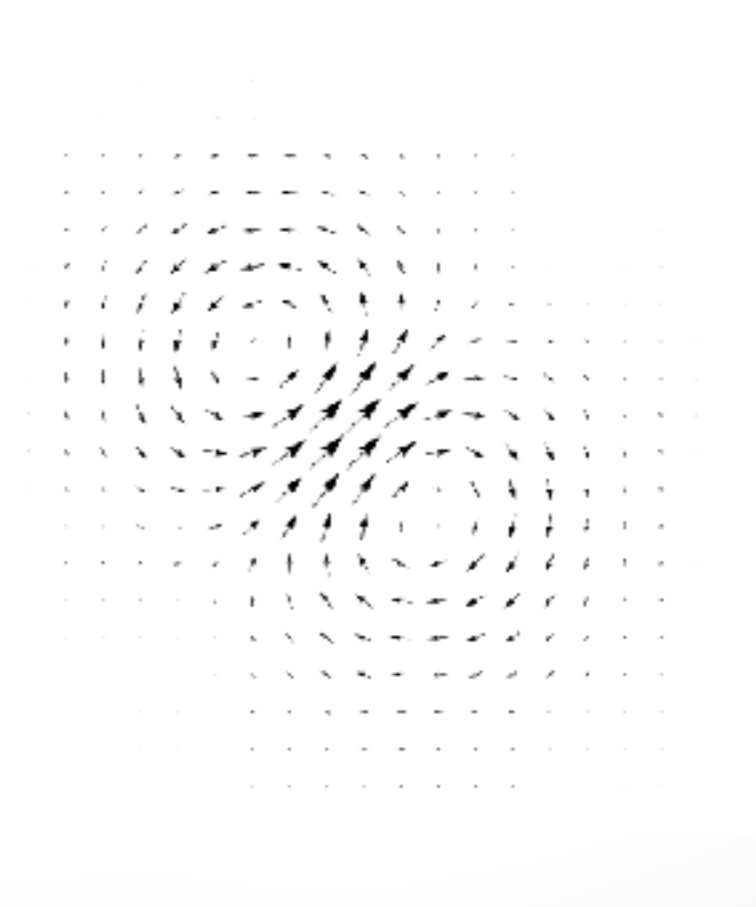
# Differential Operators

## Divergence

$$\operatorname{div} F = \nabla \cdot F := \frac{\partial F_1}{\partial x_1} + \dots + \frac{\partial F_n}{\partial x_n}$$



high divergence



low divergence



# Laplace Operator

Laplace operator

gradient operator

2nd partial derivatives

function in Euclidean space

divergence operator

Cartesian coordinates

$$\Delta f = \operatorname{div} \nabla f = \sum_i \frac{\partial^2 f}{\partial x_i^2}$$

# Laplace-Beltrami Operator

## Extension of Laplace of functions on manifolds

Laplace-  
Beltrami

gradient  
operator

...of the surface

$$\Delta_{\mathcal{S}} f = \operatorname{div}_{\mathcal{S}} \nabla_{\mathcal{S}} f$$

function on  
manifold  $\mathcal{S}$

divergence  
operator

**Laplace on the surface**

# Laplace-Beltrami Operator

Laplace-Beltrami

gradient operator

mean curvature

function on manifold  $\mathcal{S}$

divergence operator

surface normal

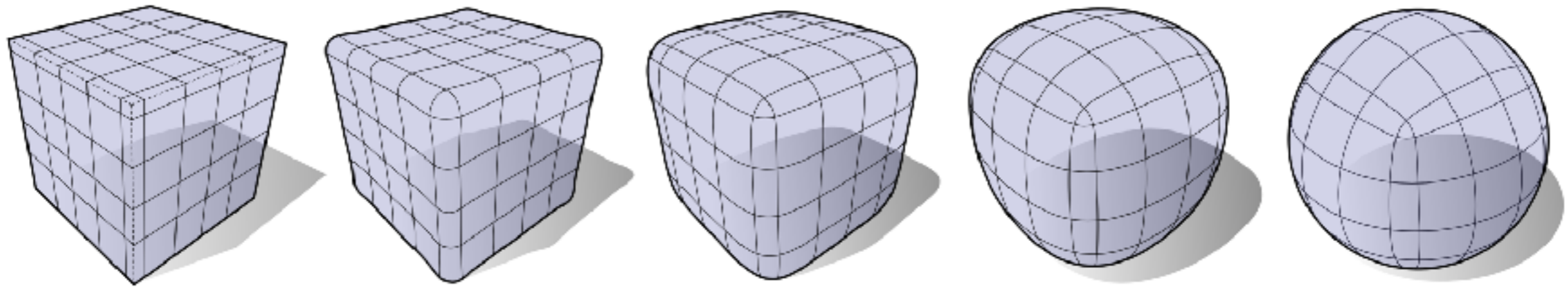
$$\Delta_{\mathcal{S}} \mathbf{x} = \operatorname{div}_{\mathcal{S}} \nabla_{\mathcal{S}} \mathbf{x} = -2H \mathbf{n}$$

The diagram illustrates the Laplace-Beltrami operator equation  $\Delta_{\mathcal{S}} \mathbf{x} = \operatorname{div}_{\mathcal{S}} \nabla_{\mathcal{S}} \mathbf{x} = -2H \mathbf{n}$ . It features six labels with arrows pointing to specific parts of the equation: 'Laplace-Beltrami' points to  $\Delta_{\mathcal{S}}$ ; 'function on manifold  $\mathcal{S}$ ' points to  $\mathbf{x}$ ; 'divergence operator' points to  $\operatorname{div}_{\mathcal{S}}$ ; 'gradient operator' points to  $\nabla_{\mathcal{S}}$ ; 'mean curvature' points to  $H$ ; and 'surface normal' points to  $\mathbf{n}$ .

# Literature

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- <http://graphics.stanford.edu/courses/cs468-13-spring/schedule.html>

# Next Time



**Discrete** Differential Geometry

<http://cs621.hao-li.com>

# Thanks!

